# Kernel regression uniform rate estimation for censored data under $\alpha$-mixing condition 

Zohra Guessoum<br>Lab. M.S.T.D., Faculté de Math., Univ. Sci. Tech. Houari Boumédiène, BP 32, El Alia, 16111, Algeria<br>e-mail: z0guessoum@hotmail.com<br>Elias Ould Saïd*<br>Univ. Lille Nord de France, F-59000, France ULCO, LMPA, F-62000, Calais, France<br>e-mail: ouldsaid@lmpa.univ-littoral.fr


#### Abstract

In this paper, we study the behavior of a kernel estimator of the regression function in the right censored model with $\alpha$-mixing data. The uniform strong consistency over a real compact set of the estimate is established along with a rate of convergence. Some simulations are carried out to illustrate the behavior of the estimate with different examples for finite sample sizes


AMS 2000 subject classifications: Primary 62G05, 62G20.
Keywords and phrases: Censored data, Kernel estimator, nonparametric regression, rate of convergence, strong consistency, strong mixing.

Received February 2008.

## Contents

1 Introduction . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 117
2 Definition of estimators . . . . . . . . . . . . . . . . . . . . . . . . . . 119
3 Assumptions and main result . . . . . . . . . . . . . . . . . . . . . . . 121
4 Simulations study . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 122
5 Proofs . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 125
Acknowledgments . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 131
References . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 131

## 1. Introduction

In many survival practical applications, censored dependent data appear. For example, in the clinical trials domain, it is frequently happens that the patients

[^0]from the same hospital have correlated survival times due to unmeasured variables like the quality of the hospital equipment. An example of such data can be found in Lipsitz and Ibrahim (2000). In economic duration data, event times are often correlated and the observation of the event may be prevented by the occurrence of an earlier competing event called censoring. Another example is the observations on duration of unemployment, which may be right censored and are typically correlated. For real data, the reader can refer to Wei and Lin (1989), Cai and Prentice (1995). However few papers deal with the regression function under censoring in the dependent case, we can cite the recent paper of El-Ghouch and Van Keilegom (2008) who estimate the regression function by applying polynomial local linear regression techniques using Beran's estimator.

Having in mind such kind of applications, consider a real random variable (rv) $Y$ and a sequence of strictly stationary rv's $\left(Y_{i}\right)_{i \geq 1}$ with common unknown absolutely continuous disribution function (df) $\bar{F}$ and let $\left(C_{i}\right)_{i>1}$, be a sequence of censoring rv's with common unknown df $G$. In contrast to statistics for complete data studies, censored model involves pairs $\left(T_{i}, \delta_{i}\right)_{i=1, \ldots, n}$ where only $T_{i}=Y_{i} \wedge C_{i}$ and $\delta_{i}=\mathbb{I}_{\left\{Y_{i} \leq C_{i}\right\}}$ are observed.

Let $X$ be an $\mathbb{R}^{d}$-valued random vector. Let $\left(X_{i}\right)_{i \geq 1}$ be a sequence of copies of the random vector $X$ and denote by $X_{i, 1}, \ldots, X_{i, d}$ the coordinates of $X_{i}$. The study we perform below is then on the set of observations $\left(T_{i}, \delta_{i}, X_{i}\right)_{i \geq 1}$. In regression analysis one expectes to identify, if any, the relationship between the $Y_{i}$ 's and $X_{i}$ 's. This means looking for a function $m^{*}(X)$ describing this relationship that realizes the minimum of the mean squared error criterion. It is well known that this minimum is achieved by the regression function $m(x)$ defined on $\mathbb{R}^{d}$ by

$$
m(x)=\mathbb{E}(Y \mid X=x)
$$

There is a wide range of literature on nonparametric estimation of the regression function and many nonlinear smoothers including kernel, spline, local polynomial, orthogonal methods and so on. For an overview on methods and results for both theoretical and application points of view considering independent or dependent case, we refer the reader to Collomb (1981), Silverman (1986), Härdle (1990), Wahba (1990), Wand and Jones (1995), Masry and Fan (1997), Cai (2003) and Cai and Ould Saïd (2003).

In the uncensored case, the behavior of nonparametric estimators built upon mixing sequences is extensively studied. The consistency has been investigated by many authors. We only cite the recent work of Gonzalez-Manteiga et al. (2002) where they developed a nonparametric test, based on kernel smoothers, to decide whether some covariates could be suppressed in a multidimensional nonparametric regression study. Under the $\alpha$-mixing condition, the uniform strong convergence of the Nadaraya-Watson estimator is treated in Doukhan (1994), Bosq (1998), Liebscher (2001) and the references therein.

Our goal is to establish the strong uniform convergence with rate for the kernel regression estimate under $\alpha$-mixing condition in random censorship models where the independence condition is relaxed. For this kind of model, Cai (2001) established the asymptotic properties of the Kaplan-Meier estimator. Liebscher
(2002) derive a rate uniform for the strong convergence of kernel density and hazard rate estimators. His result represents an improvement of that given in Cai (1998b).

To this end, we were interested in extending the result of Guessoum and Ould Saïd (2008) from the iid to the dependent case. The paper is organized as follows: In Section 2 we give some definitions and notations under the censorship model of the regression function and strong-mixing process. Section 3 is devoted to the assumptions and main result. In Section 4, some simulations are drawn to lend further support to our theoretical results. Proof with auxiliary results are relegated to Section 5.

## 2. Definition of estimators

Suppose that $\left\{Y_{i}, i \geq 1\right\}$ and $\left\{C_{i}, i \geq 1\right\}$ are two independent sequences of stationary random variables. We want to estimate $m(x)=\mathbb{E}(Y \mid X=x)$ which can be written as $m(x)=\frac{r_{1}(x)}{\ell(x)}$ where

$$
\begin{equation*}
r_{1}(x)=\int_{\mathbb{R}} y f_{X, Y}(x, y) d y \tag{1}
\end{equation*}
$$

with $f_{.,,}(x, y)$ being the joint density of $(X, Y)$ and $\ell(\cdot)$ the density function of the covariates.

Now, it is well known that the kernel estimator of the regression function $m(\cdot)$ under censorship model (see, eg Carbonez et al. (1995)) is given by

$$
\begin{equation*}
\tilde{m}_{n}(x)=\sum_{i=1}^{n} W_{i n}(x) \frac{\delta_{i} T_{i}}{\bar{G}\left(T_{i}\right)} \tag{2}
\end{equation*}
$$

where $\bar{G}$ is the survival function of the rv $C$ and

$$
W_{i n}(x)=\frac{K_{d}\left(\frac{x-X_{i}}{h_{n}}\right)}{\sum_{j=1}^{n} K_{d}\left(\frac{x-X_{j}}{h_{n}}\right)}
$$

are the Watson-Nadaraya weights, $K_{d}$ is a probability density function (pdf) defined on $\mathbb{R}^{d}$ and $h_{n}$ a sequence of positive numbers converging to 0 as $n$ goes to infinity. Then (2) can be written

$$
\tilde{m}_{n}(x)=: \frac{\tilde{r}_{1, n}(x)}{\ell_{n}(x)}
$$

where
$\tilde{r}_{1, n}(x)=\frac{1}{n h_{n}^{d}} \sum_{i=1}^{n} \frac{\delta_{i} T_{i}}{\bar{G}\left(T_{i}\right)} K_{d}\left(\frac{x-X_{i}}{h_{n}}\right) \quad$ and $\quad \ell_{n}(x)=\frac{1}{n h_{n}^{d}} \sum_{i=1}^{n} K_{d}\left(\frac{x-X_{i}}{h_{n}}\right)$.

