# CHARACTERIZATION OF CONVEXITY FOR A PIECEWISE $C^{2}$ FUNCTION BY THE LIMITING SECOND-ORDER SUBDIFFERENTIAL 

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#### Abstract

We prove in this paper that a piecewise $C^{2}$ function $\varphi: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is convex if and only if for every $(x, y) \in \operatorname{gph} \partial \varphi$, the limiting second-order subdifferential mapping $\partial^{2} \varphi(x, y): \mathbb{R}^{n} \rightrightarrows \mathbb{R}^{n}$ has the so-called positive semidefiniteness (PSD) - in analogy with the notion of positive semi-definiteness of symmetric real matrices. As a by-product, characterization for strong convexity of $\varphi$ is established.


## 1. Introduction

Due to its important role in mathematical economics, engineering, management science, and optimization theory, convexity of functions and sets has been studied intensively; see $[1,3,5-7,9,11,13,14]$ and the references therein.

First-order characterizations for the convexity of extended real-valued functions via the monotonicity of the Fréchet derivative and the monotonicity of the Fréchet subdifferential mapping or the limiting subdifferential mapping can be found, e.g., in $[6,11,12]$ and $[7$, Theorem 3.56].

The classical second-order characterization of convexity of real-valued functions (see for instance [11, 12]) says that a $C^{2}$ function $\varphi: U \rightarrow \mathbb{R}$ where $U$ is an open convex subset of $\mathbb{R}^{n}$ is convex if and only if for every $x \in U$ the Hessian $\nabla^{2} f(x)$ is a positive semidefinite matrix. To relax the assumption on the $C^{2}$ smoothness of the function under consideration, several authors have characterized the convexity by using various kinds of generalized second-order directional derivatives. The reader is referred to $[1,4,5,13,14]$ for results in this direction.

[^0]Recently, the authors in [3] have found that to a certain extent convexity of functions can be characterized by second-order subdifferential mappings. Among other things, they obtained some characterizations for convexity of piecewise linear functions and of piecewise $C^{2}$ functions of a special type via the limiting secondorder subdifferential. The purpose of this paper is to characterize the convexity of piecewise $C^{2}$ functions by the limiting second-order subdifferential.

We will show that a piecewise $C^{2}$ function $\varphi: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is convex if and only if for every $(x, y) \in \operatorname{gph} \partial \varphi$, the limiting second-order subdifferential mapping $\partial^{2} \varphi(x, y): \mathbb{R}^{n} \rightrightarrows \mathbb{R}^{n}$ has the so-called positive semi-definiteness (PSD) - in analogy with the notion of positive semi-definiteness of symmetric real matrices. Since strong convexity of functions plays a remarkable role in theory of algorithms [12] and stability theory of optimization problems [2], by using the limiting second-order subdifferential we derive a necessary and sufficient condition for strong convexity of piecewise $C^{2}$ functions.

The rest of the paper is organized as follows. Section 2 contains some definitions and results which are needed in the sequel. Section 3 is devoted to the necessary and sufficient condition for convexity of a piecewise $C^{2}$ function by its limiting secondorder subdifferential. As a by-product, the second-order necessary and sufficient condition for strong convexity of piecewise $C^{2}$ functions is given.

## 2. Preliminaries

We start by recalling some notions related to generalized differentiation. The notions and related results of generalized differentiation can be found in [7].

For a set $\Omega \subset \mathbb{R}^{n}$ and an extended real-valued function $\varphi: \mathbb{R}^{n} \rightarrow \overline{\mathbb{R}}$, the symbols $x \xrightarrow{\Omega} \bar{x}$ and $x \xrightarrow{\varphi} \bar{x}$ mean that $x \rightarrow \bar{x}$ with $x \in \Omega$ and $x \rightarrow \bar{x}$ with $\varphi(x) \rightarrow \varphi(\bar{x})$, respectively. Given a set-valued mapping $F: \mathbb{R}^{n} \rightrightarrows \mathbb{R}^{n}$, we denote by

$$
\begin{aligned}
\underset{x \rightarrow \bar{x}}{\operatorname{Limsup}} F(x):=\left\{x^{*} \in \mathbb{R}^{n} \mid \exists\right. & \text { sequences } x_{k} \xrightarrow{\Omega} \bar{x} \text { and } x_{k}^{*} \rightarrow x^{*} \\
& \text { with } \left.x_{k}^{*} \in F\left(x_{k}\right) \text { for all } k \in \mathbb{N}\right\}
\end{aligned}
$$

the sequential Painleve-Kuratowski upper limit of the mapping $F$ as $x \xrightarrow{\Omega} \bar{x}$.
Let $\varphi: \mathbb{R}^{n} \rightarrow \overline{\mathbb{R}}$ be finite at $\bar{x} \in \mathbb{R}^{n}$ and let $\varepsilon \geqslant 0$. The $\varepsilon$-subdifferential of $\varphi$ at $\bar{x}$ is the set $\widehat{\partial}_{\varepsilon} \varphi(\bar{x})$ defined by

$$
\widehat{\partial}_{\varepsilon} \varphi(\bar{x})=\left\{x^{*} \in \mathbb{R}^{n}: \liminf _{x \rightarrow \bar{x}} \frac{\varphi(x)-\varphi(\bar{x})-\left\langle x^{*}, x-\bar{x}\right\rangle}{\|x-\bar{x}\|} \geqslant-\varepsilon\right\} .
$$

We put $\widehat{\partial}_{\varepsilon} \varphi(\bar{x})=\emptyset$ if $|\varphi(\bar{x})|=\infty$. When $\varepsilon=0$ the set $\widehat{\partial}_{0} \varphi(\bar{x})$, denoted by $\widehat{\partial} \varphi(\bar{x})$, is called the Frechet subdifferential of $\varphi$ at $\bar{x}$. The limiting subdifferential (or Mordukhovich subdifferential) of $\varphi$ at $\bar{x}$ is given by

$$
\begin{equation*}
\partial \varphi(\bar{x})=\operatorname{Limsup}_{x \xrightarrow{\varphi} \bar{x} ; \varepsilon \downarrow 0} \widehat{\partial}_{\varepsilon} \varphi(x), \tag{2.1}
\end{equation*}
$$

that is, $x^{*} \in \partial \varphi(\bar{x})$ if and only if there exist sequences $\varepsilon_{k} \downarrow 0, x_{k} \xrightarrow{\varphi} \bar{x}$ and $x_{k}^{*} \rightarrow x^{*}$ such that $x_{k}^{*} \in \widehat{\partial}_{\varepsilon_{k}} \varphi\left(x_{k}\right)$. Note that $\widehat{\partial}_{\varepsilon} \varphi(\cdot)$ can be replaced by $\widehat{\partial} \varphi(\cdot)$ in (2.1) when $\varphi$ is lower semicontinuous around $\bar{x}$.

