

## NON-LINEAR PREDICTION PROBLEMS FOR ORNSTEIN-UHLENBECK PROCESS

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### §0. Introduction

We shall discuss in this paper some problems in non-linear prediction theory. An Ornstein-Uhlenbeck process  $\{U(t)\}$  is taken to be a basic process, and we shall deal with stochastic processes  $X(t)$  that are transformed by functions  $f$  satisfying certain condition. Actually, observed processes are expressed in the form  $X(t) = f(U(t))$ . Our main problem is to obtain the best non-linear predictor  $\hat{X}(t, \tau)$  for  $X(t + \tau)$ ,  $\tau > 0$ , assuming that  $X(s)$ ,  $s \leq t$ , are observed. The predictor is therefore a non-linear functional of the values  $X(s)$ ,  $s \leq t$ .

Non-linear prediction theory that discusses how to obtain such non-linear predictors has been considered in various situations. For instance, I. I. Gihman and A. V. Skorohod (cf. [1], §8, Chapter IV, Vol. I) have considered optimum mean square predictor of  $X(t + \tau)$ ,  $\tau > 0$ , assuming that the basic process  $V(s)$ ,  $s \leq t$ , itself is observed. As is well-known the predictor  $\hat{X}(t, \tau)$  is given by the conditional expectation:

$$(1) \quad \hat{X}(t, \tau) = E\{X(t + \tau) | \mathcal{B}_t(V)\}, \quad \mathcal{B}_t(V) = \sigma\{V(s); s \leq t\}.$$

While A. M. Yaglom [5] has discussed the optimum mean square predictor assuming that Markov process  $V(t)$  is transformed by a function  $f$  with inverse  $f^{-1}$  and that  $X(s) = f(V(s))$ ,  $s \leq t$ , are observed.

In this case, it holds evidently that

$$(2) \quad \begin{aligned} \hat{X}(t, \tau) &= E\{X(t + \tau) | X(s); s \leq t\} = E\{X(t + \tau) | X(t)\} \\ &= E\{X(t + \tau) | V(t)\} = E\{X(t + \tau) | V(s); s \leq t\}. \end{aligned}$$

Yaglom's situation coincides with ours in the sense that the  $X(s)$  are assumed to be given for  $s \leq t$ . In this case, too, the predictor (2) coincides with (1) actually, because  $f$  is invertible.