In practice, $G$ is usually unknown, we replace it by the corresponding KaplanMeier (1958) estimator (KME) $G_{n}$ defined by

$$
\bar{G}_{n}(t)= \begin{cases}\prod_{i=1}^{n}\left(1-\frac{1-\delta_{i}}{n-i+1}\right)^{\mathbb{1}_{\left\{Y_{i} \leq t\right\}}}, & \text { if } t<Y_{(n)} \\ 0, & \text { if } t \geq Y_{(n)}\end{cases}
$$

The properties of the KME for dependent variables can be found in Cai (1998a, 2001). Then a feasible estimator of $m(x)$ is given by:

$$
m_{n}(x)=\frac{r_{1, n}(x)}{\ell_{n}(x)}
$$

where

$$
\begin{equation*}
r_{1, n}(x)=\frac{1}{n h_{n}^{d}} \sum_{i=1}^{n} \frac{\delta_{i} T_{i}}{\bar{G}_{n}\left(T_{i}\right)} K_{d}\left(\frac{x-X_{i}}{h_{n}}\right) \tag{4}
\end{equation*}
$$

is an estimator of $r_{1}(x)$ and $\ell_{n}(x)$ (defined in (3)) an estimator of $\ell(x)$.
In what follows, we define the endpoints of $F$ and $G$ by $\tau_{F}=\sup \{y, \bar{F}(y)>0\}$, $\tau_{G}=\sup \{y, \bar{G}(y)>0\}$ and we assume that $\tau_{F}<\infty$ and $\bar{G}\left(\tau_{F}\right)>0$ (this implies $\left.\tau_{F}<\tau_{G}\right)$.

For technical reasons (see Lemma 1), we assume that $\left\{C_{i}, i \geq 1\right\}$ and $\left\{\left(X_{i}, Y_{i}\right)\right.$, $i \geq 1\}$ are independent; furthermore this condition is plausible whenever the censoring is independent of the characteristics of the patient under study. We point out that since $Y$ can be a lifetime we can suppose it bounded. We put $\|t\|=\sum_{j=1}^{d}\left|t_{j}\right|$ for $t \in \mathbb{R}^{d}$.

In order to define the $\alpha$-mixing property, we introduce the following notations. Denote by $\mathcal{F}_{i}^{k}(Z)$ the $\sigma$-algebra generated by $\left\{Z_{j}, i \leq j \leq k\right\}$.
Definition Let $\left\{Z_{i}, i=1,2, \ldots\right\}$ denote a sequence of rv's. Given a positive integer $n$, set
$\alpha(n)=\sup \left\{|\mathbb{P}(A \cap B)-\mathbb{P}(A) \mathbb{P}(B)|: A \in \mathcal{F}_{1}^{k}(Z)\right.$ and $\left.B \in \mathcal{F}_{k+n}^{\infty}(Z), k \in \mathbb{N}^{*}\right\}$.
The sequence is said to be $\alpha$-mixing (strong mixing) if the mixing coefficient $\alpha(n) \rightarrow 0$ as $n \rightarrow \infty$.

Many processes do fulfill the strong mixing property. We quote, here, the usual ARMA processes which are geometrically strongly mixing, i.e., there exist $\rho \in(0,1)$ and $a>0$ such that, for any $n \geq 1, \alpha(n) \leq a \rho^{n}$ (see, e.g., Jones (1978)). The threshold models, the EXPAR models (see, Ozaki (1979)), the simple ARCH models (see Engle (1982)), their GARCH extension (see Bollerslev (1986)) and the bilinear Markovian models are geometrically strongly mixing under some general ergodicity conditions. We refer the reader to the recent Bradley's monograph.

We suppose that the sequences $\left\{Y_{i}, i \geq 1\right\}$ and $\left\{C_{i}, i \geq 1\right\}$ are $\alpha$-mixing with coefficients $\alpha_{1}(n)$ and $\alpha_{2}(n)$, respectively. Cai (2001, Lemma 2) showed that $\left\{T_{i}, i \geq 1\right\}$ is then strongly mixing, with coefficient

$$
\alpha(n)=4 \max \left(\alpha_{1}(n), \alpha_{2}(n)\right) .
$$

From now on, we suppose that $\left\{\left(T_{i}, \delta_{i}, X_{i}\right) \quad i=1, \ldots, n\right\}$ is strongly mixing with mixing's coefficient $\alpha(n)$ such that $\alpha(n)=O\left(n^{-\nu}\right)$ for some $\nu>3$.

Now we are in position to give our assumptions and main result.

## 3. Assumptions and main result

Let $\mathcal{C}$ be a compact set of $\mathbb{R}^{d}$ which is included in $\mathcal{C}_{0}=\left\{x \in \mathbb{R}^{d} / \ell(x)>0\right\}$. We will make use of the following assumptions gathered here for easy reference:

A1) The bandwidth $h_{n}$ satisfies:
i) $\lim _{n \rightarrow+\infty} \frac{n h_{n}^{d}}{\log n}=+\infty$,
ii) $\sqrt{\frac{\log \log n}{n}}=o\left(h_{n}\right)$,
iii) $\lim _{n \rightarrow+\infty} h_{n}^{d(\nu-2)} \log n=0$.

A2) The kernel $K_{d}$ is bounded and satisfies:
i) $\int_{\mathbb{R}^{d}}\|t\| K_{d}(t) d t<+\infty$,
ii) $\int_{\mathbb{R}^{d}}\left(t_{1}+t_{2}+\cdots+t_{d}\right) K_{d}^{2}(t) d t<+\infty$ and $\int_{\mathbb{R}^{d}} K_{d}^{2}(t) d t<+\infty$,
iii) $\forall(t, s) \in \mathcal{C}^{2} \quad\left|K_{d}(t)-K_{d}(s)\right| \leq\|t-s\|^{\gamma}$ for $\gamma>0$.

A3) The function $r_{1}(\cdot)$ defined in (1) is continuously differentiable and $\sup _{x \in \mathcal{C}}\left|\frac{\partial r_{1}}{\partial x_{i}}(x)\right|<+\infty$ for $i=1, \ldots, d$.

A4) The function $r_{2}(x):=\int_{\mathbb{R}^{d}} \frac{y^{2}}{G(y)} f_{X, Y}(x, y) d y$ is continuously differentiable and $\sup _{x \in \mathcal{C}}\left|\frac{\partial r_{2}}{\partial x_{i}}(x)\right|<+\infty$ for $i=1, \ldots, d$.
A5) $\exists D_{1}>0$ and $\exists D_{2}>0$ such that $\sup _{u, v \in \mathcal{C}}\left|\ell_{i j}(u, v)\right|<D_{1}$ and $\sup _{u \in \mathcal{C}}|\ell(u)|<$ $D_{2}$, where $\ell_{i j}$ is the joint distribution of $\left(X_{i}, X_{j}\right)$.