Given $\Omega \subset \mathbb{R}^{n}$ with its indicator function $\delta(x ; \Omega)=0$ if $x \in \Omega$ and $\delta(x ; \Omega)=$ $\infty$ otherwise, the Fréchet normal cone and the limiting normal cone to $\Omega$ at $x$ are defined, respectively, by

$$
\widehat{N}(x ; \Omega)=\widehat{\partial} \delta(x ; \Omega) \text { and } N(x ; \Omega)=\partial \delta(x ; \Omega)
$$

Obviously, $\widehat{N}(x ; \Omega) \subset N(x ; \Omega)$ and

$$
x^{*} \in \widehat{N}(x ; \Omega) \Leftrightarrow \limsup _{u \xrightarrow{\Omega} x} \frac{\left\langle x^{*}, u-x\right\rangle}{\|u-x\|} \leq 0
$$

Let $F: \mathbb{R}^{n} \rightrightarrows \mathbb{R}^{m}$ be a set-valued mapping with the graph

$$
\operatorname{gph} F=\left\{(x, y) \in \mathbb{R}^{n} \times \mathbb{R}^{m}: y \in F(x)\right\}
$$

The limiting coderivative $D^{*} F(\bar{x}, \bar{y}): \mathbb{R}^{m} \rightrightarrows \mathbb{R}^{n}$ of $F$ at $(\bar{x}, \bar{y}) \in \operatorname{gph} F$ is defined by

$$
D^{*} F(\bar{x}, \bar{y})\left(y^{*}\right)=\left\{x^{*} \in \mathbb{R}^{n}:\left(x^{*},-y^{*}\right) \in N((\bar{x}, \bar{y}) ; \operatorname{gph} F)\right\}
$$

We omit $\bar{y}=f(\bar{x})$ in the above coderivative notion if $F=f: \mathbb{R}^{n} \rightarrow \mathbb{R}^{m}$ is single-valued. If $f: \mathbb{R}^{n} \rightarrow \mathbb{R}^{m}$ is strictly differentiable at $\bar{x}$ in the sense that

$$
\lim _{x, u \rightarrow \bar{x}} \frac{f(x)-f(u)-\langle\nabla f(\bar{x}), x-u\rangle}{\|x-u\|}=0
$$

with the derivative operator $\nabla f(\bar{x}): \mathbb{R}^{m} \rightarrow \mathbb{R}^{m}$, being linear contiunous, then $D^{*} f(\bar{x})\left(y^{*}\right)=\left\{\nabla f(\bar{x})^{*} y^{*}\right\}$ for all $y^{*} \in \mathbb{R}^{m}$. Therefore, the limiting coderivative is an extension of the adjoint derivative operator of the classical derivative to nonsmooth functions and set-valued mappings.

Let $\varphi: \mathbb{R}^{n} \rightarrow \overline{\mathbb{R}}$ be an extended real-valued function with a finite value at $\bar{x}$. Given $\bar{y} \in \partial \varphi(\bar{x})$, the mapping $\partial^{2} \varphi(\bar{x}, \bar{y}): \mathbb{R}^{n} \rightrightarrows \mathbb{R}^{n}$ defined by

$$
\partial^{2} \varphi(\bar{x}, \bar{y})(u)=\left(D^{*} \partial \varphi\right)(\bar{x}, \bar{y})(u), \quad u \in \mathbb{R}^{n}
$$

is called the limiting second-order subdifferential of $\varphi$ at $\bar{x}$ relative to $\bar{y}$. If $\varphi$ is twice continuously differentiable at $\bar{x}$ and $\bar{y} \in \partial \varphi(\bar{x})$ (actually, $\bar{y}=\nabla \varphi(\bar{x})$ ), then

$$
\partial^{2} \varphi(\bar{x}, \bar{y})(u)=\left\{\nabla^{2} \varphi(\bar{x})(u)\right\} \text { for all } u \in \mathbb{R}^{n}
$$

which is known as the symmetric Hessian matrix. The reader can find various properties and calculus rules for the limiting second-order subdifferential with a number of applications in $[7,8,10]$ and the references therein.

Theorem 2.1. (see [3, Theorem 3.2]). Let $\varphi: \mathbb{R}^{n} \rightarrow \overline{\mathbb{R}}$ be proper lower semicontinuous. If $\varphi$ is convex, then

$$
\langle z, u\rangle \geq 0 \quad \text { for all } u \in \mathbb{R}^{n} \text { and } z \in \partial^{2} \varphi(x, y)(u) \text { with }(x, y) \in \operatorname{gph} \partial \varphi
$$

that is, for every $(x, y) \in \operatorname{gph} \partial \varphi$, the mapping $\partial^{2} \varphi(x, y): \mathbb{R}^{n} \rightrightarrows \mathbb{R}^{n}$ is positive semi-definite (PSD).

