Research Article An SIR Epidemic Model with Time Delay and General

Nonlinear Incidence Rate

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An SIR epidemic model with nonlinear incidence rate and time delay is investigated. The disease transmission function and the rate that infected individuals recovered from the infected compartment are assumed to be governed by general functions F(S, I) and G(I), respectively. By constructing Lyapunov functionals and using the Lyapunov-LaSalle invariance principle, the global asymptotic stability of the disease-free equilibrium and the endemic equilibrium is obtained. It is shown that the global properties of the system depend on both the properties of these general functions and the basic reproductive number R_0 .

1. Introduction

The mechanism of transmission is usually qualitatively known for most diseases from epidemiological point of view. For modeling the spread process of infectious diseases mathematically and quantitatively, many classical epidemic models have been proposed and studied, such as SIR, SIS, SEIR, and SIRS models. Recently, considerable attention have been paid to study the dynamics of epidemic models with epidemiological meaningful time delays.

The fundamental assumption in epidemic models is that the population can be divided into distinct groups. The most common groups are the susceptible (S) which contains individuals that may be infected by the disease; the infected (I) which contains individuals that are already infected and can spread the disease to susceptible individuals; the removed (R) which contains individuals that have the immunity and cannot be infected. Therefore such models are referred to SIR models. The simplest forms of these models are ordinary differential equations (ODEs).

It is well known that the disease transmission progress plays an important role in the epidemic dynamics; that is, applying different incidence rates can potentially change the behaviors of the system. In many epidemic models, following incidence functions with delay or without delay are widely used in different epidemiological backgrounds.

- The bilinear incidence rate βSI (e.g., [1–8]), where β is the average number of contacts per infected individual per day.
- (2) The standard incidence rate $\beta SI/N$ ([9–12]), where N = S + I + R.
- (3) The Holling type incidence rate of the form $\beta SI/(1 + \alpha_1 S)$ ([13–15]), where α_1 is a positive constant.
- (4) The saturated incidence rate of the form $\beta SI/(1 + \alpha_2 I)$ ([16–21]), where α_2 is a positive constant.
- (5) The saturated incidence rate of the form $\beta SI/(1+\alpha_1S+\alpha_2I)$ ([22–25]), where α_1, α_2 is a positive constant.

The bilinear incidence rate in (1) is based on the law of mass action, which is more appropriate for communicable diseases, such as influenza, but not suitable for sexually transmitted diseases. It has been pointed out that standard incidence rate in (2) may be a good approximation when the number of available partners is large enough and everybody could not make more contacts than that is practically feasible. In fact, the infection probability per contact is likely influenced by the number of infective individuals, because more infective individuals can increase the infection risk.

In the incidence rates in (3) and (4), βSI measures the infection force of the disease and $1/(1 + \alpha_1 S)$, $1/(1 + \alpha_2 I)$ measure the inhibition effect from the behavioral changes of

the susceptible individuals when their number increases or from the crowding effect of the infective individuals. In these incidence rates, the number of effective contacts between infectived and susceptible individuals may saturate at high infective levels. These incidence rates seem more reasonable than the bilinear incidence rate βSI , because they include the behavioral changes of susceptible individuals and crowding effect of the infective individuals which prevent the unboundedness of the contact rate by choosing suitable parameters.

Obviously, the incidence rate in (5) includes the former three incidence rates: the bilinear incidence rate βSI (when $\alpha_1 = 0, \alpha_2 = 0$), the Holling type incidence rate $\beta SI/(1 + \alpha_1 S)$ (when $\alpha_2 = 0$), and the saturated incidence rate $\beta SI/(1 + \alpha_2 I)$ (when $\alpha_1 = 0$).

The incidence rate can also be modeled by many other kinds of more general functions. It is interesting that whether the functional form of the incidence rate can change the epidemic dynamics or not. Korobeinikov studied the global properties for epidemiological models with various nonlinear incidence rates, such as f(s)g(i) in [26], f(s,i) in [27–29]. By constructing Lyapunov functions, [27, 28] established the global stability for ordinary differential equations models of epidemiological dynamics with nonlinear incidence rate f(s, i) under some conditions.

