

## WHITE NOISE ANALYSIS AND TANAKA FORMULA FOR INTERSECTIONS OF PLANAR BROWNIAN MOTION

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### § 1. Introduction

In this paper, we shall use Hida's [5, 7, 9] theory of generalized Brownian functionals (or named white noise analysis) to establish a stochastic integral formula concerning the multiple intersection local times of planar Brownian motion  $B(t)$ . First, we review some basic facts. It is well-known that, for each  $r \geq 2$ , a.s.  $B(t)$  has points of multiplicity  $r$ , see Dvoretzky-Erdős-Kakutani [1] and Geman-Horowitz-Rosen [4]. A formal measure on such  $r$ -fold self-intersections is

$$(1.1) \quad \int \cdots \int_D \delta(B(t_2) - B(t_1)) \cdots \delta(B(t_r) - B(t_{r-1})) dt_1 \cdots dt_r,$$

where  $D \subset \{(t_1, \dots, t_r) | 0 \leq t_1 \leq t_2 \leq \dots \leq t_r < \infty\}$ . Rosen [15] proved that (a.s.) there exists measurable  $\alpha_r(x, D)$ ,  $x \in R^{2(r-1)}$ , called the  $r$ -fold intersection local time, such that for all bounded measurable  $g(x)$  on  $R^{2(r-1)}$

$$\begin{aligned} \int \cdots \int_D g(B(t_2) - B(t_1), \dots, B(t_r) - B(t_{r-1})) dt_1 \cdots dt_r \\ = \int_{R^{2(r-1)}} \cdots \int g(x) \alpha_r(x, D) dx. \end{aligned}$$

In case  $D = \prod_{i=1}^r [a_i, b_i]$ ,  $0 < a_1 < b_1 < a_2 < b_2 < \dots < b_r$  (the off-diagonal case), Rosen [15, 17] proved that (a version of)  $\alpha_r(x, D)$  can be chosen so that it is (a.s.) jointly continuous in  $x, a_i, b_i$ . Thus, (1.1) is represented as  $\alpha_r(0, D)$  in this case. However, in case  $D = D_T = \{(t_1, \dots, t_r) | 0 \leq t_1 \leq \dots \leq t_r \leq T\}$  (the diagonal case), then  $\alpha_r(x, T) \equiv \alpha_r(x, D_T)$  can only be continuous on  $(R^2 \setminus \{0\})^{r-1}$ . To study the asymptotics of  $\alpha_r(x, T)$  as  $x \rightarrow 0$ , it is intended to find that after subtracting off certain explicit "infinite part" from  $\alpha_r(x, T)$  the remainder  $\tilde{\alpha}_r(x, T)$ , called the renormalized intersection local time, admits a jointly continuous extension to all  $(x, T) \in R^{2(r-1)} \times R_+$ .

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