## 3. Characterization of Convexity

Recall that a function $\varphi: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is said to be piecewise $C^{2}$ if there exist families $\left\{P_{1}, \ldots, P_{k}\right\}$ of polyhedral convex sets in $\mathbb{R}^{n}$ and twice continuously differentiable functions $\varphi_{i}: \mathbb{R}^{n} \rightarrow \mathbb{R}$ such that $\mathbb{R}^{n}=\bigcup_{i=1}^{k} P_{i}, \operatorname{int} P_{i} \cap \operatorname{int} P_{j}=\emptyset$ for all $i \neq j$, and

$$
\begin{equation*}
\varphi(x)=\varphi_{i}(x) \text { for any } x \in P_{i}, \quad i \in\{1, \ldots, k\} \tag{3.1}
\end{equation*}
$$

From (3.1) it follows that $\varphi_{i}(x)=\varphi_{j}(x)$ whenever $x \in P_{i} \cap P_{j}$ and $i, j \in\{1, \ldots, k\}$.
We need the following two lemmas taken from [3].

Lemma 3.1. If $I:=\left\{i \in\{1,2, \ldots, k\} \mid \operatorname{int} P_{i} \neq \emptyset\right\}$, then $\bigcup_{i \in I} P_{i}=\mathbb{R}^{n}$.
Lemma 3.2. Let $[x, y]$ be an interval in $\mathbb{R}^{n}(x \neq y), 0=\tau_{0}<\tau_{1}<\ldots<$ $\tau_{m-1}<\tau_{m}=1(m \in \mathbb{N}, m>1)$, and $x_{i}:=x+\tau_{i}(y-x)(i=0,1, \ldots, m)$. Suppose that $\varphi$ is nonconvex and continuous on $[x, y]$. Then there must exist $i \in\{0,1, \ldots, m-2\}$ such that $\varphi$ is nonconvex on $\left[x_{i}, x_{i+2}\right]$.

We are now ready to state and prove the main result of this paper.
Theorem 3.3. Suppose that $\varphi: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is a piecewise $C^{2}$ function. Then $\varphi$ is convex if and only if

$$
\begin{equation*}
\langle z, u\rangle \geq 0 \text { for all } u \in \mathbb{R}^{n}, z \in \partial^{2} \varphi(x, y)(u) \text { with }(x, y) \in \operatorname{gph} \partial \varphi \tag{3.2}
\end{equation*}
$$

Proof. The necessary condition is due to Theorem 2.1. It remains to prove the sufficient condition. By Lemma 3.1, we can assume that $\operatorname{int} P_{i} \neq \emptyset$ for all $i \in\{1,2, \ldots, k\}$. Suppose that (3.2) holds but $\varphi$ is nonconvex. Since $\varphi$ is twice continuously differentiable on $\operatorname{int} P_{i}, \partial^{2} \varphi(x, y)(u)=\left\{\nabla^{2} \varphi(x)(u)\right\}$ for all $x \in$ $\operatorname{int} P_{i}, y \in \partial \varphi(x)$ and $u \in \mathbb{R}^{n}$. Together with (3.2) this implies that $\nabla^{2} \varphi(x)$ is positive semi-definite on $\operatorname{int} P_{i}$. By the classical result on characterizing the convexity of $C^{2}$ functions, $\varphi$ is convex on $P_{i}(i=1,2, \ldots, k)$. We consider the following two cases.

Case 1. $k=2$. Let $P_{1}=\left\{x \in \mathbb{R}^{n}:\langle a, x\rangle \leq \alpha\right\}, P_{2}=\left\{x \in \mathbb{R}^{n}:\langle a, x\rangle \geq\right.$ $\alpha\}\left(a \in \mathbb{R}^{n} \backslash\{0\}, \alpha \in \mathbb{R}\right), P_{12}=P_{1} \cap P_{2}$ and

$$
\varphi(x)= \begin{cases}\varphi_{1}(x) & \text { if } x \in P_{1} \\ \varphi_{2}(x) & \text { if } x \in P_{2}\end{cases}
$$

where $\varphi_{1}, \varphi_{2} \in C^{2}$ and $\varphi_{1}(x)=\varphi_{2}(x)$ for all $x \in P_{12}$. Observe that $\mathbb{R}^{n}$ is the union of disjoint nonempty sets $\operatorname{int} P_{1}, \operatorname{int} P_{2}, P_{12}$, and

$$
\partial \varphi(x)=\widehat{\partial} \varphi(x)= \begin{cases}\left\{\nabla \varphi_{1}(x)\right\} & \text { if } x \in \operatorname{int} P_{1}  \tag{3.3}\\ \left\{\nabla \varphi_{2}(x)\right\} & \text { if } x \in \operatorname{int} P_{1}\end{cases}
$$

Since $\varphi$ is convex on each one of the convex sets $P_{1}$ and $P_{2}$ but it is nonconvex on $\mathbb{R}^{n}=P_{1} \cup P_{2}$, there exist $x_{0} \in \operatorname{int} P_{1}, y_{0} \in \operatorname{int} P_{2}$ and $t_{1} \in(0,1)$ such that

$$
\begin{equation*}
\varphi\left(z_{1}\right)>\left(1-t_{1}\right) \varphi\left(x_{0}\right)+t_{1} \varphi\left(y_{0}\right), \tag{3.4}
\end{equation*}
$$

where $z_{1}=\left(1-t_{1}\right) x_{0}+t_{1} y_{0}$. We will prove that

$$
\begin{equation*}
\varphi\left(z_{0}\right)>\left(1-t_{0}\right) \varphi\left(x_{0}\right)+t_{0} \varphi\left(y_{0}\right) \tag{3.5}
\end{equation*}
$$

with $z_{0}=\left(1-t_{0}\right) x_{0}+t_{0} y_{0} \in P_{12}\left(t_{0} \in(0,1)\right)$. If $t_{0}=t_{1}$ then (3.5) follows from (3.4), because $z_{1}=z_{0}$. If $t_{0} \in\left(0, t_{1}\right)$ then $z_{1}=(1-\lambda) y_{0}+\lambda z_{0}$ with $\lambda=\left(1-t_{1}\right) /\left(1-t_{0}\right) \in(0,1)$. Since $\varphi$ is convex on $\left[z_{0}, y_{0}\right] \subset P_{2}, \varphi\left(z_{1}\right) \leq$ $(1-\lambda) \varphi\left(y_{0}\right)+\lambda \varphi\left(z_{0}\right)$. Combining this fact with (3.4), we obtain