These models have not included time delays, which are usually used to model the fact that an individual may not be infectious until some time after becoming infected. In the context of epidemiology, delays can be caused by a variety of factors. The most common reasons for a delay are (i) the latency of the infection in a vector and (ii) the latency of the infection in an infected host [30]. In these cases, some time should elapse before the level of infection in the infected host or the vector reaching a sufficiently high level to transmit the infection further.

Motivated by all the above, we present a model described by delay differential equations (DDEs) with two general nonlinear terms as follows:

$$\frac{dS(t)}{dt} = \lambda - \mu S(t) - F(S(t), I(t)),$$

$$\frac{dI(t)}{dt} = e^{-\mu\tau} F(S(t-\tau), I(t-\tau)) - (\mu + \alpha) I(t) - G(I(t)),$$

$$\frac{dR(t)}{dt} = G(I(t)) - \mu R(t),$$
(1)

where S(t), I(t), and R(t), as mentioned above, represent the population of the susceptible, the infected, and the removed at time t, respectively. The parameters in the equations are explained as below. The positive λ is the recruitment rate of the population, μ is the natural death rate of the population, α is the death rate due to disease, all $\tau \ge 0$ is the latent period. The term $0 \le e^{-\mu\tau} < 1$ represents the survival rate of population and the time they take to become infectious is τ . We assume that the force of infection at any time t is given by the general function F(S(t), I(t)), and the recovered infected individuals at any time t is given by the function G(I(t)). Since R(t) does not appear in equations for dS(t)/dt and dI(t)/dt, it is sufficient to analyze the behaviors of solutions of (1) by the following system of DDEs:

$$\frac{dS(t)}{dt} = \lambda - \mu S(t) - F(S(t), I(t)),$$

$$\frac{dI(t)}{dt} = e^{-\mu\tau} F(S(t-\tau), I(t-\tau)) - (\mu + \alpha) I(t) - G(I(t)).$$
(2)

The initial conditions for system (2) take the form

$$S(\theta) = \phi_1(\theta), \qquad I(\theta) = \phi_2(\theta),$$

$$\phi_1(\theta) \ge 0, \quad \phi_2(\theta) \ge 0, \quad \theta \in [-\tau, 0], \qquad (3)$$

$$\phi_1(0) > 0, \quad \phi_2(0) > 0,$$

where $\phi = (\phi_1(\theta), \phi_2(\theta)) \in C^+ \times C^+$. Here *C* denotes the Banach space $C = C([-\tau, 0], \mathbb{R})$ of continuous functions mapping the interval $[-\tau, 0]$ into \mathbb{R} , equipped with the supremum norm. The nonnegative cone of *C* is defined as $C^+ = C([-\tau, 0], \mathbb{R}^+)$.

The organization of this paper is as follows. In Section 2, we study the existence of a positive equilibrium. In Section 3, we show that the global asymptotic stability of the disease-free equilibrium and the endemic equilibrium of model (2) depend only on the basic reproductive number under some hypotheses. A brief discussion is given in the last section to conclude this paper.

2. The Existence of Positive Equilibrium

In this section, we prove the existence of a positive equilibrium. We assume that F(S, I) and G(I) are always positive, continuously differentiable, and monotonically increasing for all S > 0 and I > 0. That is, they satisfy the following conditions:

- (H1) $F(S, I) > 0, F'_S(S, I) > 0, F'_I(S, I) > 0$ for S > 0 and I > 0.
- (H2) F(S,0) = F(0,I) = 0, $F'_S(S,0) = 0$, $F'_I(S,0) > 0$ for S > 0 and I > 0.
- (H3) G(0) = 0. G'(I) > 0 for $I \ge 0$.

Global behaviors of system (2) may depend on the basic reproduction number R_0 , which is the average number of secondary cases produced by a single infective individual introduced into an entirely susceptible population. The basic reproductive number for system (2) can be computed as

$$R_0 = \frac{e^{-\mu\tau} F_I'(S_0, 0)}{\mu + \alpha + G'(0)},\tag{4}$$

where $S_0 = \lambda/\mu$. Usually, $R_0 < 1$ implies that the number of infected individuals will tend to zero and $R_0 > 1$ implies that the number will increase.