A6) $\exists \theta>0, \exists c_{1}>0$, such that

$$
c_{1} n^{\frac{\gamma(3-\nu)}{d \gamma(\nu+1)+2 \gamma+1]}+\theta d} \leq h_{n}^{d} .
$$

A7) The marginal density $\ell($.$) is continuously differentiable and \sup _{x \in \mathcal{C}}\left|\frac{\partial \ell}{\partial x_{i}}(x)\right|<$ $+\infty$ for $i=1, \ldots, d$ and there exists $\xi>0$ such that $\ell(x)>\xi \quad \forall x \in \mathcal{C}$.

Remark 3.1. Assumption A1 is very common in functional estimation both in independent and dependent cases. However, it must be reinforced by Assumption A6 which ensure the convergence of the series which appear in proof of Lemma 3. We point out that A1 $i$ ) implies A1 $i i)$ for $d \geq 2$. Assumptions A2, A3, A4 and A6 are needed in the study of the bias term of $r_{1, n}(x)$ which is the kernel estimator of $r_{1}(x)$. We point out that we do not require for $K_{d}$ to be symmetric as in Guessoum and Ould Saïd (2008). Assumption A7 intervenes in the convergence of the kernel density.

In the sequel the letter $C$ denotes any generic constant.
Our main result is given in the following theorem which concerns the rate of the almost sure uniform convergence of the regression function.

Theorem 3.1. Under Assumptions A1-A7, we have
$\sup _{x \in \mathcal{C}}\left|m_{n}(x)-m(x)\right|=O\left(\sqrt{\frac{\log n}{n h_{n}^{d}}}+\sqrt{h_{n}^{d(\nu-2)} \log n}\right)+O\left(h_{n}\right)$ a.s $\quad$ as $n \rightarrow \infty$.
Remark 3.2. The rate obtained here is slightly different from that obtained by Guessoum and Ould Saïd (2008) in the independent case, which is $O\left(\max \left\{\sqrt{\frac{\log n}{n h_{n}}}, h_{n}^{2}\right\}\right)$ for $d=1$. Their result can easily be generalized for higher dimensional covariate, ie $X \in \mathbb{R}^{d}$, by adapting their Assumptions A2 and A4 to obtain the rate $O\left(\max \left\{\sqrt{\frac{\log n}{n h_{n}^{d}}}, h_{n}^{2}\right\}\right)$.

Remark 3.3. If we choose $h_{n}=O\left(\left(\frac{\log n}{n}\right)^{1 / d+2}\right)$ then Theorem 3.1 becomes:

$$
\sup _{x \in \mathcal{C}}\left|m_{n}(x)-m(x)\right|=O\left(\left(\frac{\log n}{n}\right)^{\frac{1}{d+2}}\right) \quad \text { a.s. }
$$

This is the optimal rate obtained by Liebscher (2001) in the uncensored case.

## 4. Simulations study

First, we consider the strong mixing bidimentionnal process generated by:

$$
\begin{aligned}
X_{i} & =\rho X_{i-1}+\sqrt{1-\rho^{2}} \epsilon_{i} \\
Y_{i} & =X_{i+1} \quad i=1,2, \ldots, n
\end{aligned}
$$

where $0<\rho<1,\left(\epsilon_{i}\right)_{i}$ is a white noise with standard Gaussian distribution and $X_{0}$ is a standard Gaussian rv independent of $\left(\epsilon_{i}\right)_{i}$. We also simulate $n$ iid rv $C_{i}$ exponentially distributed with parameter $\lambda=1.5$. It is clear that the process $\left(X_{n}, Y_{n}, C_{n}\right)$ is stationary and strongly mixing, in fact the process $\left(X_{n}\right)$ is an $\operatorname{AR}(1)$ and given $X_{1}=x$, we have $Y_{1}=\rho x+\sqrt{1-\rho^{2}} \epsilon_{2}$, then, $Y_{1} \rightsquigarrow N\left(\rho x, 1-\rho^{2}\right)$. We calculate our estimator based on the observed data $\left(X_{i}, T_{i}, \delta_{i},\right) i=1, \ldots, n$, by choosing a Gaussian kernel $K$. In this case, we have $m(x)=\mathbb{E}\left(Y_{1} \mid X_{1}=x\right)=\rho x$. In all cases we took $h_{n}$ satisfying A6, that is $h_{n}=O\left((\log n / n)^{1 / 3}\right)$. The following graphs show the behavior of our estimator when the percentage of censoring and $\rho$ increase, for $n$ rather large (here $n=$ 300). One notices without surprise that the best behavior is obtained for a rate of censoring equal to 0 (uncensored case) and an index of weak dependence ( $\rho=0.1$ ).

We see that the asymptotic behavior is better for a small $\rho$ and a weak rate of censoring which is conforted by the following table, where we show how the quality of the estimation is influenced by the percentage of the censoring which appear clearly when we have high censoring, for various values of $\rho$ and $n$. The quality becomes slightly worse when we have high percentage of censoring, however it remains acceptable.


Fig 1. $m(x)=\rho x$, with $\rho=0.1, n=300$ and a percentage of censoring $=0 \%, 20 \%$ and $40 \%$, respectively.




Fig 2. $m(x)=\rho x$, with $\rho=0.9, n=300$ and a percentage of censoring $=0 \%, 20 \%$ and $40 \%$, respectively.

Here we use the mean squarre error of the estimator with respect to the theoretical value. For each values $n$ and $\rho$ we replicate $B=100$ times and taking the median over $x \in[-2,2]$, that is

$$
\operatorname{med}_{x \in[-2,2]}\left[\frac{1}{100} \sum_{i=1}^{100} \mathbb{E}\left[m_{n}(x)-m(x)\right]^{2}\right],
$$

which are consigned in the following table.
It is clear that the high censoring and the dependency (for high values of $\rho$ ) affect slitghly the accuracy which is predictable but it remains all in all satisfactory.

We also consider two nonlinear cases with a percentage of censoring $=15 \%$ and $\rho=0.9$

$$
\begin{align*}
Y_{i} & =\sin \left(\frac{\pi}{2} X_{i}\right), \quad \text { sinus case }  \tag{5}\\
Y_{i} & =\frac{5}{12} X_{i+1}^{2}-0.15, \quad \text { parabolic case. } \tag{6}
\end{align*}
$$

| percentage of censoring | $n=50$ |  |  | $n=100$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\rho=0.9$ | $\rho=0.3$ | $\rho=0.1$ | $\rho=0.9$ | $\rho=0.3$ | $\rho=0.1$ |
| 0\% | 0.180 | 0.070 | 0.059 | 0.099 | 0.045 | 0.041 |
| 20\% | 0.484 | 0.086 | 0.064 | 0.365 | 0.073 | 0.035 |
| 40\% | 0.648 | 0.094 | 0.063 | 0.577 | 0.088 | 0.053 |


| percentage of censoring | $n=300$ |  |  |
| :---: | :---: | :---: | :---: |
| $0 \%$ <br> $20 \%$ <br> $40 \%$ | $\rho=0.9$ | $\rho=0.3$ | $\rho=0.1$ |
|  | 0.305 | 0.016 | 0.010 |



FIG 3. $m(x)=\sin \frac{\pi}{2} x$, with $n=50,100$ and 300 , respectively.


