

ON SOME SPECIAL SYSTEMS OF EQUATIONS

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1. Let F be an arbitrary field. Let S be a system of equations which, when solved for two of its variables, takes the following form:

$$(1) \quad \begin{aligned} x_1^{k_1} &= f(x_3, \dots, x_n), \\ x_2^{k_2} &= g(x_3, \dots, x_n), \end{aligned}$$

where f and g are arbitrary functions of the indicated variables. Consider also the equation

$$(2) \quad y^{k_1 k_2} = f^{s k_2}(y_3, \dots, y_n) g^{r k_1}(y_3, \dots, y_n).$$

THEOREM 1. *If $(k_1, k_2) = 1$ and $r k_1 + s k_2 = 1$, then the distinct solutions of (1) in F with $x_1 x_2 \neq 0$ may be put in one-to-one correspondence with the distinct solutions of (2) in F with $y \neq 0$. Moreover, these solutions of (1), $x_1 x_2 \neq 0$, may be determined from the solutions of (2), $y \neq 0$, and conversely, by means of transformations (3) and (4) below.*

Proof. Assuming for the rest of this section that $x_1 x_2 \neq 0$, $y \neq 0$, we put

$$(3) \quad \begin{aligned} x_1 &= y^{k_2} \left\{ \frac{f(y_3, \dots, y_n)}{g(y_3, \dots, y_n)} \right\}^r, \\ x_2 &= y^{k_1} \left\{ \frac{g(y_3, \dots, y_n)}{f(y_3, \dots, y_n)} \right\}^s, \\ x_i &= y_i \qquad \qquad \qquad (i=3, \dots, n) \end{aligned}$$

and notice that if (y, y_3, \dots, y_n) is a solution of (2) then (3) determines a solution of (1). Now let

$$(4) \quad \begin{aligned} y &= x_1^s x_2^r, \\ y_i &= x_i \qquad \qquad \qquad (i=3, \dots, n). \end{aligned}$$

It may be verified directly that if (x_1, x_2, \dots, x_n) is a solution of (1) then (4) determines a solution of (2). Further, given a solution (x_1, x_2, \dots, x_n) of (1) and a solution (y, y_3, \dots, y_n) of (2) with $x_i = y_i$ ($i=3, \dots, n$), then (3) implies (4) and conversely—which may be verified with the use of the relation $r k_1 + s k_2 = 1$.