The epidemiologically natural condition F(S, 0) = 0ensures that system (2) always has a disease-free equilibrium $E_0 = (S_0, 0)$. And it may also admit an endemic equilibrium $E^* = (S^*, I^*)$ which depends on R_0 . And S^* , I^* satisfy the following equations:

$$\lambda - \mu S^* = F(S^*, I^*),$$

$$F(S^*, I^*) = e^{\mu \tau} [(\mu + \alpha) I^* + G(I^*)].$$
(5)

We will show that under certain epidemiologically reasonable conditions, the existence of the positive equilibrium state E^* is ensured. We have the following theorem.

Theorem 1. Assume that F(S, I) satisfies (H1) and (H2), and G(I) satisfies (H3). Then system (2) has a positive equilibrium state $E^* = (S^*, I^*)$ if $R_0 > 1$.

Proof. Let the right-hand sides of the three equations in system (2) equal zero; we have that

$$\lambda - \mu S = F(S, I) = e^{\mu \tau} \left[\left(\mu + \alpha \right) I + G(I) \right].$$
(6)

Substituting the expression of *S* by *I*, we obtain the following equation for *I*:

$$H(I) = F\left(\frac{\lambda - e^{\mu\tau}\left[\left(\mu + \alpha\right)I + G(I)\right]}{\mu}, I\right)$$

$$- e^{\mu\tau}\left[\left(\mu + \alpha\right)I + G(I)\right].$$
(7)

It is obvious that H(0) = 0, and we can compute that there exists a positive I_0 such that $\lambda = e^{\mu \tau} [(\mu + \alpha)I_0 + G(I_0)]$. Hence

$$H(I_0) = F(0, I_0) - \lambda = -\lambda < 0.$$
(8)

And when $I \ge 0$, since H(I) is continuously differentiable, we have

$$H'(0) = \lim_{I \to 0^{+}} \frac{H(I) - H(0)}{I - 0}$$

= $F'_{I}(S_{0}, 0) - e^{\mu \tau} \left[\mu + \alpha + G'(0)\right] F'_{S}(S_{0}, 0)$
 $- e^{\mu \tau} \left[\mu + \alpha + G'(0)\right]$ (9)
= $F'_{I}(S_{0}, 0) - e^{\mu \tau} \left[\mu + \alpha + G'(0)\right]$
= $e^{\mu \tau} \left[\mu + \alpha + G'(0)\right] (R_{0} - 1).$

Thus, $R_0 > 1$ ensures that H'(0) > 0. And H(I) is continuous on $[0, I_0]$; then there exists some $I^* \in (0, I_0)$ such that $H(I^*) = 0$. Since G(I) is strictly monotonically increasing, we have $e^{\mu\tau}[(\mu+\alpha)I^*+G(I^*)] < e^{\mu\tau}[(\mu+\alpha)I_0+G(I_0)]$. Therefore $S^* = (\lambda - e^{\mu\tau}[(\mu+\alpha)I^*+G(I^*)])/\mu > 0$, and we have proved the existence of the endemic equilibrium $E^* = (S^*, I^*)$ for system (2) under condition $R_0 > 1$. This completes the proof.

3. Global Dynamics of the Model

In this section, we will analyze the global dynamics of system (2) and show the global asymptotic stability of the disease-free equilibrium and the endemic equilibrium.

3.1. Stability of the Disease-Free Equilibrium. In this subsection, we will study the global stability of the disease-free equilibrium $E_0 = (S_0, 0)$ of system (2). We propose the following conditions:

- (H4) $F'_{I}(S, 0)$ is increasing with respect to S > 0.
- (H5) $F(S, I) \leq I \cdot (\partial F(S, 0) / \partial I)$ with respect to I > 0.

(H6) $G'(0) \leq G(I)/I$ with respect to I > 0.

By (H4), the following inequalities hold true:

$$\frac{F_{I}'(S_{0},0)}{F_{I}'(S,0)} > 1 \quad \text{for } S \in (0, S_{0}),$$

$$\frac{F_{I}'(S_{0},0)}{F_{I}'(S,0)} < 1 \quad \text{for } S > S_{0}.$$
(10)

Under these conditions, we have the following theorems.

Theorem 2. Suppose that conditions (H1)–(H3) are satisfied. Then the disease-free equilibrium $E_0 = (S_0, 0)$ of system (2) is locally asymptotically stable for any $\tau > 0$ if $R_0 < 1$; $E_0 = (S_0, 0)$ is unstable if $R_0 > 1$.