FIG 4. $m(x)=\frac{5}{12} \rho^{2} x^{2}+\frac{5}{12}\left(1-\rho^{2}\right)-0.15$, with $n=50,100$ and 300 , respectively.

Then we have $m(x)=\sin \left(\frac{\pi}{2} x\right)$ for (5) and $m(x)=\frac{5}{12} \rho^{2} x^{2}+\frac{5}{12}\left(1-\rho^{2}\right)-0.15$ for (6).

Figures 3 and 4 show that the quality of fit for the non linear model is as good as in the linear model. Furthermore, we see that the quality is better when $n$ increase.

## 5. Proofs

We split the proof of the Theorem 3.1 in the following Lemmata.
Lemma 5.1. Under Assumptions $\boldsymbol{A 1} \boldsymbol{A 2}$ i) and $\boldsymbol{A} 3$, for $n$ large enough:

$$
\sup _{x \in \mathcal{C}}\left|\mathbb{E}\left(\tilde{r}_{1, n}(x)\right)-r_{1}(x)\right|=O\left(h_{n}\right) \quad \text { a.s. }
$$

Proof of Lemma 5.1. Observe that

$$
\begin{aligned}
\mathbb{E}\left(\left.\frac{\delta_{1} T_{1}}{\bar{G}\left(T_{1}\right)} \right\rvert\, X_{1}=u\right) & =\mathbb{E}\left[\left.\mathbb{E}\left[\left.\frac{\mathbb{1}_{\left\{Y_{1} \leq C_{1}\right\}} Y_{1}}{\bar{G}\left(Y_{1}\right)} \right\rvert\, Y_{1}\right] \right\rvert\, X_{1}=u\right] \\
& =\mathbb{E}\left[\left.\frac{Y_{1}}{\bar{G}\left(Y_{1}\right)} \mathbb{E}\left[\mathbb{1}_{\left\{Y_{1} \leq C_{1}\right\}} \mid Y_{1}\right] \right\rvert\, X_{1}=u\right] \\
& =\mathbb{E}\left[Y_{1} \mid X_{1}=u\right] \\
& =m(u) .
\end{aligned}
$$

Then, we have from (3)

$$
\begin{aligned}
\mathbb{E}\left(\tilde{r}_{1, n}(x)\right)-r_{1}(x) & =\mathbb{E}\left(\frac{1}{h_{n}^{d}} \frac{\delta_{1} T_{1}}{\bar{G}\left(T_{1}\right)} K_{d}\left(\frac{x-X_{1}}{h_{n}}\right)\right)-r_{1}(x) \\
& =\mathbb{E}\left(\frac{1}{h_{n}^{d}} K_{d}\left(\frac{x-X_{1}}{h_{n}}\right) \mathbb{E}\left(\left.\frac{\delta_{1} T_{1}}{\bar{G}\left(T_{1}\right)} \right\rvert\, X_{1}\right)\right)-r_{1}(x) \\
& =\int_{\mathbb{R}^{d}} \frac{1}{h_{n}^{d}} K_{d}\left(\frac{x-u}{h_{n}}\right) m(u) \ell(u) d u-r_{1}(x) \\
& =\int_{\mathbb{R}^{d}} K_{d}(t)\left[r_{1}\left(x-h_{n} t\right)-r_{1}(x)\right] d t
\end{aligned}
$$

since $r_{1}=m \ell$.
A Taylor expansion gives

$$
r_{1}\left(x-h_{n} t\right)-r_{1}(x)=-h_{n}\left(t_{1} \frac{\partial r_{1}}{\partial x_{1}}\left(x^{\prime}\right)+\cdots+t_{d} \frac{\partial r_{1}}{\partial x_{d}}\left(x^{\prime}\right)\right)
$$

where $x^{\prime}$ is between $x-h_{n} t$ and $x$. Then

$$
\begin{aligned}
\sup _{x \in \mathcal{C}}\left|\mathbb{E}\left(\tilde{r}_{1, n}(x)\right)-r_{1}(x)\right| & =\sup _{x \in \mathcal{C}}\left|\int_{\mathbb{R}^{d}} K_{d}(t)\left[r_{1}\left(x-h_{n} t\right)-r_{1}(x)\right] d t\right| \\
& \leq h_{n} \sup _{x \in \mathcal{C}} \int_{\mathbb{R}^{d}}\left|K_{d}(t)\left(t_{1} \frac{\partial r_{1}}{\partial x_{1}}\left(x^{\prime}\right)+\cdots+t_{d} \frac{\partial r_{1}}{\partial x_{d}}\left(x^{\prime}\right)\right) d t\right|
\end{aligned}
$$

Then Assumptions A1, A2 i) and A3, give the result.
Now, we introduce the following lemma (Ferraty and Vieu (2006) Proposition A. 11 ii), p. 237).

Lemma 5.2. Let $\left\{U_{i}, i \in \mathbb{N}\right\}$ be a sequence of real random variables, with strong mixing coefficient $\alpha(n)=O\left(n^{-\nu}\right), \nu>1$, such that $\forall n \in \mathbb{N}, \forall i \in \mathbb{N}, 1 \leq i \leq$ $n\left|U_{i}\right|<+\infty$. Then for each $\varepsilon>0$ and for each $q>1$ :

$$
\mathbb{P}\left\{\left|\sum_{i=1}^{n} U_{i}\right|>\varepsilon\right\} \leq C\left(1+\frac{\varepsilon^{2}}{q S_{n}^{2}}\right)^{-\frac{q}{2}}+n C q^{-1}\left(\frac{2 q}{\varepsilon}\right)^{\nu+1}
$$

where $S_{n}^{2}=\sum_{i} \sum_{j}\left|\operatorname{cov}\left(U_{i}, U_{j}\right)\right|$.
Lemma 5.3. Under Assumptions A1-A 6, we have
$\sup _{x \in \mathcal{C}}\left|\tilde{r}_{1, n}(x)-\mathbb{E}\left(\tilde{r}_{1, n}(x)\right)\right|=O\left(\sqrt{\frac{\log n}{n h_{n}^{d}}}+\sqrt{h_{n}^{d(\nu-2)} \log n}\right) \quad$ a.s $\quad$ as $n \rightarrow \infty$.
Proof of Lemma 5.3. $\mathcal{C}$ is a compact set, then it admits a covering $\mathfrak{S}$ by a finite number $\mathfrak{s}_{n}$ of balls $\mathcal{B}_{k}\left(x_{k}^{*}, a_{n}^{d}\right)$ centered at $x_{k}^{*}=\left(x_{1, k}^{*}, \ldots x_{d, k}^{*}\right), \quad k \in$ $\left\{1, \ldots, \mathfrak{s}_{n}\right\}$. Then for all $x \in \mathcal{C}$ there exists $k \in\left\{1, \ldots, \mathfrak{s}_{n}\right\}$ such that $\left\|x-x_{k}^{*}\right\| \leq$ $a_{n}^{d}$, where $a_{n}$ verifies $a_{n}^{d \gamma}=h_{n}^{d\left(\gamma+\frac{1}{2}\right)} n^{-\frac{d}{2}},(\gamma$ is the same as in Assumption A2 iii)). Since $\mathcal{C}$ is bounded there exists a constant $M>0$ such that $\mathfrak{s}_{n} \leq \frac{M}{a_{n}^{d}}$.

