W_{δ} (T) IS CONVEX

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Stampfli introduced a generalization of the numerical range for any bounded linear operator T on a Hilbert space \mathscr{H} . This is denoted by $W_{\delta}(T)$ and is defined by

 $W_{\delta}(T) =$ closure $\{\langle Tx, x \rangle : ||x|| = 1 \text{ and } ||Tx|| \ge \delta \}$.

Stampfii asked whether $W_{\delta}(T)$ is convex. In this short note we provide an affirmative answer to this question.

 $\mathscr{L}(\mathscr{H})$ will denote the set of bounded linear operators on the Hilbert space \mathscr{H} .

LEMMA 1. Suppose S and A belong to $\mathcal{L}(\mathcal{H})$, and that $S = S^*$. Then

 $S(A, \delta) = \{x \in \mathscr{H} : ||x|| = 1 \text{ and } ||Ax|| \ge \delta \text{ and } \langle Sx, x \rangle = 0\}$

is path connected.

Proof. Suppose x and y belong to $S(A, \delta)$. We may assume that x and y are linearly independent. (If not, they both lie on an arc of

$$\{e^{i\theta}x: 0 \leq \theta \leq 2\pi\}$$

which lies in $S(A, \delta)$ if x does.)

Choose θ in **R** such that $e^{i\theta} \langle Sx, y \rangle$ is purely imaginary and let $a = e^{i\theta}x$.

Choose *n* such that $(-1)^* \operatorname{Re} \langle (A^*A - \delta^2 I)a, y \rangle$ is positive and let $b = (-1)^* y$. Then *a* and *b* may be joined by a path in $S(A, \delta)$ to *x* and *y* respectively. Thus we need only find a path connecting *a* to *b*. Let y(t) = ta + (1-t)b and let $x(t) = ||y(t)||^{-1}y(t)$. Then $\langle Sx(t), x(t) \rangle = 0 \Leftrightarrow \langle Sy(t), y(t) \rangle = 0$ and

$$egin{aligned} &\langle Sy(t),\,y(t)
angle &=t^2\langle Sa,\,a
angle +(1-t)^2\langle Sb,\,b
angle \ &+2Ret(1-t)\langle Sa,\,b
angle \ &=2(-1)^nt(1-t)Ree^{i heta}\langle Sx,\,y
angle \ &=0 \ . \end{aligned}$$

Also

$$egin{aligned} ||Ay(t)||^2 &= \langle A^*Ay(t), \, y(t)
angle \ &= t^2 \, ||Aa\,||^2 + (1-t)^2 ||Ab\,||^2 \ &+ 2t(1-t) Re \langle A^*Aa, \, b
angle \end{aligned}$$