Proof. The characteristic equation of system (2) at $E_0 = (S_0, 0)$ is

$$(\lambda + u) \left(\lambda - e^{-\tau(\lambda + \mu)} F_I'(S_0, 0) + \mu + \alpha + G'(0)\right) = 0.$$
(11)

It has a negative real root $\lambda_1 = -\mu$. Moreover, it has a root of

$$\lambda - e^{-\tau(\lambda+\mu)} F_I'(S_0, 0) + \mu + \alpha + G'(0) = 0.$$
(12)

In (12), if $\tau = 0$, $R_0 < 1$ becomes $R_{01} = F'_I(S_0, 0)/[\mu + \alpha + G'(0)] < 1$; one can see that $\lambda_2 = [\mu + \alpha + G'(0)](R_{01} - 1) < 0$. Hence the $E_0 = (S_0, 0)$ is locally asymptotically stable. In (12), if $\tau > 0$, x > 0, $y \neq 0$, $\lambda = x + i \cdot y$ is a root of (12), then we have

$$x + \mu + \alpha + G'(0) = e^{-\tau(x+\mu)} F'_I(S_0, 0) \cos(y\tau),$$

$$y = -e^{-\tau(x+\mu)} F'_I(S_0, 0) \sin(y\tau).$$
(13)

Further we have

$$\left[x + \mu + \alpha + G'(0) \right]^2 + y^2 = \left[e^{-\tau(x+\mu)} F'_I(S_0, 0) \right]^2$$

$$\leq \left[e^{-\mu\tau} F'_I(S_0, 0) \right]^2,$$
(14)

which is a contradiction. Hence the $E_0 = (S_0, 0)$ is locally asymptotically stable.

If $R_0 > 1$, let $h(\lambda) = \lambda - e^{-\tau(\lambda+\mu)} F'_I(S_0, 0) + \mu + \alpha + G'(0)$; then we have

$$h(0) = \left[\mu + \alpha + G'(0)\right] (1 - R_0) < 0,$$

$$\lim_{\lambda \to +\infty} h(\lambda) = +\infty.$$
 (15)

And when $\lambda \ge 0$, since $h(\lambda)$ is continuously, then $h(\lambda) = 0$ has at least one positive root. Hence $E_0 = (S_0, 0)$ is unstable. This completes the proof.

Theorem 3. Suppose that conditions (H1)–(H6) are satisfied. Then the disease-free equilibrium $E_0 = (S_0, 0)$ of system (2) is globally asymptotically stable for any $\tau > 0$ if $R_0 \le 1$.

Proof. Define a Lyapunov functional

$$V_{1}(t) = U_{1}(t) + U_{2}(t), \qquad (16)$$

where

$$U_{1}(t) = S(t) - S_{0} - \int_{S_{0}}^{S(t)} \lim_{I \to 0^{+}} \frac{F(S_{0}, I(t))}{F(\theta, I(t))} d\theta + e^{\mu \tau} I(t),$$
$$U_{2}(t) = \int_{0}^{\tau} F(S(t - \eta), I(t - \eta)) d\eta.$$
(17)

By (H1)–(H6), it is obvious that V_1 is defined and continuously differentiable for all S(t), I(t) > 0, and $V_1 = 0$ at $E_0 = (S_0, 0)$. The system (2) at $E_0 = (S_0, 0)$ has $\lambda = \mu S_0$. The time derivative of U_1 along the solutions of system (2) is given by

$$\frac{dU_{1}(t)}{dt} = S'(t) - \lim_{I \to 0^{+}} \frac{F(S_{0}, I(t))}{F(S(t), I(t))} \cdot S'(t) + e^{\mu\tau}I'(t) \\
= \left(1 - \lim_{I \to 0^{+}} \frac{F(S_{0}, I(t))}{F(S(t), I(t))}\right) \left[\lambda - \mu S(t) - F(S(t), I(t))\right] \\
+ F(S(t - \tau), I(t - \tau)) - e^{\mu\tau}\left[(\mu + \alpha)I(t) + G(I(t))\right] \\
= \mu S(t) \left(\frac{S_{0}}{S(t)} - 1\right) \left(1 - \lim_{I \to 0^{+}} \frac{F(S_{0}, I(t))}{F(S(t), I(t))}\right) \\
- F(S(t), I(t)) + F(S(t), I(t)) \cdot \lim_{I \to 0^{+}} \frac{F(S_{0}, I(t))}{F(S(t), I(t))} \\
+ F(S(t - \tau), I(t - \tau)) - e^{\mu\tau}\left[(\mu + \alpha)I(t) + G(I(t))\right]. \tag{18}$$

