## ON CONTINUOUS IMAGE AVERAGING OF PROBABILITY MEASURES

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Let  $M$  be a compact space, and  $X$  a complete sparable metric space. Let  $P(X)$  denote the probability measures on *X.* Let *λ* be a probability measure on *M.* Define a function  $\varphi_{\lambda}$  *from*  $C(M, P(X))$  *to*  $P(X)$  *by*  $\varphi_{\lambda}(T)(f) = \Big| T(t)(f) d\lambda(t)$  *for* every  $T \in C(M, P(X)), f \in C(X)$ . We show that  $\varphi_{\lambda}$  is an open mapping.

1. Introduction. By a measure on a space  $X$ , we mean a regular Borel measure on *X.* A nonnegative measure is called a probability measure if its total mass is 1.

Let  $M$  be a compact space, and let  $X$  be a complete separable metric space. Let  $P(X)$  denote the collection of all probability measures on *X.* Let *C(X)* denote the set of all bounded continuous real-valued functions on X. Give  $P(X)$  the weak topology as functionals on  $C(X)$ . Let  $C(M, P(X))$  denote the set of all continuous functions from *M* into  $P(X)$ . Give  $C(M, P(X))$  the topology of uniform convergence. Let  $\lambda$  be a fixed probability measure on M. For each  $T \in C(M, P(X))$ , define a functional  $\varphi_1(T)$  on  $C(X)$  by

$$
\varphi_{\lambda}(T)(f) = \int T(t)(f) d\lambda(t) .
$$

By [3, p. 35 and p. 47],  $\varphi_{\lambda}(T)$  may be considered as a measure in  $P(X)$ . Write  $\varphi_{\lambda}(T)=\Big\langle T(t)d\lambda(t). \Big\rangle$  Denote the mapping  $T\rightarrow \varphi_{\lambda}(T)$  by  $\varphi_{\lambda}$ . Then  $\varphi_{\lambda}$  is a continuous function from  $C(M, P(X))$  into  $P(X)$ . This paper is to show that  $\varphi$ , is an open mapping. This result contains a result due to Eifler [2, Theorem 2.4] as a special case when *M* consists of two points.

For a metric space X, we write  $x_n \to x$  if  $(x_n)_{n=1}^{\infty}$  converges to x in  $X$ .

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2. Basic lemmas. We will use the following notation in Lemma 2.1: Let *X* and *Y* be complete separable metric spaces, and *π: Y—>X* a continuous function. Then  $\pi$  induces a mapping also denoted by  $\pi$ , from  $P(Y)$  to  $P(X)$  and defined by  $\pi \mu(E) = \mu(\pi^{-1}(E)).$