$$
\begin{aligned}
\varphi\left(z_{0}\right) & >\lambda^{-1}\left[\left(1-t_{1}\right) \varphi\left(x_{0}\right)+t_{1} \varphi\left(y_{0}\right)-(1-\lambda) \varphi\left(y_{0}\right)\right] \\
& =\left(1-t_{0}\right) \varphi\left(x_{0}\right)+t_{0} \varphi\left(y_{0}\right)
\end{aligned}
$$

which gives (3.5). Similarly, (3.5) is also valid if $t_{0} \in\left(t_{1}, 1\right)$. Therefore (3.5) holds. Since $x_{0} \in P_{1}, y_{0} \in P_{2}$ and $z_{0} \in P_{12}$, by (3.5), we have

$$
\left(1-t_{0}\right) \varphi_{1}\left(z_{0}\right)+t_{0} \varphi_{2}\left(z_{0}\right)>\left(1-t_{0}\right) \varphi_{1}\left(x_{0}\right)+t_{0} \varphi_{2}\left(y_{0}\right)
$$

or in other words,

$$
\begin{equation*}
\left(1-t_{0}\right)\left(\varphi_{1}\left(z_{0}\right)-\varphi_{1}\left(x_{0}\right)\right)+t_{0}\left(\varphi_{2}\left(z_{0}\right)-\varphi_{2}\left(y_{0}\right)>0\right. \tag{3.6}
\end{equation*}
$$

According to the mean value theorem, we have
$\varphi_{1}\left(z_{0}\right)-\varphi_{1}\left(x_{0}\right)=\left\langle\nabla \varphi_{1}\left(a_{1}\right), z_{0}-x_{0}\right\rangle$ and $\varphi_{2}\left(z_{0}\right)-\varphi_{1}\left(y_{0}\right)=\left\langle\nabla \varphi_{2}\left(a_{2}\right), z_{0}-y_{0}\right\rangle$,
for some $a_{1} \in\left(x_{0}, z_{0}\right)$ and $a_{2} \in\left(z_{0}, y_{0}\right)$. Note that $z_{0}=\left(1-t_{0}\right) x_{0}+t_{0} y_{0}$ and $t_{0} \in(0,1)$. By (3.6),

$$
\begin{equation*}
\left\langle\nabla \varphi_{1}\left(a_{1}\right)-\nabla \varphi_{2}\left(a_{2}\right), y_{0}-x_{0}\right\rangle>0 \tag{3.7}
\end{equation*}
$$

Our next task is to show

$$
\begin{equation*}
\left\langle\nabla \varphi_{1}\left(z_{0}\right)-\nabla \varphi_{2}\left(z_{0}\right), y_{0}-x_{0}\right\rangle>0 \tag{3.8}
\end{equation*}
$$

Assume by contradiction that $\left\langle\nabla \varphi_{1}\left(z_{0}\right)-\nabla \varphi_{2}\left(z_{0}\right), y_{0}-x_{0}\right\rangle \leq 0$. Since $\varphi_{1}$ is convex on $\left[a_{1}, z_{0}\right]$,

$$
\left\langle\nabla \varphi_{1}\left(z_{0}\right)-\nabla \varphi_{1}\left(a_{1}\right), z_{0}-a_{1}\right\rangle \geq 0
$$

from which we get

$$
\left\langle\nabla \varphi_{1}\left(z_{0}\right)-\nabla \varphi_{1}\left(a_{1}\right), y_{0}-x_{0}\right\rangle \geq 0
$$

Similarly, $\left\langle\nabla \varphi_{2}\left(a_{2}\right)-\nabla \varphi_{2}\left(z_{0}\right), y_{0}-x_{0}\right\rangle \geq 0$. Hence

$$
\begin{aligned}
\left\langle\nabla \varphi_{1}\left(a_{1}\right)-\nabla \varphi_{2}\left(a_{2}\right), y_{0}-x_{0}\right\rangle & \leq\left\langle\nabla \varphi_{1}\left(z_{0}\right)-\nabla \varphi_{2}\left(z_{0}\right), y_{0}-x_{0}\right\rangle \\
& \leq 0
\end{aligned}
$$

This contradicts (3.7) and thus (3.8) is valid.
We claim that $\widehat{\partial} \varphi\left(z_{0}\right)=\emptyset$. Suppose that it is not true. Then there exists $x^{*} \in \mathbb{R}^{n}$ satisfying

$$
\begin{equation*}
\liminf _{u \rightarrow z_{0}} \frac{\varphi(u)-\varphi\left(z_{0}\right)-\left\langle x^{*}, u-x\right\rangle}{\left\|u-z_{0}\right\|} \geq 0 \tag{3.9}
\end{equation*}
$$

Let $u_{j}:=z_{0}-\frac{1}{j}\left(y_{0}-x_{0}\right)$. Then $u_{j} \rightarrow z_{0}$ as $j \rightarrow \infty$. It is easy to see that $u_{j} \in P_{1}$ for all $j \in \mathbb{N}$. Together with (3.9) this gives

$$
\liminf _{j \rightarrow \infty} \frac{\varphi_{1}\left(u_{j}\right)-\varphi_{1}\left(z_{0}\right)-\left\langle x^{*}, u_{j}-z_{0}\right\rangle}{\left\|u_{j}-z_{0}\right\|} \geq 0
$$