Further, we have

$$\frac{dU_{2}(t)}{dt} = \frac{d}{dt} \int_{0}^{\tau} F(S(t-\eta), I(t-\eta)) d\eta$$

$$= F(S(t), I(t)) - F(S(t-\tau), I(t-\tau)).$$
(19)

Thus

$$\frac{dV_{1}(t)}{dt} = \frac{dU_{1}(t)}{dt} + \frac{dU_{2}(t)}{dt}
= \mu S(t) \left(\frac{S_{0}}{S(t)} - 1\right) \left(1 - \lim_{I \to 0^{+}} \frac{F(S_{0}, I(t))}{F(S(t), I(t))}\right)
+ F(S(t), I(t)) \cdot \lim_{I \to 0^{+}} \frac{F(S_{0}, I(t))}{F(S(t), I(t))}
- e^{\mu \tau} \left[(\mu + \alpha) I(t) + G(I(t))\right].$$
(20)

By (10), we have

$$\left(\frac{S_{0}}{S(t)} - 1\right) \left(1 - \lim_{I \to 0^{+}} \frac{F(S_{0}, I(t))}{F(S(t), I(t))}\right)$$

$$= \left(\frac{S_{0}}{S(t)} - 1\right) \left(1 - \frac{F_{I}'(S_{0}, 0)}{F_{I}'(S(t), 0)}\right) \le 0.$$
(21)

Note that $F'_{I}(S_{0}, 0)/F'_{I}(S, 0) \neq 1$, for $S \neq S_{0}$, S > 0, and by $F'_{I}(S, 0) > 0$ and (H4), the equality in (21) holds if and only if $S = S_{0}$. Furthermore, (H5) and (H6) imply that

$$F(S(t), I(t)) \cdot \lim_{I \to 0^{+}} \frac{F(S_{0}, I(t))}{F(S(t), I(t))} - e^{\mu \tau} [(\mu + \alpha) I(t) + G(I(t))] = F(S(t), I(t)) \cdot \frac{F'_{I}(S_{0}, 0)}{F'_{I}(S(t), 0)} - e^{\mu \tau} [(\mu + \alpha) I(t) + G(I(t))] \leq I(t) \cdot [F'_{I}(S_{0}, 0) - e^{\mu \tau} (\mu + \alpha + G'(0))] = e^{\mu \tau} (\mu + \alpha + G'(0)) I(t) (R_{0} - 1).$$
(22)

Therefore, $R_0 \leq 1$ ensures that $dV_1/dt \leq 0$ for all $S(t) \geq 0$, $I(t) \geq 0$, where $dV_1/dt = 0$ holds only for $S = S_0$. It is easy to verify that the disease-free equilibrium E_0 is the only fixed point of the systems on the plane $S = S_0$ and hence it is easy to show that the largest invariant set in $\{(S(t), I(t)) \mid dV_1/dt = 0\}$ is the singleton $\{E_0\}$. By the Lyapunov-LaSalle asymptotic stability theorem in [31], E_0 is globally asymptotically stable for any $\tau > 0$. This completes the proof.

3.2. Global Stability of the Endemic Equilibrium. In this subsection, we will study the global stability of the endemic equilibrium $E^* = (S^*, I^*)$ of system (2) by the Lyapunov direct method. We propose the following hypotheses:

- (H7) $I/I^* \leq F(S, I)/F(S, I^*)$ for $I \in (0, I^*), F(S, I)/F(S, I^*) \leq I/I^*$ for $I \geq I^*$.
- (H8) $G(I)/G(I^*) \le I/I^*$ for $I \in (0, I^*), I/I^* \le G(I)/G(I^*)$ for $I \ge I^*$.

Based on these, we have the following theorem.

Theorem 4. Suppose that conditions (H1)–(H3) and (H7)–(H8) are satisfied. Then the endemic equilibrium $E^* = (S^*, I^*)$ of system (2) is globally asymptotically stable for any $\tau > 0$ if $R_0 > 1$.

