## A THREE POINT CONVEXITY PROPERTY

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There exist an interesting variety of set properties determined by placing restrictions on each triple of points of the set. It is the purpose here to study those closed sets in the *n*-dimensional Euclidean space  $E_n$  (in particular the plane  $E_2$ ) which satisfy the following condition.

DEFINITION 1. A set S in  $E_n$  is said to possess the *three-point* convexity property  $P_3$  if for each triple of points x, y, z in S at least one of the closed segments xy, yz, xz is in S.

The principal result obtained in this paper appears in Theorem 2. In order to achieve this result a series of lemmas and theorems is first established. Most of these are also of independent interest.

1. Closed connected sets in  $E_n$ ,  $n \ge 1$ . In this section we assume that S is a closed connected set in  $E_n$ ,  $n \ge 1$ . The concept of *local* convexity is a useful one for our purpose, so we restate the well-known definition.

DEFINITION 2. A set S is said to be *locally convex at a point*  $q \in S$  if there exists an open sphere N with center at q such that  $S \cdot N$  is convex. If a set is locally convex at each of its points, it is said to be *locally convex*.

NOTATION 1. The open segment determined by points x and y is denoted by (xy), whereas xy denotes the closed segment. The line determined by x and y is denoted by L(x, y). The boundary of a set S is B(S), and H(S) denotes the closed convex hull of S. The symbol + stands for set union, and the symbol  $\cdot$  stands for set product.

THEOREM 1. Let S be a closed connected set in  $E_n$   $(n \ge 1)$  which has property  $P_3$ . Then either S is convex or S is starlike with respect to each of its points of local nonconvexity (It may be starlike elsewhere).

*Proof.* If S is locally convex, then by a theorem of Tietze [4, pp. 697-707], [2, pp. 448-449], the set S is convex, in which case it is starlike with respect to each of its points. Hence, suppose S is not locally convex, and let  $q \in S$  be a point of local nonconvexity. This implies that in each spherical neighborhood  $N_i$  of q, there exist points

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