

TOPOLOGIES FOR FUNCTION SPACES

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1. Introduction. Let Z^Y denote the class of continuous functions (or "mappings," or "maps")

$$(1.1) \quad f: Y \rightarrow Z$$

of a topological space Y into another Z . A great variety of topologies t may be introduced into Z^Y making it into a topological space $Z^Y(t)$. The topologies we deal with in this paper can be classified by using the notion of "continuous convergence" of directed sets (generalized sequences) f_μ in Z^Y as follows: with no reference to any topology Z^Y , we can say f_μ *converges continuously* (Frink [1]; Kuratowski [2]) to f (f_μ and f are elements of Z^Y) if

$$(1.2) \quad f_\mu(y_\nu) \rightarrow f(y)$$

whenever $y_\nu \rightarrow y$ in Y . (We use the " \rightarrow " for convergence as in (1.2), as well as for indicating the domain-range relation as in (1.1). The context prevents confusion.) We can classify the topologies t for Z^Y according as to whether

$$(1.3) \quad \text{convergence in } Z^Y(t) \text{ implies continuous convergence}$$

or

$$(1.4) \quad \text{continuous convergence implies convergence in } Z^Y(t).$$

Certainly there are other topologies possible in Z^Y , but we do not discuss these. There may be a topology t satisfying both (1.3) and (1.4), but if so it is unique; see (5.6).

An apparently different approach to the same classification is suggested by homotopy theory. Beside Y and Z , consider a third space X . For a function g defined on $X \times Y$ with values in Z , we can define $g^*(x)$ mapping Y into Z^Y by setting $g^*(x)(y) = g(x, y)$. Then a topology t for Z^Y may be such that, for any X ,

$$(1.5) \quad \text{if } g \text{ is continuous, then } g^* \text{ is continuous,}$$

or

$$(1.6) \quad \text{if } g^* \text{ is continuous, then } g \text{ is continuous.}$$