Proof. Define a Lyapunov functional

$$V_{2}(t) = W_{1}(t) + W_{2}(t), \qquad (23)$$

where

$$W_{1}(t) = S(t) - S^{*} - \int_{S^{*}}^{S(t)} \frac{F(S^{*}, I^{*})}{F(\varphi, I^{*})} d\varphi + e^{\mu \tau} \left(I(t) - I^{*} - I^{*} \ln \frac{I(t)}{I^{*}} \right).$$

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$$W_{2}(t) = F(S^{*}, I^{*}) \int_{0}^{\tau} \left(\frac{F(S(t-\xi), I(t-\xi))}{F(S^{*}, I^{*})} - 1 - \ln \frac{F(S(t-\xi), I(t-\xi))}{F(S^{*}, I^{*})} \right) d\xi.$$
(24)

By (H1)–(H6), $V_2(t) = W_1(t) + W_2(t)$ is defined and continuously differentiable for all S(t), I(t) > 0. And $V_2(0) = 0$ at $E^* = (S^*, I^*)$. At $E^* = (S^*, I^*)$, system (2) has

$$\lambda - \mu S^* = F(S^*, I^*),$$

$$F(S^*, I^*) = e^{\mu \tau} [(\mu + \alpha) I^* + G(I^*)].$$
(25)

The time derivative of W_1 along the solutions of system (2) is given by

$$\frac{dW_{1}(t)}{dt} = S'(t) - \frac{F(S^{*}, I^{*})}{F(S(t), I^{*})}S'(t) + e^{\mu\tau}I'(t)\left(1 - \frac{I^{*}}{I(t)}\right) \\
= \left(1 - \frac{F(S^{*}, I^{*})}{F(S(t), I^{*})}\right)\left[\mu S^{*} - \mu S(t) + F(S^{*}, I^{*}) - F(S(t), I(t))\right] \\
+ \left(1 - \frac{I^{*}}{I(t)}\right)\left[F(S(t - \tau), I(t - \tau)) - F(S^{*}, I^{*})\frac{I(t)}{I^{*}} + e^{\mu\tau}G(I^{*})\frac{I(t)}{I^{*}} - e^{\mu\tau}G(I(t))\right] \\
= \mu S^{*}\left(1 - \frac{F(S^{*}, I^{*})}{F(S(t), I^{*})}\right)\left(1 - \frac{S(t)}{S^{*}}\right) \\
+ F(S^{*}, I^{*})\left(1 - \frac{F(S^{*}, I^{*})}{I(t)} + \frac{F(S(t), I(t))}{F(S(t), I^{*})}\right) \\
+ F(S^{*}, I^{*})\left(1 - \frac{I(t)}{I^{*}} - \frac{I^{*}}{I(t)} \cdot \frac{F(S(t - \tau), I(t - \tau))}{F(S^{*}, I^{*})}\right) \\
+ e^{\mu\tau}G(I^{*})\left[\frac{I(t)}{I^{*}} - 1 - \frac{G(I(t))}{G(I^{*})} + \frac{G(I(t))}{G(I^{*})} \cdot \frac{I^{*}}{I(t)}\right] \\
- F(S(t), I(t)) + F(S(t - \tau), I(t - \tau)).$$
(26)

Further, we have

$$\begin{aligned} \frac{dW_2(t)}{dt} \\ &= F\left(S^*, I^*\right) \cdot \frac{d}{dt} \int_0^\tau \left(\frac{F\left(S\left(t-\xi\right), I\left(t-\xi\right)\right)}{F\left(S^*, I^*\right)} - 1 \right. \\ &\left. -\ln\frac{F\left(S\left(t-\xi\right), I\left(t-\xi\right)\right)}{F\left(S^*, I^*\right)}\right) d\xi \end{aligned}$$

$$= F(S(t), I(t)) - F(S(t - \tau), I(t - \tau)) + F(S^*, I^*) \ln \frac{F(S(t - \tau), I(t - \tau))}{F(S(t), I(t))}.$$
(27)