By the mean value theorem,

$$
\liminf _{j \rightarrow \infty} \frac{\left\langle\nabla \varphi_{1}\left(\xi_{j}\right),-\frac{1}{j}\left(y_{0}-x_{0}\right)\right\rangle-\left\langle x^{*},-\frac{1}{j}\left(y_{0}-x_{0}\right)\right\rangle}{\frac{1}{j}\left\|y_{0}-x_{0}\right\|} \geq 0
$$

where $\xi_{j} \in\left(u_{j}, z_{0}\right)$. Since $\nabla \varphi_{1}(\cdot)$ is continuous and $\xi_{j} \rightarrow z_{0}$ as $j \rightarrow \infty$, we have

$$
\left\langle\nabla \varphi_{1}\left(z_{0}\right), y_{0}-x_{0}\right\rangle \leq\left\langle x^{*}, y_{0}-x_{0}\right\rangle
$$

Similarly, by taking $u_{j}=z_{0}+\frac{1}{j}\left(y_{0}-x_{0}\right)$ we obtain

$$
\left\langle x^{*}, y_{0}-x_{0}\right\rangle \leq\left\langle\nabla \varphi_{2}\left(z_{0}\right), y_{0}-x_{0}\right\rangle
$$

Consequently, $\left\langle\nabla \varphi_{1}\left(z_{0}\right)-\nabla \varphi_{2}\left(z_{0}\right), y_{0}-x_{0}\right\rangle \leq 0$ which contradicts (3.8). Hence $\widehat{\partial} \varphi\left(z_{0}\right)=\emptyset$ and $\nabla \varphi_{1}\left(z_{0}\right) \neq \nabla \varphi_{2}\left(z_{0}\right)$ by (3.8). By virtual of (3.5), we can find a positive number $\gamma$ such that for each $u \in P_{12} \cap\left(z_{0}+\gamma \mathbb{B}\right)$ there exist $x_{u} \in \operatorname{int} P_{1}$, $y_{u} \in \operatorname{int} P_{2}$ satisfying $u=\left(1-t_{0}\right) x_{u}+t_{0} y_{u}$ and

$$
\varphi(u)>\left(1-t_{0}\right) \varphi\left(x_{u}\right)+t_{0} \varphi\left(y_{u}\right)
$$

where $\mathbb{B}:=\left\{x \in \mathbb{R}^{n} \mid\|x\|<1\right\}$. Then as in the proof of the claim $\widehat{\partial} \varphi\left(z_{0}\right)=\emptyset$, we can show that $\widehat{\partial} \varphi(u)=\emptyset$ and $\nabla \varphi_{1}(u) \neq \nabla \varphi_{2}(u)$ for all $u \in P_{12} \cap\left(z_{0}+\gamma \mathbb{B}\right)$. By the continuity of $\nabla \varphi_{1}(\cdot)$ and of $\nabla \varphi_{2}(\cdot)$, together with (3.3) this gives

$$
\begin{aligned}
& \partial \varphi(x)=\operatorname{Limsup}_{u \rightarrow x} \widehat{\partial} \varphi(u) \\
& =\stackrel{\operatorname{Limsup}}{u \rightarrow x} \widehat{\partial} \varphi(u) \cup \operatorname{Limsup} \widehat{\partial} \varphi(u) \cup \operatorname{Limsup} \widehat{\partial} \varphi(u) \\
& =\left\{\nabla \varphi_{1}(x), \nabla \varphi_{2}(x)\right\} \xrightarrow{\stackrel{i n}{u} \xrightarrow{u} \xrightarrow{\text { int } P_{2}} x} x \quad u \xrightarrow{P_{12}} x
\end{aligned}
$$

for all $x \in P_{12} \cap\left(z_{0}+\gamma \mathbb{B}\right)$. Hence

$$
\partial \varphi(x)= \begin{cases}\left\{\nabla \varphi_{1}(x)\right\} & \text { if } x \in \operatorname{int} P_{1},  \tag{3.10}\\ \left\{\nabla \varphi_{2}(x)\right\} & \text { if } x \in \operatorname{int} P_{2}, \\ \left\{\nabla \varphi_{1}(x), \nabla \varphi_{2}(x)\right\} & \text { if } x \in P_{12} \cap\left(z_{0}+\gamma \mathbb{B}\right) .\end{cases}
$$

For $x \in P_{12} \cap\left(z_{0}+\gamma \mathbb{B}\right), y=\nabla \varphi_{1}(x)$, and $u \in \mathbb{R}^{n}$, it holds

$$
\partial^{2} \varphi(x, y)(u)=\nabla^{2} \varphi_{1}(x)(u)+\mathbb{R}_{+} a
$$

Indeed, let $z=\nabla^{2} \varphi_{1}(x)(u)+\lambda a$ for some $\lambda \geq 0$. Since $\nabla \varphi_{1}(\cdot), \nabla \varphi_{2}(\cdot)$ are continuous and $y=\nabla \varphi_{1}(x) \neq \nabla \varphi_{2}(x)$, by (3.10) for all $\left(x^{\prime}, y^{\prime}\right) \in \operatorname{gph} \partial \varphi$ near
$(x, y)$ we have $x^{\prime} \in P_{1}$ and $y^{\prime}=\nabla \varphi_{1}\left(x^{\prime}\right)$. Hence

$$
\begin{aligned}
& \limsup _{\left(x^{\prime}, y^{\prime}\right) \xrightarrow{\operatorname{ghh} \partial \varphi}(x, y)} \frac{\left\langle z, x^{\prime}-x\right\rangle-\left\langle u, y^{\prime}-y\right\rangle}{\left\|x^{\prime}-x\right\|+\left\|y^{\prime}-y\right\|} \\
& =\underset{x^{\prime} \xrightarrow{P_{1}} x}{\lim \sup } \frac{\left\langle z, x^{\prime}-x\right\rangle-\left\langle u, \nabla \varphi_{1}\left(x^{\prime}\right)-\nabla \varphi_{1}(x)\right\rangle}{\left\|x^{\prime}-x\right\|+\left\|\nabla \varphi_{1}\left(x^{\prime}\right)-\nabla \varphi_{1}(x)\right\|} \\
& =\underset{x^{\prime} \rightarrow x}{\limsup } \frac{\left\langle z-\nabla^{2} \varphi_{1}\left(\xi_{x^{\prime}}\right)(u), x^{\prime}-x\right\rangle}{\left\|x^{\prime}-x\right\|+\left\|\nabla \varphi_{1}\left(x^{\prime}\right)-\nabla \varphi_{1}(x)\right\|} \\
& =\limsup _{x^{\prime} P_{1} x} \frac{\left\langle\nabla^{2} \varphi_{1}(x)(u)-\nabla^{2} \varphi_{1}\left(\xi_{x^{\prime}}\right)(u), x^{\prime}-x\right\rangle+\lambda\left\langle a, x^{\prime}-x\right\rangle}{\left\|x^{\prime}-x\right\|+\left\|\nabla \varphi_{1}\left(x^{\prime}\right)-\nabla \varphi_{1}(x)\right\|} \\
& \leq\|u\| \lim \sup \left\|\nabla^{2} \varphi_{1}(x)-\nabla^{2} \varphi_{1}\left(\xi_{x^{\prime}}\right)\right\|=0, \\
& x^{{ }^{P_{1}}} \xrightarrow{P_{x}}
\end{aligned}
$$