Now we set, for $x \in \mathcal{C}$ :

$$
\Delta_{i}(x)=\frac{1}{n h_{n}^{d}} \frac{\delta_{i} T_{i}}{\bar{G}\left(T_{i}\right)} K_{d}\left(\frac{x-X_{i}}{h_{n}}\right)-\mathbb{E}\left(\frac{1}{n h_{n}^{d}} \frac{\delta_{1} T_{1}}{\bar{G}\left(T_{1}\right)} K_{d}\left(\frac{x-X_{1}}{h_{n}}\right)\right) .
$$

It is obvious that

$$
\sum_{i=1}^{n} \Delta_{i}(x)=\tilde{r}_{1, n}(x)-\mathbb{E}\left(\tilde{r}_{1, n}(x)\right)
$$

Writing $\Delta_{i}(x)-\Delta_{i}\left(x_{k}^{*}\right)=\tilde{\Delta}_{i}(x)$, we have clearly $\left|\Delta_{i}(x)\right| \leq\left|\tilde{\Delta}_{i}(x)\right|+\left|\Delta_{i}\left(x_{k}^{*}\right)\right|$. Then,

$$
\begin{aligned}
\sup _{x \in \mathcal{C}}\left|\sum_{i=1}^{n} \tilde{\Delta}_{i}(x)\right| \leq & \sup _{x \in \mathcal{C}}\left\{\frac{1}{n} \sum_{i=1}^{n} \frac{\delta_{i}\left|T_{i}\right|}{\bar{G}\left(T_{i}\right)} \frac{1}{h_{n}^{d}}\left|K_{d}\left(\frac{x-X_{i}}{h_{n}}\right)-K_{d}\left(\frac{x_{k}^{*}-X_{i}}{h_{n}}\right)\right|\right\} \\
& +\sup _{x \in \mathcal{C}}\left\{\mathbb{E}\left(\frac{\delta_{1}\left|T_{1}\right|}{\bar{G}\left(T_{1}\right)} \frac{1}{h_{n}^{d}}\left|K_{d}\left(\frac{x-X_{1}}{h_{n}}\right)-K_{d}\left(\frac{x_{k}^{*}-X_{1}}{h_{n}}\right)\right|\right)\right\} .
\end{aligned}
$$

From Assumption A2 iii)

$$
\begin{aligned}
\sup _{x \in \mathcal{C}}\left|\sum_{i=1}^{n} \tilde{\Delta}_{i}(x)\right| & \leq \sup _{x \in \mathcal{C}}\left(\frac{2 \mathbb{E}\left(\left|Y_{1}\right|\right)}{\bar{G}\left(\tau_{F}\right)} \frac{1}{h_{n}^{d}}\left\|\frac{x-x_{k}^{*}}{h_{n}}\right\|^{\gamma}\right) \leq \frac{\mathbb{E}\left(\left|Y_{1}\right|\right)}{\bar{G}\left(\tau_{F}\right)} \frac{a_{n}^{d \gamma}}{h_{n}^{\gamma+d}} \\
& \leq \frac{\mathbb{E}\left(\left|Y_{1}\right|\right)}{\bar{G}\left(\tau_{F}\right)} \frac{h_{n}^{d\left(\gamma+\frac{1}{2}\right)} n^{-\frac{d}{2}}}{h_{n}^{\gamma+d}} \leq \frac{C}{\sqrt{n h_{n}^{d}}} h_{n}^{\gamma(d-1)} .
\end{aligned}
$$

Assumption A1 $i$ ) implies that $\sup _{x \in \mathcal{C}}\left|\sum_{i=1}^{n} \tilde{\Delta}_{i}(x)\right|=O\left(\frac{1}{\sqrt{n h_{n}^{d}}}\right) \quad$ a.s.

On the other hand, let $U_{i}=n h_{n}^{d} \Delta_{i}\left(x_{k}^{*}\right)$. In order to apply Lemma 5.2, we have to calculate $S_{n}^{2}$. It is clear that

$$
S_{n}^{2}=\sum_{\substack{i \\ i \neq j}} \sum_{j}\left|\operatorname{cov}\left(U_{i}, U_{j}\right)\right|+n \operatorname{Var}\left(U_{1}\right)
$$

We have

$$
\begin{aligned}
\operatorname{Var}\left(U_{1}\right) & =\mathbb{E}\left[\frac{\delta_{1}^{2} T_{1}^{2}}{\bar{G}^{2}\left(T_{1}\right)} K_{d}^{2}\left(\frac{x_{k}^{*}-X_{1}}{h_{n}}\right)\right]-\mathbb{E}^{2}\left[\frac{\delta_{1} T_{1}}{\bar{G}\left(T_{1}\right)} K_{d}\left(\frac{x_{k}^{*}-X_{1}}{h_{n}}\right)\right] \\
& =: \mathcal{I}_{1}-\mathcal{I}_{2}
\end{aligned}
$$

Using the conditional expectation properties and a change of variables, we get

$$
\begin{aligned}
\mathcal{I}_{1} & =\mathbb{E}\left[\frac{\delta_{1}^{2} T_{1}^{2}}{G^{2}\left(T_{1}\right)} K_{d}^{2}\left(\frac{x_{k}^{*}-X_{1}}{h_{n}}\right)\right] \\
& =\mathbb{E}\left[K_{d}^{2}\left(\frac{x_{k}^{*}-X_{1}}{h_{n}}\right) \mathbb{E}\left(\left.\frac{\delta_{1}^{2} T_{1}^{2}}{G^{2}\left(T_{1}\right)} \right\rvert\, X_{1}\right)\right] \\
& \leq \frac{h_{n}^{d}}{\bar{G}\left(\tau_{F}\right)} \int_{\mathbb{R}^{d}} K_{d}^{2}(t) r_{2}\left(x_{k}^{*}-h_{n} t\right) d t .
\end{aligned}
$$

By a Taylor expansion around $x_{k}^{*}$, under Assumptions A2 ii) and A4, we obtain

$$
\mathcal{I}_{1}=O\left(h_{n}^{d}\right)
$$

From Assumption A3,

$$
\begin{aligned}
\mathcal{I}_{2} & =\mathbb{E}^{2}\left[K_{d}\left(\frac{x_{k}^{*}-X_{1}}{h_{n}}\right) \mathbb{E}\left[\left.\frac{\delta_{1} T_{1}}{\bar{G}\left(T_{1}\right)} \right\rvert\, X_{1}\right]\right] \\
& =\left[\int_{\mathbb{R}^{d}} K_{d}\left(\frac{x_{k}^{*}-u}{h_{n}}\right) r_{1}(u) d t\right]^{2} \\
& =O\left(h_{n}^{2 d}\right) .
\end{aligned}
$$

