

CONTROL OF DIFFUSION PROCESSES IN R^d AND BELLMAN EQUATION WITH DEGENERATION

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0. Introduction

In this paper we consider the existence and uniqueness of solutions of the following Bellman equation:

$$(0.1) \quad \begin{cases} \inf_{\alpha \in A} \{ \partial v / \partial s + 1/2 \sum_{1 \leq i, j \leq \nu} a_{ij}(\alpha, s, x) \partial^2 v / \partial x_i \partial x_j + \\ \sum_{i=1}^d b_i(\alpha, s, x) \partial v / \partial x_i - c(\alpha, s, x) v + L(\alpha, s, x) \} = 0, \\ v(T, x) = h(x) \end{cases}$$

where $1 \leq \nu < d$, A is a separable metric space and (a_{ij}) , $1 \leq i, j \leq \nu$, is a positive definite matrix.

W.H. Fleming already considered in [1] the following equation which is more restrictive than Eq. (0.1):

$$(0.2) \quad \begin{cases} \partial v / \partial s + 1/2 \sum_{1 \leq i, j \leq \nu} a_{ij}(s, x) \partial^2 v / \partial x_i \partial x_j + \sum_{i=\nu+1}^d b_i(s, x) \partial v / \partial x_i \\ + \inf_{\alpha \in A} \{ \sum_{i=1}^{\nu} b_i(\alpha, s, x) \partial v / \partial x_i - c(\alpha, s, x) v + L(\alpha, s, x) \} = 0, \\ v(T, x) = h(x). \end{cases}$$

In [1] he also considered the deterministic case that $\nu=0$ in Eq. (0.2). His approach to this equation is as follows; consider stochastic control problem for a system described by the following stochastic differential equation:

$$(0.3) \quad dX_t = b(\alpha_t, t, X_t) dt + \sigma(t, X_t) dB_t, \quad X_s = x,$$

where $b_i(\alpha, s, x) = b_i(s, x)$ for all $i = \nu + 1, \dots, d$, $\sigma = \begin{pmatrix} \bar{\sigma} & 0 \\ 0 & 0 \end{pmatrix}$, $\bar{\sigma}$ is a nonsingular (ν, ν) -matrix, (B_t) is a vector valued Brownian motion, x is a vector of R^d and (α_t) is a non-anticipative control variable having values in A . Define the cost v by the following formula:

$$(0.4) \quad v(s, x) = \inf E \left[\int_s^T L(\alpha_t, t, X_t^{\alpha, s, x}) \exp \left\{ - \int_s^t c(\alpha_r, r, X_r^{\alpha, s, x}) dr \right\} dt \right. \\ \left. + h(X_T^{\alpha, s, x}) \exp \left\{ - \int_s^T c(\alpha_t, t, X_t^{\alpha, s, x}) dt \right\} \right],$$