ON THE DETERMINATION OF CONFORMAL IMBEDDING

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Two imbedding fundamental forms determine (up to motions) the smooth imbedding of an oriented surface in E^3 . The situation is, however, substantially different for the sufficiently smooth conformal imbedding of a Riemann surface R in E^3 . Conventionally such an imbedding is achieved by a conformal correspondence between R and the Riemann surface R_1 determined on a smoothly imbedded oriented surface S in E^3 by its first fundamental from I. We show that except where $H \cdot K = 0$ on S, such an R_1 conformal imbedding of R in E^3 is determined (up to motions) by the second fundamental form II on S, expressed as a form on R. In particular, I is determined by II on R_1 , where $H \cdot K \neq 0$ on S.

Similar remarks are valid for two less standard methods of conformal imbedding. If an oriented surface S is smoothly imbedded in E^3 so that H > 0 and K > 0, then II defines a Riemann surface R_2 on S. And, if S is imbedded so that K < 0, then II' given by

$$H'II' = KI - HII$$

with

$$H' = -\sqrt{H^2 - K}$$

defines a Riemann surface R'_2 on S. Thus a conformal correspondence between R and R_2 (or R'_2) is called an R_2 (or R'_2) conformal imbedding of R in E^3 . We show that I on S, expressed as a form on R, determines the R_2 or (wherever $H \neq 0$ and sign H is know) the R'_2 imbedding of R in E^3 (up to motions). In particular, I determines II on R_2 , and (where $H \neq 0$, and sign H is known) on R'_2 as well. Finally, we give restatements of the fundamental theorem of surface theory in forms appropriate to R_1, R_2 and R'_2 conformal imbeddings in E^3 .

The two fundamental forms which determine (up to motions) the smooth imbedding of an oriented surface in E^3 are, of course, related by various equations. But neither form determines the other, except in very special cases. Thus, for instance, isometric imbeddings of a surface in E^3 may differ essentially unless (to cite a famous example) the surface is compact, and the common metric imposed by imbedding has positive Gaussian curvature.

2. Consider an oriented surface S which is C^3 imbedded in E^3 .

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