

DECOMPOSITION THEOREMS FOR 3-CONVEX SUBSETS OF THE PLANE

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Let S be a 3-convex subset of the plane. If $(\text{cl } S \sim S) \subseteq \text{int } (\text{cl } S)$ or if $(\text{cl } S \sim S) \subseteq \text{bdry } (\text{cl } S)$, then S is expressible as a union of four or fewer convex sets. Otherwise, S is a union of six or fewer convex sets. In each case, the bound is best possible.

1. **Introduction.** Let S be a subset of R^d . Then S is said to be 3-convex iff for every three distinct points in S , at least one of the segments determined by these points lies in S . Valentine [2] has proved that for S a closed, 3-convex subset of the plane, S is expressible as a union of three or fewer closed convex sets. We are interested in obtaining a similar decomposition without requiring the set S to be closed. The following definitions and results obtained by Valentine will be useful.

For $S \subseteq R^d$, a point x in S is a *point of local convexity* of S iff there is some neighborhood U of x such that, if $y, z \in S \cap U$, then $[y, z] \subseteq S$. If S fails to be locally convex at some point q in S , then q is called a *point of local nonconvexity* (lnc point) of S .

Let S be a closed, connected, 3-convex subset of the plane, and let Q denote the closure of the set of isolated lnc points of S . Valentine has proved that for S not convex, then $\text{card } Q \geq 1$, Q lies in the convex kernel of S , and $Q \subseteq \text{bdry } (\text{conv } Q)$. An *edge* of $\text{bdry } (\text{conv } Q)$ is a closed segment (or ray) in $\text{bdry } (\text{conv } Q)$ whose endpoints are in Q . We define a *leaf* of S in the following manner: In case $\text{card } Q \geq 3$, let L be the line determined by an edge of $\text{bdry } (\text{conv } Q)$, L_1, L_2 the corresponding open halfspaces. Then L supports $\text{conv } Q$, and we may assume $\text{conv } Q \subseteq \text{cl } (L_1)$. We define $W = \text{cl } (L_2 \cap S)$ to be a *leaf* of S . For $2 \geq \text{card } Q \geq 1$, constructions used by Valentine may be employed to decompose S into two closed convex sets, and we define each of these convex sets to be a *leaf* of S .

By Valentine's results, every point of S is either in $\text{conv } Q$ or in some leaf W of S (or both), and every leaf W is convex. Moreover, Valentine obtains his decomposition of S by showing that for any collection $\{s_i\}$ of disjoint edges of $\text{bdry } (\text{conv } Q)$, with $\{W_i\}$ the corresponding collection of leaves, $\text{conv } Q \cup (\bigcup W_i)$ is closed and convex.

Finally, we will use the following familiar definitions: For x, y in S , we say x *see* y *via* S iff the corresponding segment $[x, y]$ lies in S . A subset T of S is *visually independent via* S iff for every