Then we have

$$\begin{split} \frac{dV_2(t)}{dt} &= \frac{dW_1(t)}{dt} + \frac{dW_2(t)}{dt} \\ &= \mu S^* \left(1 - \frac{F(S^*, I^*)}{F(S(t), I^*)} \right) \left(1 - \frac{S(t)}{S^*} \right) \\ &+ F(S^*, I^*) \left(1 - \frac{F(S^*, I^*)}{F(S(t), I^*)} + \frac{F(S(t), I(t))}{F(S(t), I^*)} \right) \\ &+ F(S^*, I^*) \left(1 - \frac{I(t)}{I^*} - \frac{I^*}{I(t)} \right) \\ &+ F(S^*, I^*) \left(1 - \frac{I(t)}{I^*} - \frac{I^*}{I(t)} \right) \\ &+ \frac{F(S(t-\tau), I(t-\tau))}{F(S(t), I(t))} \right) \\ &+ e^{\mu T} G(I^*) \left[\frac{I(t)}{I^*} - 1 - \frac{G(I(t))}{G(I^*)} \right) \\ &+ \frac{G(I(t))}{G(I^*)} \cdot \frac{I^*}{I(t)} \right] \\ &= \mu S^* \left(1 - \frac{F(S^*, I^*)}{F(S(t), I^*)} \right) \left(1 - \frac{S(t)}{S^*} \right) \\ &+ F(S^*, I^*) \left(1 - \frac{F(S^*, I^*)}{F(S(t), I^*)} + \ln \frac{F(S^*, I^*)}{F(S(t), I^*)} \right) \\ &+ F(S^*, I^*) \left(1 - \frac{I^*}{I(t)} \cdot \frac{F(S(t-\tau), I(t-\tau))}{F(S^*, I^*)} \right) \\ &+ F(S^*, I^*) \left(1 - \frac{I(t)}{I^*} \cdot \frac{F(S(t), I^*)}{F(S(t), I(t))} \right) \\ &+ F(S^*, I^*) \left(1 - \frac{I(t)}{I^*} \cdot \frac{F(S(t), I^*)}{F(S(t), I(t))} \right) \\ &+ F(S^*, I^*) \left(1 - \frac{I(t)}{I^*} - \frac{F(S(t), I^*)}{F(S(t), I(t))} \right) \\ &+ F(S^*, I^*) \left(\frac{I(t)}{I^*} - \frac{F(S(t), I^*)}{F(S(t), I^*)} \right) \\ &\times \left(\frac{F(S(t), I^*)}{F(S(t), I(t))} - 1 \right) \\ &\times \left(\frac{F(S(t), I^*)}{F(S(t), I(t))} - 1 \right) \\ &+ e^{\mu T} G(I^*) \left(\frac{G(I(t))}{G(I^*)} - \frac{I(t)}{I^*} \right) \left(\frac{I^*}{I(t)} - 1 \right). \end{split}$$

The function F(S, I) is monotonically increasing for any S > 0; hence the following inequality holds:

$$\left(1 - \frac{F(S^*, I^*)}{F(S(t), I^*)}\right) \left(1 - \frac{S(t)}{S^*}\right) \le 0.$$
(29)

And by the properties of the function $g(x) = 1 - x + \ln x$, (x > 0), we note that g(x) has its global maximum g(1) = 0. Hence $g(x) \le 0$ when x > 0 and the following inequalities hold true:

$$1 - \frac{F(S^*, I^*)}{F(S(t), I^*)} + \ln \frac{F(S^*, I^*)}{F(S(t), I^*)} \le 0,$$

$$1 - \frac{I^*}{I(t)} \cdot \frac{F(S(t - \tau), I(t - \tau))}{F(S^*, I^*)}$$

$$+ \ln \frac{I^*}{I(t)} \cdot \frac{F(S(t - \tau), I(t - \tau))}{F(S^*, I^*)} \le 0,$$

$$1 - \frac{I(t)}{I^*} \cdot \frac{F(S(t), I^*)}{F(S(t), I(t))} + \ln \frac{I(t)}{I^*} \cdot \frac{F(S(t), I^*)}{F(S(t), I(t))} \le 0.$$

(30)

Furthermore, by (H7) the following inequality holds:

$$\left(\frac{I(t)}{I^*} - \frac{F(S(t), I(t))}{F(S(t), I^*)}\right) \left(\frac{F(S(t), I^*)}{F(S(t), I(t))} - 1\right) \le 0.$$
(31)

And by (H8) we have the following inequality:

$$\left(\frac{G\left(I\left(t\right)\right)}{G\left(I^{*}\right)} - \frac{I\left(t\right)}{I^{*}}\right)\left(\frac{I^{*}}{I\left(t\right)} - 1\right) \le 0.$$
(32)

By (29)–(32), we see that $dV_2/dt \leq 0$ for all $S(t) \geq 0$, $I(t) \geq 0$. It is easy to verify that the largest invariant set in $\{(S(t), I(t)) \mid dV_2/dt = 0\}$ is the singleton $\{E^*\}$. By the Lyapunov-LaSalle asymptotic stability theorem in [31], E^* is globally asymptotically stable for any $\tau > 0$. This completes the proof.