Finally $\operatorname{Var}\left(U_{1}\right)=O\left(h_{n}^{d}\right)$.
Now let $S_{n}^{2 *}=\sum_{i \neq j} \sum_{j}\left|\operatorname{cov}\left(U_{i}, U_{j}\right)\right|$, a direct calculus of $\left|\operatorname{cov}\left(U_{i}, U_{j}\right)\right|$ gives

$$
\begin{aligned}
\left|\operatorname{cov}\left(U_{i}, U_{j}\right)\right| & =\left|\mathbb{E}\left(U_{i} U_{j}\right)\right| \\
& =\left\lvert\, \mathbb{E}\left\{\left[\frac{\delta_{i} T_{i}}{\bar{G}\left(T_{i}\right)} K_{d}\left(\frac{x_{k}^{*}-X_{i}}{h_{n}}\right)-\mathbb{E}\left(\frac{\delta_{i} T_{i}}{\bar{G}\left(T_{i}\right)} K_{d}\left(\frac{x_{k}^{*}-X_{i}}{h_{n}}\right)\right)\right]\right.\right.
\end{aligned}
$$

$$
\left.\times\left[\frac{\delta_{j} T_{j}}{\bar{G}\left(T_{j}\right)} K_{d}\left(\frac{x_{k}^{*}-X_{j}}{h_{n}}\right)-\mathbb{E}\left(\frac{\delta_{j} T_{j}}{\bar{G}\left(T_{j}\right)} K_{d}\left(\frac{x_{k}^{*}-X_{j}}{h_{n}}\right)\right)\right]\right\}
$$

$$
\leq\left|\mathbb{E}\left(\frac{Y_{i}}{\bar{G}\left(Y_{i}\right)} K_{d}\left(\frac{x_{k}^{*}-X_{i}}{h_{n}}\right) \frac{Y_{j}}{\bar{G}\left(Y_{j}\right)} K_{d}\left(\frac{x_{k}^{*}-X_{j}}{h_{n}}\right)\right)\right|
$$

$$
+\left|\mathbb{E}\left(\frac{Y_{i}}{\bar{G}\left(Y_{i}\right)} K_{d}\left(\frac{x_{k}^{*}-X_{i}}{h_{n}}\right)\right) \mathbb{E}\left(\frac{Y_{j}}{\bar{G}\left(Y_{j}\right)} K_{d}\left(\frac{x_{k}^{*}-X_{j}}{h_{n}}\right)\right)\right|
$$

$$
\leq C h_{n}^{2 d} \int_{\mathbb{R}^{d}} \int_{\mathbb{R}^{d}} K_{d}(z) K_{d}(t)
$$

$$
\times\left[\ell_{i j}\left(x_{k}^{*}-z h_{n}, x_{k}^{*}-t h_{n}\right)+\ell_{i}\left(x_{k}^{*}-z h_{n}\right) \ell_{j}\left(x_{k}^{*}-t h_{n}\right)\right] d z d t
$$

Assumption A5 gives

$$
\begin{equation*}
\left|\operatorname{cov}\left(U_{i}, U_{j}\right)\right|=O\left(h_{n}^{2 d}\right) \tag{7}
\end{equation*}
$$

On the other hand, from a result in Bosq (1998, p. 22), we have

$$
\begin{equation*}
\left|\operatorname{cov}\left(U_{i}, U_{j}\right)\right| \leq C \alpha(|i-j|) \tag{8}
\end{equation*}
$$

Then to evaluate $S_{n}^{2 *}$ the idea is to introduce a sequence of integers $w_{n}$ which we will precise below. Then we use (7) for the close $i$ and $j$ and (8) otherwise. That is

$$
\begin{aligned}
S_{n}^{2 *} & =\sum_{\left\{0<|i-j| \leq w_{n}\right\}}\left|\operatorname{cov}\left(U_{i}, U_{j}\right)\right|+\sum_{\left\{|i-j|>w_{n}\right\}}\left|\operatorname{cov}\left(U_{i}, U_{j}\right)\right| \\
& \leq C \sum_{\left\{0<|i-j| \leq w_{n}\right\}} h_{n}^{2 d}+C \sum_{\left\{|i-j|>w_{n}\right\}} \sum^{2 d} \alpha(|i-j|) \\
& \leq C\left(n h_{n}^{2 d} w_{n}\right)+C n^{2} \alpha\left(w_{n}\right) .
\end{aligned}
$$

Now choosing $w_{n}=\left[\frac{1}{h_{n}^{d}}\right]+1$, we have $S_{n}^{2 *} \leq O\left(n h_{n}^{d}\right)+C n^{2} \alpha\left(\frac{1}{h_{n}^{d}}\right)$. The mixing coefficient yields $n^{2} \alpha\left(\frac{1}{h_{n}^{d}}\right)=O\left(n^{2} h_{n}^{d \nu}\right)$.

So

$$
S_{n}^{2 *}=O\left(n h_{n}^{d}\right)+O\left(n^{2} h_{n}^{d \nu}\right)
$$

Finally, we have

$$
S_{n}^{2}=S_{n}^{2 *}+n \operatorname{Var}\left(U_{1}\right)=O\left(n h_{n}^{d}\right)+O\left(n^{2} h_{n}^{d \nu}\right)
$$

Then, for $\varepsilon>0$, applying Lemma 5.2, we have

$$
\begin{align*}
\mathbb{P}\left\{\left|\sum_{i=1}^{n} \Delta_{i}\left(x^{* k}\right)\right|>\varepsilon\right\} & =\mathbb{P}\left\{\left|\sum_{i=1}^{n} U_{i}\right|>n h_{n}^{d} \varepsilon\right\} \\
& \leq C\left(1+C \frac{\varepsilon^{2} n h_{n}^{d}}{q\left(1+n h_{n}^{d(\nu-1)}\right)}\right)^{-\frac{q}{2}}+n C q^{-1}\left(\frac{q}{\varepsilon n h_{n}^{d}}\right)^{\nu+1} \tag{9}
\end{align*}
$$

If we replace $\varepsilon$ by $\varepsilon_{0}\left(\sqrt{\frac{\log n}{n h_{n}^{d}}}+\sqrt{h_{n}^{d(\nu-2)} \log n}\right)=: \varepsilon_{n}$ for all $\varepsilon_{0}>0$ in (9), we get

$$
\left.\begin{array}{l}
\mathbb{P}\left\{\left|\sum_{i=1}^{n} \Delta_{i}\left(x^{* k}\right)\right|>\varepsilon_{n}\right\} \\
\quad \leq C\left(1+C \frac{\varepsilon_{0}^{2} \log n}{q}\right)^{-\frac{q}{2}}+n C q^{-1}\left(\frac{q}{\varepsilon_{0}\left(\sqrt{\frac{\log n}{n h_{n}^{d}}}+\sqrt{h_{n}^{d(\nu-2)} \log n}\right.}\right) \tag{10}
\end{array}\right)^{\nu+1} .
$$

By choosing $q=(\log n)^{1+b} \quad(b>0),(10)$ becomes

$$
\begin{aligned}
\mathbb{P}\left\{\left|\sum_{i=1}^{n} \Delta_{i}\left(x^{* k}\right)\right|>\varepsilon_{n}\right\} & \leq C n^{-C \varepsilon_{0}^{2}}+n C q^{-1}\left(\frac{q}{\varepsilon_{0}}\right)^{\nu+1}\left(n h_{n}^{d} \log n\right)^{-\frac{\nu+1}{2}} \\
& \leq C n^{-C \varepsilon_{0}^{2}}+C \varepsilon_{0}^{-(\nu+1)}(\log n)^{\nu(1+b)} n^{1-\frac{\nu+1}{2}} h_{n}^{-\frac{d(\nu+1)}{2}} .
\end{aligned}
$$