where $\xi_{x^{\prime}} \in\left(x^{\prime}, x\right)$. This implies that $z \in \partial^{2} \varphi(x, y)(u)$ and thus,

$$
\nabla^{2} \varphi_{1}(x)(u)+\mathbb{R}_{+} a \subset \partial^{2} \varphi(x, y)(u)
$$

To prove the reverse inclusion, take any $z \in \partial^{2} \varphi(x, y)(u)$. Then there exist $\left(z_{i}, u_{i}\right) \rightarrow$ $(z, u)$ and $\left(x_{i}, y_{i}\right) \rightarrow(x, y)$ with $\left(x_{i}, y_{i}\right) \in \operatorname{gph} \partial \varphi$ such that $\left(z_{i},-u_{i}\right) \in \widehat{N}$ $\left(\left(x_{i}, y_{i}\right) ; \operatorname{gph} \partial \varphi\right)$ for all $i$. Note that $\nabla \varphi_{1}(\cdot), \nabla \varphi_{2}(\cdot)$ are continuously differentiable functions satisfying $\nabla \varphi_{1}(x) \neq \nabla \varphi_{2}(x)$ for all $x \in P_{12} \cap\left(z_{0}+\gamma \mathbb{B}\right)$. By (3.10), we may assume that $x_{i} \in P_{1} \cap\left(z_{0}+\gamma \mathbb{B}\right), y_{i}=\nabla \varphi_{1}\left(x_{i}\right)$ for all $i$. Hence,

$$
\begin{aligned}
& \left(z_{i},-u_{i}\right) \in \widehat{N}\left(\left(x_{i}, y_{i}\right) ; \operatorname{gph} \partial \varphi\right) \\
\Leftrightarrow & \limsup _{x^{\prime} \xrightarrow{P_{1}} x_{i}} \frac{\left\langle z_{i}, x^{\prime}-x_{i}\right\rangle-\left\langle u_{i}, \nabla \varphi_{1}\left(x^{\prime}\right)-\nabla \varphi_{1}\left(x_{i}\right)\right\rangle}{\left\|x^{\prime}-x_{i}\right\|+\left\|\nabla \varphi_{1}\left(x^{\prime}\right)-\nabla \varphi_{1}\left(x_{i}\right)\right\|} \leq 0 \\
\Rightarrow & \limsup _{x^{\prime} \xrightarrow{P_{1}} x_{i}} \frac{\left\langle z_{i}-\nabla^{2} \varphi_{1}\left(\xi_{x^{\prime}}\right)\left(u_{i}\right), x^{\prime}-x_{i}\right\rangle}{\left(1+\sup _{\xi \in z_{0}+\gamma \mathbb{B}}\left\|\nabla^{2} \varphi_{1}(\xi)\right\|\right)\left\|x^{\prime}-x_{i}\right\|} \leq 0 \quad\left(\text { for some } \xi_{x^{\prime}} \in\left(x^{\prime}, x_{i}\right)\right) \\
\Rightarrow & \left\langle z_{i}-\nabla^{2} \varphi_{1}\left(x_{i}\right)\left(u_{i}\right), x^{\prime}\right\rangle \leq 0 \quad \text { whenever }\left\langle a, x^{\prime}\right\rangle \leq 0 .
\end{aligned}
$$

Taking $i \rightarrow \infty$, we have $\left\langle z-\nabla^{2} \varphi_{1}(x)(u), x^{\prime}\right\rangle \leq 0$ if $\left\langle a, x^{\prime}\right\rangle \leq 0$. By the Farkas lemma, there exists $\lambda \geq 0$ such that $z-\nabla^{2} \varphi_{1}(x)(u)=\lambda a$ which proves $\partial^{2} \varphi(x, y)(u) \subset \nabla^{2} \varphi_{1}(x)(u)+\mathbb{R}_{+} a$. Therefore, $\partial^{2} \varphi(x, y)(u)=\nabla^{2} \varphi_{1}(x)(u)+\mathbb{R}_{+} a$ for all $x \in P_{12} \cap\left(z_{0}+\gamma \mathbb{B}\right), y=\nabla \varphi_{1}(x)$ and $u \in \mathbb{R}^{n}$. Let $x \in P_{12} \cap\left(z_{0}+\gamma \mathbb{B}\right), y=$ $\nabla \varphi_{1}(x), z=-\nabla^{2} \varphi_{1}(x)(a)+t a(t \geq 0)$ and $u=-a$. We have $z \in \partial^{2} \varphi(x, y)(u)$ and $\langle z, u\rangle=\left\langle\nabla^{2} \varphi_{1}(x)(a), a\right\rangle-t\|a\|^{2}<0$ for $t \geq 0$ large enough. This contradicts (3.2).

