

NONLINEAR DIFFERENTIAL EQUATIONS WITH MONOTONE SOLUTIONS

KURT KREITH

The differential equation $dy^4/dt^4 - y = 0$ has as a fundamental set of solutions $\sin t, \cos t, e^t$, and e^{-t} . The latter of these is distinguished by the properties of being positive and strictly decreasing to zero as $t \rightarrow \infty$. As such, e^{-t} is the prototype of the "monotone solution" whose existence will be demonstrated for a large class of nonlinear differential equations of even order.

Our method will be restricted to differential equations of order $2n$ which can be written as second order systems of the form

$$(1.1) \quad \mathbf{x}'' = f(\mathbf{x}, t)$$

where $\mathbf{x} \in \mathbf{R}^n$ and f is a continuous function from $\mathbf{R}^n \times [0, \infty)$ into \mathbf{R}^n satisfying other conditions to be formulated in §2. Without resolving the question of what scalar equations allow such a representation, it is clear that our considerations will include nonselfadjoint linear fourth order equations (see [5]), equations of the form

$$\begin{aligned} (p_1 y'')'' &= f_2(y, y'', t) \\ [p_2(p_1 y'')]'' &= f_3(y, y'', y^{iv}, t), \end{aligned}$$

and similar equations of higher order.

In case (1.1) is linear and

$$(1.2) \quad \mathbf{x}'' = A(t)\mathbf{x}$$

where $A(t) = (a_{ij}(t))$ is a continuous $n \times n$ matrix, criteria for the existence of monotone solutions of (1.2) are well known. In particular, by letting $\mathbf{w} = -'\mathbf{x}$, (1.2) can be written as a first order system of the form

$$(1.3) \quad \begin{pmatrix} \mathbf{x} \\ \mathbf{w} \end{pmatrix}' = - \begin{pmatrix} 0 & I \\ A(t) & 0 \end{pmatrix} \begin{pmatrix} \mathbf{x} \\ \mathbf{w} \end{pmatrix}.$$

According to Hartman [2; Ch 14, Theorem 2.1], the condition $a_{ij}(t) \geq 0$ for $1 \leq i, j \leq n$, and $0 \leq t < \infty$ assures the existence of a nontrivial solution of (1.3) for which $x_i(t) \geq 0$ and $x'_i(t) \leq 0$ for $1 \leq i \leq n$ and $0 \leq t < \infty$. Since $\mathbf{x}(t)$ also satisfies (1.2), these results readily carry over to linear second order systems.

Nonlinear problems of the form (1.1) have also been studied by Hartman and Wintner [3] in terms of the related first order systems.