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## ON EQUIVARIANT J-HOMOMORPHISM FOR INVOLUTIONS

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**Introduction.** Let G be the cyclic group of order 2.

We denote by  $\pi_S^{*,*}$  the equivariant stable cohomotopy theory [2, 3] and by  $KO_G^*$  the K-theory of real G-vector bundles on G-spaces. For a finite pointed G-complex we then have an equivariant  $J_G$ -map  $J: \widetilde{KO}_G^{-1}(X) \to \pi_S^{0,0}(X)$  [14], which becomes a homomorphism if X is a suspension in the usual sense.

Let  $R^{p,q}$  be the euclidean space  $R^{p+q}$  with non trivial G-action on the first p coordinates and  $\Sigma^{p,q}$  be the one point compactification of  $R^{p,q}$ , with  $\infty$  as base point. We have the canonical isomorphism  $\pi_{S}^{0,0}(\Sigma^{p,q}) \approx \pi_{p,q}^{S}$ , the (p, q)-th equivariant stable homotopy group of Landweber [9, 3] (which is  $\pi_{p+q,p}$  of Bredon [5]), and therefore we get an induced map

$$\widetilde{KO}_{G}^{-1}(\Sigma^{p,q}) \rightarrow \pi^{0,0}_{S}(\Sigma^{p,q}) \approx \pi^{S}_{p,q}$$

which we also denote by  $J_G$ . P. Löffler [10] showed that if  $\widetilde{KO}_G^{-1}(\Sigma^{p,q})$  is a torsion group then  $J_G$  is a split injection. In this paper we shall study the image of  $J_G$ when  $\widetilde{KO}_G^{-1}(\Sigma^{p,q})$  is torsion free. And then we shall give a supplement to [11] on Im  $J_R$ . The  $J_G$  is also studied by M.C. Crabb [6].

We denote by Z/n a cyclic group of order *n*, by  $R \cdot x$  the free module over a ring *R* generated by *x*. If  $p \equiv i \mod 8$  and  $q \equiv j \mod 8$ , then we write  $(p, q) \equiv (i, j) \mod 8$ .

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## 1. The J-homomorphism $J_G$

In this section we shall give the relations between various homomorphisms and collect some basic tools. Let X be a finite pointed G-complex.

Let KR denote the K-functor of [4]. By regarding a Real vector bundle on X as a real G-vector bundle on X we get a homomorphism  $\sigma \colon \widetilde{KR}^{-1}(X) \to \widetilde{KO}_{G}^{-1}(X)$ . We define a map  $J_{\mathbb{R}} \colon \widetilde{KR}^{-1}(X) \to \pi_{S}^{0,0}(X)$  by

$$(1.1) J_R = J_G a$$