Remark. As can be seen from the above proof, we also obtain the contradiction if it is only supposed that $\varphi$ is nonconvex on some ball $\bar{x}+\varepsilon \mathbb{B}\left(\bar{x} \in \mathbb{R}^{n}, \varepsilon>0\right)$ and (3.2) is replaced by the condition:
$\langle z, u\rangle \geq 0$ for all $u \in \mathbb{R}^{n}, z \in \partial^{2} \varphi(x, y)(u)$ with $(x, y) \in \operatorname{gph} \partial \varphi$ and $x \in \bar{x}+\varepsilon \mathbb{B}$.
This remark will be used in the sequel.
Case 2. $k>2$. Since $\varphi$ is nonconvex on $\mathbb{R}^{n}=\bigcup_{j=1}^{k} P_{j}$ but it is convex on each one of the polyhedrals $P_{j}(j=1,2, \ldots, k)$, there exist $x, y \in \mathbb{R}^{n}(x \neq y)$, $0=\tau_{0}<\tau_{1}<\ldots<\tau_{m-1}<\tau_{m}=1(m \in \mathbb{N}, m>1)$, and $x_{i}:=x+\tau_{i}(y-x)$ $(i=0,1, \ldots, m)$ such that $\varphi$ is convex on $\left[x_{i}, x_{i+1}\right](i=0,1, \ldots, m-1)$ but it is nonconvex on $[x, y]$. By Lemma 3.2 we can find $i \in\{0,1, \ldots, m-2\}$ such that $\varphi$ is nonconvex on $\left[x_{i}, x_{i+2}\right]$. Thus, without loss of generality we can assume that there exists $\bar{x} \in(x, y)$ such that $\varphi$ is convex on each one of intervals $[x, \bar{x}]$ and $[\bar{x}, y]$ but it is nonconvex on $[x, y]$. For each $u \in \mathbb{R}^{n}$, we put $I(u)=\{i \in\{1,2, \ldots, k\}$ : $\left.u \in P_{i}\right\}$. Let $\varepsilon>0$ such that $(\bar{x}+\varepsilon \mathbb{B}) \cap P_{i}=\emptyset$ for all $i \in\{1,2, \ldots, k\} \backslash I(\bar{x})$. We may assume that $x, y \in \mathbb{B}(\bar{x}, \varepsilon)$. Since $\varphi$ is convex on $[x, \bar{x}]$ and on $[\bar{x}, y]$ and it is nonconvex on $[x, y],|I(\bar{x})| \geq 2$ and $\bar{x} \notin \operatorname{int} P_{i}$ for all $i$. If $|I(\bar{x})|=2$, then we obtain a contradiction by using the above remark. If $|I(\bar{x})|>2$, then $\operatorname{dim} L<n-1$ where $L:=\operatorname{aff}\left(\bigcap_{i \in I(\bar{x})} P_{i}\right)$ denotes the affine hull of $\bigcap_{i \in I(\bar{x})} P_{i}$. Indeed, without loss of generality we may assume that $\{1,2,3\} \subset I(\bar{x})$. Since int $P_{i} \neq \emptyset, \operatorname{int} P_{j} \neq \emptyset$ and $\operatorname{int} P_{i} \cap \operatorname{int} P_{j}=\emptyset(\forall i \neq j)$, by the separation theorem, there exists a hyperplane $L_{i j}$ separating the sets $\operatorname{int} P_{i}$ and $\operatorname{int} P_{j}(1 \leq i<j \leq 3)$. Since it is impossible that $L_{12}=L_{13}=L_{23}, \operatorname{dim}\left(L_{12} \cap L_{13} \cap L_{23}\right)<n-1$. Noting that $L \subset\left(L_{12} \cap L_{13} \cap L_{23}\right)$, we have $\operatorname{dim} L<n-1$. In the case where $y \in L$, by invoking the last property we can find $\tilde{y} \in \mathbb{R}^{n} \backslash L$ as close to $y$ as desired. Let $t \in(0,1)$ be such that $\bar{x}=(1-t) x+t y$. Define $\tilde{x}_{\tilde{y}}$ by the condition $\bar{x}=(1-t) \tilde{x}_{\tilde{y}}+t \tilde{y}$. Clearly, $\tilde{x}_{\tilde{y}} \notin L$ and $\tilde{x}_{\tilde{y}} \rightarrow x$ as $\tilde{y} \rightarrow y$. Since $\varphi$ is continuous and nonconvex on $[x, y]$, there exists $\tilde{y} \in \mathbb{R}^{n} \backslash L$ as close to $y$ as desired such that $\varphi$ is nonconvex on $[\tilde{x} \tilde{y}, \tilde{y}]$. Thus, replacing $(x, y)$ by $\left(\tilde{x}_{\tilde{y}}, \tilde{y}\right)$ if necessary, we can assume that $y \notin L$ and $x \notin L$. (Note that such replacement may destroy the property of $\varphi$ of being convex on each one of the segments $[x, \bar{x}]$ and $[\bar{x}, y]$. But this property will not be employed in the sequel.) Take $\rho>0$ such that $(y+\rho \mathbb{B}) \subset(\bar{x}+\varepsilon \mathbb{B}),(y+\rho \mathbb{B}) \cap L=\emptyset, x \notin(y+\rho \mathbb{B})$, and $\varphi$ is nonconvex on $[x, z]$ for each $z \in(y+\rho \mathbb{B})$. Our aim now is to show that there exists $z \in(y+\rho \mathbb{B})$ such that $[x, z] \cap L=\emptyset$. Suppose that this is not true. Then $[x, z] \cap L \neq \emptyset$ for all $z \in(y+\rho \mathbb{B})$. Choose $y_{i} \in(y+\rho \mathbb{B})(i=1,2, \ldots, n-1)$ such that $\left\{x-y, y_{1}-y, \ldots, y_{n-1}-y\right\}$ is linearly independent. For each $i \in\{1,2, \ldots, n-1\}$, we can take a vector $\bar{x}_{i} \in\left[x, y_{i}\right] \cap L$ because $[x, z] \cap L \neq \emptyset$ for all $z \in(y+\rho \mathbb{B})$ and $y_{i} \in(y+\rho \mathbb{B})(i=1,2, \ldots, n-1)$. Note that $\bar{x}_{i}-\bar{x}=\alpha_{i}(x-y)+\beta_{i}\left(y_{i}-y\right)$ for
some $\alpha_{i} \in \mathbb{R}, \beta_{i} \in \mathbb{R} \backslash\{0\}$ and $\left\{x-y, y_{1}-y, \ldots, y_{n-1}-y\right\}$ is linearly independent. Hence the system $\left\{\bar{x}_{1}-\bar{x}, \ldots, \bar{x}_{n-1}-\bar{x}\right\}$ is linearly independent from which we get $\operatorname{dim} L \geq n-1$. This contradicts the fact $\operatorname{dim} L<n-1$ derived above and thus there exists $z \in(y+\rho \mathbb{B})$ satisfying $[x, z] \cap L=\emptyset$. Since $\varphi$ is nonconvex on $[x, z]$, we can find $\left[x^{\prime}, y^{\prime}\right] \subset[x, z]$ and $\bar{x}^{\prime} \in\left(x^{\prime}, y^{\prime}\right)$ such that $\varphi$ is convex on each of the two intervals $\left[x^{\prime}, \bar{x}^{\prime}\right]$ and $\left[\bar{x}^{\prime}, y^{\prime}\right]$ and it is nonconvex on $\left[x^{\prime}, y^{\prime}\right]$. Observing that $\bar{x}^{\prime} \in(\bar{x}+\varepsilon \mathbb{B}) \backslash\left[\bigcap_{i \in I(\bar{x})} P_{i}\right]$ and $(\bar{x}+\varepsilon \mathbb{B}) \cap P_{i}=\emptyset$ for all $i \in\{1,2, \ldots, k\} \backslash I(\bar{x})$, we have $\left|I\left(\bar{x}^{\prime}\right)\right|<|I(\bar{x})|$. Hence if $|I(\bar{x})|>2$, then there exist $\left[x^{\prime}, y^{\prime}\right]$ and $\bar{x}^{\prime} \in\left(x^{\prime}, y^{\prime}\right)$ such that $\varphi$ is convex on each of the segments $\left[x^{\prime}, \bar{x}^{\prime}\right]$ and $\left[\bar{x}^{\prime}, y^{\prime}\right]$ but it is nonconvex on $\left[x^{\prime}, y^{\prime}\right]$ and $\left|I\left(\bar{x}^{\prime}\right)\right|<|I(\bar{x})|$. Thus, by repeating this procedure after finitely many times, we can reduce the case where $|I(\bar{x})|=2$ and obtain a contradiction. The proof is now completed.

