## THREE-DIMENSIONAL OPEN BOOKS CONSTRUCTED FROM THE IDENTITY MAP

## MAURICE GILMORE

Three-dimensional manifolds are constructed as open books, using the identity diffeomorphism. The open book constructed in this way with (non)orientable page of Euler characteristic  $\chi$  is the connected sum of  $(1-\chi)$  copies of the (non)orientable  $S^2$  bundle over  $S^1$ 

Introduction. We investigate orientable and nonorientable three-dimensional manifolds which are open books according to the following definition of Winkelnkemper [2].

DEFINITION. A manifold of dimension n is said to have an open book description if it can be constructed using a co-dimension 2 submanifold  $\partial V$  and a diffeomorphism  $h: V \to V$  of an (n-1)-dimensional manifold with boundary  $\partial V$ . h is required to be the identity map in a neighborhood of  $\partial V$ . The construction is to form the mapping torus  $(V \times I)/(v, 0) = (h(v), 1)$  and then to identify (v, t) = (v, t') for all v in  $\partial V$  and t, t' in I. The image of the copies of  $\partial V$  in the resulting manifold is called the binding of the open book and the circle's worth of copies of V are called the pages.

Related results appear in the recent book of Rolfsen [1].

Statement of results.

Theorem 1. If  $V = S_g - n\mathring{B^2}$ , the surface of genus g with n disjoint, open discs removed from it, then the open book produced by setting h equal to the identity map is the connected sum of (2g + (n-1)) copies of  $(S^1 \times S^2)$ . (Adopt the convention that zero copies of  $(S^1 \times S^2)$  will refer to  $S^3$ .)

THEOREM 2. If  $V = P_k - n\mathring{B^2}$ , the 2-sphere with k cross-caps attached and n disjoint, open discs removed from it, then the open book produced by setting h equal to the identity map is the connected sum of (k + (n-1)) copies of the Klein bottle of dimension three.  $(k \ge 1, n \ge 1)$ 

By the three-dimensional Klein bottle we mean the nonorientable  $S^2$  bundle over  $S^1$ ,  $(S^2 \times I)/(x, y, z, 0) = (-x, y, z, 1)$ .

Proofs of results.