4. Discussion and Conclusion

In this paper, we formulated an SIR epidemic model with delay and two general functions, one is F(S, I) which represents the incidence rate, and the other is G(I) which represents the recovered infected individuals from the infected compartment. We studied the global asymptotic stability of disease-free equilibrium and endemic equilibrium of system (2), respectively. We showed that in Theorem 2 the disease-free equilibrium $E_0 = (S_0, 0)$ is locally asymptotically for any $\tau > 0$ if the basic reproduction number $R_0 < 1$ and $E_0 = (S_0, 0)$ are unstable if $R_0 > 1$; in Theorem 3 the disease-free equilibrium $E_0 = (S_0, 0)$ is globally asymptotically for any $\tau > 0$ if $R_0 \le 1$, while in Theorem 4, the endemic equilibrium $E^* = (S^*, I^*)$ is globally asymptotically for any $\tau > 0$ if $R_0 > 1$.

In order to obtain the global properties of the system (2), we proposed assumptions (H1)–(H8) for functions of F(S, I) and G(I). Conditions (H1)–(H3) are some basic assumptions; for example, (H1) implies that the function F(S, I) is a non-negative differentiable function on nonnegative quadrant and

is positive if and only if both arguments are positive. We used (H4)-(H6), (H7)-(H8) to establish the global asymptotic stability of disease-free equilibrium and endemic equilibrium of system (2), respectively. These hypotheses seem to be mathematical techniques; however, they may be obviously true for many concrete forms of the functions of F(S, I) and G(I) in previous studies.

A special case of system (2) is that when $G(I) = \gamma I$, γ is the recovery rate of the infective individuals. System (2) becomes the following DDEs:

10 (1)

$$\frac{dS(t)}{dt} = \lambda - \mu S(t) - F(S(t), I(t)),$$

$$\frac{dI(t)}{dt} = e^{-\mu\tau} F(S(t-\tau), I(t-\tau)) - (\mu + \alpha + \gamma) I(t).$$
(33)

The basic reproductive number for system (33) is presented as

$$R'_{0} = \frac{e^{-\mu\tau}F'_{I}(S_{0},0)}{\mu + \alpha + \gamma}.$$
(34)

Using Theorems 3 and 4, we can easily obtain the global asymptotic stability of the disease-free equilibrium and the endemic equilibrium of system (33). Regarding to system (33), we now give examples of incidence function F(S, I) that satisfies the required hypotheses obviously.

Example 5. Without delay: let $\tau = 0$, $\lambda = \mu$ and $\delta = \mu + \alpha + \gamma$. Then system (33) becomes to the SIR model studied in [27].

Example 6. Holling type II incidence rate: let $F(S, I) = v_m SI/(C_h + S)$ for some constant $v_m, C_h > 0$. Then the hypotheses on F(S, I) are satisfied and the global properties are determined by the basic reproductive number. This model was introduced by [32, 33] for considering delays in the standard bacterial growth model in a chemostat. Its global dynamics were first proved by [32] by the fluctuation lemma and a different proof was given in [34, Theorem 5.16] by comparison.

Example 7. Saturate incidence rate: let $F(S, I) = \beta SI/(1+\alpha_1S+\alpha_2I)$ for some constant $\alpha_1 > 0$, $\alpha_2 > 0$. Then hypotheses about F(S, I) are also satisfied and the global properties are determined by the basic reproductive number. The behaviors of this model were previously studied in [23, 24]. In [23], the local stability of disease-free equilibrium and endemic equilibrium was obtained. And in [24], the global stability of disease-free equilibrium was studied.

From these Examples 5–7, we can see that system (2) is reasonably established and it can contain many classical epidemic models and imply their global dynamics as special cases.

Conflict of Interests

The authors declare that there is no conflict of interests regarding the publication of this paper.

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