

REPRESENTATIONS OF GAUSSIAN PROCESSES BY WIENER PROCESSES

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Let $\{X(t), a \leq t \leq b\}$ and $\{W(t), 0 \leq t < \infty\}$ be a Gaussian process and the standard Wiener process, respectively. Investigating covariance structure of $X(t)$, the paper gives various representations of $X(t)$ in terms of $W(t)$, including stochastic integral representations. Some of these representations are useful in finding hitherto unknown barrier-crossing probabilities of $X(t)$.

1. Introduction. Let $X(t)$ be a Gaussian process on some interval I with covariance function

$$R(s, t) = E\{X(s) - \mu(s)\{X(t) - \mu(t)\},$$

where $\mu(t)$ is the mean function, $\mu(t) = EX(t)$.

It is well-known that a Gaussian process is uniquely determined, up to the mean function, by the covariance function $R(s, t)$.

The Gaussian process which has been studied most extensively is, of course, the Wiener process $\{W(t); t \geq 0\}$. Therefore, it is natural to seek representations of Gaussian processes in terms of Wiener processes.

(i) A classical result by Doob [3, pp. 401-402] shows that: If a Gaussian process $X(t)$ has mean zero and the covariance function in the form

$$R(s, t) = u(s)v(t), \quad s \leq t$$

for s, t in some interval, and if the ratio $u(t)/v(t) \equiv a(t)$ is continuous and increasing with its inverse function $a_1(t)$, then

$$X(a_1(t))/v(a_1(t)) = W(t),$$

where $W(t)$ is the standard Wiener process (or the Brownian motion process).

Another well-known result is the following:

(ii) If a Gaussian process $X(t)$ with zero mean has a factorable covariance function on $[0, T]^2$, i.e.,

$$R(s, t) = \int_0^T r(s, u)r(t, u)du,$$

where for each $t \in [0, T]$ $r(t, \cdot) \in L_2[0, T]$, then $X(t)$ has a stochastic integral representation