Now we can write

$$
\begin{align*}
& \mathbb{P}\left\{\max _{k=1, \ldots, \mathfrak{s}_{n}}\left|\sum_{i=1}^{n} \Delta_{i}\left(x^{* k}\right)\right|>\varepsilon_{0}\left(\sqrt{\frac{\log n}{n h_{n}^{d}}}+\sqrt{h_{n}^{d(\nu-2)} \log n}\right)\right\} \\
& \quad \leq \sum_{i=1}^{\mathfrak{s}_{n}} \mathbb{P}\left\{\left|\sum_{i=1}^{n} \Delta_{i}\left(x^{* k}\right)\right|>\varepsilon_{n}\right\} \\
& \quad \leq M a_{n}^{-d}\left(C n^{-C \varepsilon_{0}^{2}}+C \varepsilon_{0}^{-(\nu+1)}(\log n)^{\nu(1+b)} n^{1-\frac{\nu+1}{2}} h_{n}^{-\frac{d(\nu+1)}{2}}\right) \\
& \quad \leq C M h_{n}^{-d\left(1+\frac{1}{2 \gamma}\right)} n^{\frac{d}{2 \gamma}-C \varepsilon_{0}^{2}} \\
& \quad+M C \varepsilon_{0}^{-(\nu+1)}(\log n)^{\nu(1+b)} n^{1-\frac{\nu+1}{2}+\frac{d}{2 \gamma}} h_{n}^{-\frac{d(\nu+1)}{2}-\frac{d}{2 \gamma}-d} \\
& \quad=: C M J_{1}+M C \varepsilon_{0}^{-(\nu+1)} J_{2} . \tag{11}
\end{align*}
$$

We have from Assumption A6

$$
\begin{aligned}
J_{2} & \leq C(\log n)^{\nu(1+b)} n^{1-\frac{\nu+1}{2}+\frac{d}{2 \gamma}} n^{-\frac{(3-\nu)}{2}-\theta d\left(\frac{\gamma(\nu+1)+2 \gamma+1}{2 \gamma}\right)} \\
& \leq C(\log n)^{\nu(1+b)} n^{-1-\theta d\left(\frac{\gamma(\nu+1)+2 \gamma+1-\frac{1}{\theta}}{2 \gamma}\right)} .
\end{aligned}
$$

Then, for an appropriate choice of $\theta, J_{2}$ is the general term of a convergent series. In the same way, $J_{1} \leq n^{\varsigma-C \varepsilon_{0}^{2}}$ and we can choose $\varepsilon_{0}$ such that $J_{1}$ is the general term of convergent series. Finally, applying Borel-Cantelli lemma, to (11) gives the result.

Remark 5.1. We point out that the parameter $\theta$ of Assumption A6 can be chosen such as:

$$
\theta>\frac{1}{\gamma(\nu+1)+2 \gamma+1}
$$

This condition ensures the convergence of the series of Lemma 5.3.
Lemma 5.4. Under Assumptions A1-A2 and A5-A7,

$$
\sup _{x \in \mathcal{C}}\left|\ell_{n}(x)-\ell(x)\right|=O\left(\sqrt{\frac{\log n}{n h_{n}^{d}}}+\sqrt{h_{n}^{d(\nu-2)} \log n}\right)+O\left(h_{n}\right) \quad \text { a.s } \quad \text { as } n \rightarrow \infty .
$$

Proof of Lemma 5.4. We have

$$
\sup _{x \in \mathcal{C}}\left|\ell(x)-\ell_{n}(x)\right| \leq \sup _{x \in \mathcal{C}}\left|\ell_{n}(x)-\mathbb{E}\left(\ell_{n}(x)\right)\right|+\sup _{x \in \mathcal{C}}\left|\mathbb{E}\left(\ell_{n}(x)\right)-\ell(x)\right| .
$$

By Assumptions A1-A2, A5-A7, by an analogous proof to that of Lemma 5.3 without censoring (that is $\bar{G}\left(T_{i}\right)=1, \delta_{i}=1$ and $Y_{i}=1$ ) and putting $\varepsilon=\varepsilon_{0}\left(\sqrt{\frac{\log n}{n h_{n}^{d}}}+\sqrt{h_{n}^{d(\nu-2)} \log n}\right)$ we get

$$
\begin{equation*}
\sup _{x \in \mathcal{C}}\left|\ell_{n}(x)-\mathbb{E}\left(\ell_{n}(x)\right)\right|=O\left(\sqrt{\frac{\log n}{n h_{n}^{d}}}+\sqrt{h_{n}^{d(\nu-2)} \log n}\right) . \tag{12}
\end{equation*}
$$

Furthermore, under A2 i) and A7 and using a Taylor expansion, we get

$$
\sup _{x \in \mathcal{C}}\left|\mathbb{E}\left(\ell_{n}(x)\right)-\ell(x)\right|=O\left(h_{n}\right)
$$

which permit us to conclude.
Lemma 5.5. Under Assumptions A1-A2, A5-A7, we have

$$
\sup _{x \in \mathcal{C}}\left|r_{1, n}(x)-\tilde{r}_{1, n}(x)\right|=o\left(h_{n}\right) \quad \text { a.s } \quad \text { as } n \rightarrow \infty .
$$

Proof of Lemma 5.5. We have from (3) and (4)

$$
\begin{aligned}
& \left|r_{1, n}(x)-\tilde{r}_{1, n}(x)\right| \\
& \quad=\frac{1}{n h_{n}^{d}}\left|\sum_{i=1}^{n} \frac{\mathbb{1}_{\left\{Y_{i}<C_{i}\right\}} Y_{i}}{\bar{G}_{n}\left(Y_{i}\right)} K_{d}\left(\frac{x-X_{i}}{h_{n}}\right)-\frac{\mathbb{1}_{\left\{Y_{1}<C_{1}\right\}} Y_{i}}{\bar{G}\left(Y_{i}\right)} K_{d}\left(\frac{x-X_{i}}{h_{n}}\right)\right| \\
& \quad \leq \frac{1}{n h_{n}^{d}}\left|\sum_{i=1}^{n} Y_{i} K_{d}\left(\frac{x-X_{i}}{h_{n}}\right) \frac{\bar{G}\left(Y_{i}\right)-\bar{G}_{n}\left(Y_{i}\right)}{\bar{G}_{n}\left(Y_{i}\right) \bar{G}\left(Y_{i}\right)}\right| \\
& \quad \leq \frac{1}{\bar{G}_{n}\left(\tau_{F}\right) \bar{G}\left(\tau_{F}\right)} \sup _{t \leq \tau_{F}}\left(\left|\bar{G}_{n}(t)-\bar{G}(t)\right|\right) \frac{1}{n h_{n}^{d}} \sum_{i=1}^{n}\left|Y_{i}\right| K_{d}\left(\frac{x-X_{i}}{h_{n}}\right) .
\end{aligned}
$$

In the same way as for Theorem 2 of Cai (2001), it can be shown under A1 that

$$
\sup _{t \leq \tau_{F}}\left(\left|\bar{G}_{n}(t)-\bar{G}(t)\right|\right)=O\left(\sqrt{\frac{\log \log n}{n}}\right) \text { a.s. }
$$

Furthermore, from the definition of $\ell_{n}(x)$, Lemma 5.4, Assumptions A1, A2 and A7, and the fact that $Y$ is bounded we get the result.

