# A NOTE ON THE JACOBI-PERRON ALGORITHM 

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In this paper we give a simple geometric description of the Jacobi-Perron algorithm, based on the matrix-theoretic approach to the algorithm. An important advantage of the geometric description is that it may be used as an aid to intuition as well as a practical tool. As an illustration, we prove convergence for a special case.

The theory and procedures of the JPA have been studied from many different viewpoints (cf. [1] and [3]). We consider here some of the linear algebra and geometry naturally associated with the matrix theory of the JPA.

In particular, for $n=2,3$ the procedures of the JPA may be represented concretely in the Euclidean spaces $R^{2}$ and $R^{3}$, and the notion of convergence of the JPA takes on a fairly simple geometrical meaning.

In §1 we summarize briefly the JPA as described by Bernstein in [1] (throughout, we use [1] as the standard reference). In §2, we restate the definitions given in §1 in matrix-theoretic terms. Based on this, we give a general description of the geometrical meaning which may be attached to the notion of convergence of the JPA. In §3 we consider in detail the geometry associated with the JPA for $n=3$. The behavior of a JPA may be represented graphically in this case. (This may be done similarly for $n=2$, but the case $n=3$ is far more representative of the general case.) We conclude with a straightforward, elementary proof of the convergence of any JPA for a $T$-function whose values are positive integers, for the case $n=3$.

1. The Jacobi-Perron algorithm (JPA). In this section, we briefly recall the description of the JPA given in [1], and throughout this section we use the notation of [1].

Let $n$ be fixed, and let $k$ be a nonnegative integer. The vector $a^{(k)}$ in $R^{n-1}$ is defined by

$$
\begin{equation*}
a^{(k)}=\left(a_{1}^{(k)}, a_{2}^{(k)}, \cdots, a_{n-1}^{(k)}\right) . \tag{1.1}
\end{equation*}
$$

A transformation $T$ of $R^{n-1}$ to itself is defined as follows: suppose $f$ is a (vector) function on $R^{n-1}$ such that

$$
\begin{equation*}
f\left(\alpha^{(k)}\right)=b^{(k)}=\left(b_{1}^{(k)}, b_{2}^{(k)}, \cdots, b_{n-1}^{(k)}\right) \tag{1.2}
\end{equation*}
$$

and suppose also that $a_{1}^{(k)} \neq b_{1}^{(k)}$. Then put