Recall that a function $\varphi: \mathbb{R}^{n} \rightarrow \mathbb{R} \cup\{+\infty\}$ is said to be strongly convex on a convex subset $\Omega \subset \operatorname{dom} \varphi$ if there exists a constant $\rho>0$ such that

$$
\varphi((1-t) x+t y) \leq(1-t) \varphi(x)+t \varphi(y)-\rho t(1-t)\|x-y\|^{2}
$$

for any $x, y \in \Omega$ and $t \in(0,1)$. It is well known (see e.g. [12, Lemma 1, p. 184]) that the above condition is fulfilled if and only if the function $\widetilde{\varphi}(x):=\varphi(x)-\rho\|x\|^{2}$ is convex on $\Omega$.

We now have the following characterization of strong convexity for piecewise $C^{2}$ functions.

Theorem 3.4. Suppose that $\varphi: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is a piecewise $C^{2}$ function. Then $\varphi$ is strongly convex on $\mathbb{R}^{n}$ with the constant $\rho>0$ if and only if for any $(x, y) \in$ $\operatorname{gph} \partial \varphi$ the second-order subdifferential mapping $\partial^{2} \varphi(x, y): \mathbb{R}^{n} \rightrightarrows \mathbb{R}^{n}$ satisfies the condition

$$
\begin{equation*}
\langle z, u\rangle \geq 2 \rho\|u\|^{2} \text { for all } u \in \mathbb{R}^{n} \text { and } z \in \partial^{2} \varphi(x, y)(u) \text { with }(x, y) \in \operatorname{gph} \partial \varphi . \tag{3.11}
\end{equation*}
$$

Proof. It is well-known that $\varphi$ is strongly convex on $\mathbb{R}^{n}$ with the constant $\rho>0$ if and only if the function $\widetilde{\varphi}:=\varphi+\psi$ where $\psi(x)=-\rho\|x\|^{2}$ is convex. By [7, Proposition 1.107(ii)],

$$
\begin{equation*}
\partial \widetilde{\varphi}(x)=\partial \varphi(x)-2 \rho x \quad \forall x \in \mathbb{R}^{n} \tag{3.12}
\end{equation*}
$$

Now, applying the coderivative sum rule with equality [7, Proposition 1.62(ii)] to the case where $F(x)=\partial \varphi(x)$ and $f(x)=-2 \rho x$, we have

$$
D^{*}(F+f)(x, y)(u)=D^{*} F(x, y-f(x))(u)-2 \rho u
$$

for any $x \in \mathbb{R}^{n}, y \in \mathbb{R}^{n}$ with $y-f(x) \in F(x)$ and for any $u \in \mathbb{R}^{n}$. Together with (3.12) this gives

$$
\begin{equation*}
\partial^{2} \widetilde{\varphi}(x, y)(u)=\partial \varphi^{2}(x, y)(u)-2 \rho u \quad \forall x \in \mathbb{R}^{n}, \forall y \in \partial \varphi(x) \tag{3.13}
\end{equation*}
$$

According to Theorem 3.3, the convexity of $\widetilde{\varphi}$ is equivalent to the PSD of the secondorder subdifferential mapping $\partial^{2} \widetilde{\varphi}(\cdot)$. Hence, by (3.13) we obtain $\langle v-2 \rho u, u\rangle \geq 0$ for any $v \in \partial \varphi^{2}(x, y)(u)$ which yields (3.11).

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