Proof of Theorem 3.1. We have

$$
\begin{aligned}
& \sup _{x \in \mathcal{C}}\left|m_{n}(x)-m(x)\right| \\
& \leq \sup _{x \in \mathcal{C}}\left|\frac{r_{1, n}(x)}{\ell_{n}(x)}-\frac{\tilde{r}_{1, n}(x)}{\ell_{n}(x)}\right|+\left|\frac{\tilde{r}_{1, n}(x)}{\ell_{n}(x)}-\frac{\mathbb{E}\left(\tilde{r}_{1, n}(x)\right)}{\ell_{n}(x)}\right| \\
&+\left|\frac{\mathbb{E}\left(\tilde{r}_{1, n}(x)\right)}{\ell_{n}(x)}-\frac{r_{1}(x)}{\ell_{n}(x)}\right|+\left|\frac{r_{1}(x)}{\ell_{n}(x)}-\frac{r_{1}(x)}{\ell(x)}\right|
\end{aligned}
$$

$$
\begin{align*}
\leq & \frac{1}{\inf \ell_{n}(x)}\left\{\sup _{x \in \mathcal{C}}\left|r_{1, n}(x)-\tilde{r}_{1, n}(x)\right|+\sup _{x \in \mathcal{C}}\left|\tilde{r}_{1, n}(x)-\mathbb{E}\left(\tilde{r}_{1, n}(x)\right)\right|\right. \\
& \left.+\sup _{x \in \mathcal{C}}\left|\mathbb{E}\left(\tilde{r}_{1, n}(x)-r_{1}(x)\right)\right|+\sup _{x \in \mathcal{C}}\left(\left|r_{1}(x)\right| \xi^{-1}\right) \sup _{x \in \mathcal{C}}\left|\ell(x)-\ell_{n}(x)\right|\right\} \tag{13}
\end{align*}
$$

The kernel estimator $\ell_{n}(x)$ is almost surely bounded away from 0 because of Lemma 5.4 and Assumption A7.

Then (13) in conjunction with Lemmas 5.1, 5.3, 5.4 and 5.5 we conclude the proof.

## Acknowledgments

The authors are grateful to the associate editor and the two anonymous referees for their careful reading and appropriate remarks which gave them the opportunity to improve the rate of convergence, the simulation part and the quality of the paper.

## References

Bollerslev, T. (1986). General autoregressive conditional heteroskedasticity. J. Economt. 31:307-327. MR0853051

BosQ, D. (1998). Nonparametric statistics for stochastic processes. Estimation and Prediction. Lecture Notes in Statistics, 110, Springer-Verlag, New York. MR1640691
Bradley, R.D. (2007). Introduction to strong mixing conditions. Vol I-III, Kendrick Press, Utah.
Cai, J., Prentice, R.L. (1995). Estimating equations for hazard ratio parameters based on correlated failure time data. MR1332846
Cai, Z. (1998a). Asymptotic properties of Kaplan-Meier estimator for censored dependent data. Statist. \& Probab. Lett. 37:381-389. Biometrika. 82:151-164. MR1624415
CAI, Z. (1998b). Kernel density and hazard rate estimation for censored dependent data. J. Multivariate Anal. 67:23-34. MR1659104
CAI, Z. (2001). Estimating a distribution function for censored time series data. J. Multivariate Anal. 78:299-318. MR1859760

CAI, Z. (2003). Weighted local linear approach to censored nonparametric regression. In Recent advances and trends in nonparametric staistics (eds M. G. Atrikas \& D.M. Politis), Elsevier, Amesterdam, the Netherlands; San Diego, CA, 217-231.
Cai, Z., Ould Saïd, E. (2003). Local M-estimator for nonparametric time series. Statist \& Probab. Lett. 65:433-449. MR2039887
Carbonez, A., Györfi, L., Van der Meulin, E.C. (1995). Partitionestimate of a regression function under random censoring. Statist. \& Decisions, 13:21-37. MR1334076
Collomb, G. (1981). Estimation non-paramétrique de la régression: Revue Bibliographique. Internat. Statist. Rev. 49:75-93. MR0623011

Doukhan, P. (1994). Mixing: Properties and examples. Lecture Notes in Statistics, 85, Springer-Verlag, New York. MR1312160
El-Ghouch, A., Van Keilegom, I. (2008). Non-parametric regression with dependent censored data. Scand. J. Statist. 35:228-247. MR2418738
Engle, R.F. (1982). Autoregressive conditional heteroskedasticity with estimates of the variance of U.K. inflation. Econometrica 50:987-1007. MR0666121
Ferraty, F., Vieu, P. (2006). Nonparametric Functionnal Data Analysis. Theory and Practice. Springer-Verlag, New York. MR2229687
Gonzalez-Manteiga, W., Quintela-del-Rio, A., Vieu, P. (2002). A note on variable selection in nonprametric regression with dependent data. Statist. \& Probab. Lett. 57:259-268. MR1912084
Guessoum, Z., Ould Saïd, E. (2008). On the nonpararametric estimation of the regression function under censorship model. Statist. \& Decisions 26:159177. MR2512266

HÄrdle, W. (1990). Applied nonparametric regression. Cambridge University Press. MR1161622
Jones, D.A. (1978). Nonlinear autoregressive processes. Proc. Roy. Soc. London A 360, 71-95. MR0501672
Kaplan, E.L., Meier, P. (1958). Nonparametric estimation from incomplete observations. J. Amer. Statist. Assoc. 53:457-481. MR0093867
Liebscher, E. (2001). Estimation of the density and the regression function under mixing condition. Statist. \& Decisions 19:9-26. MR1817218
Liebscher, E. (2002). Kernel density and hazard rate estimation for censored data under $\alpha$-mixing condition. Ann. Inst. Statist. Math. 34:19-28. MR1893539
Lipsitz, S.R., Ibrahim, J.G. (2000). Estimation with correlated censored survival data with missing covariates. Biostatistics. 1: 315-327.
Masry, E., FAN, J. (1997). Local polynomial estimation of regression function for mixing processes. Scand. J. Statist. 24:165-179. MR1455865
Ozaki, T. (1979). Nonlinear time series models for nonlinear random vibrations. Technical report. Univ. of Manchester. MR0557437
Robinson, P.M. (1983). Nonparametric estimators for time series. J. Time Ser. Anal. 4:185-297. MR0732897
Silverman, B.W. (1986). Estimation for statistics and data analysis. Monographs on Statist. and Appl. Probab. Chapman \& Hall. London. MR0848134
TaE, Y.K., Cox, D.D. (1996). Uniform strong consistency of kernel density estimator under dependence. Statist. \& Probab. Lett. 26:179-185. MR1381469
Wand, M.P., Jones, M.C. (1995). Kernel smoothing. Chapman \& Hall. London. MR1319818
Wahba, G. (1990). Spline models for observational data. SIAM, Philadelphia. MR1045442
Wei, L.J., Lin, D.Y. (1989). Regression analysis of multivariate incomplete failure times by modelling marginal distribution. J. Amer. Statist. Assoc. 84: 1064-1073.


[^0]:    * Corresponding author.

