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## **REPRESENTATION OF EUCLIDEAN RANDOM FIELD**

## SHIGEO TAKENAKA

P. Lévy introduced a notion of Brownian motion  $\mathscr{X} \equiv \{X(p); p \in M\}$ with parameter in a metric space (M, d), which is a centered Gaussian system satisfying

 $E|X(p) - X(q)|^2 = d(p, q)$  and X(O) = 0, O being the origin.

In the case of  $M = \mathbb{R}^n$ ,  $S^n$  or the hyperbolic space  $H^n$  with usual geodesic metric, the Brownian motion above has the following representation

(1)  $X(p) = Y(S_p)$ , where  $S_p = \{$ hyperplanes intersect  $Op\}$  and  $\mathscr{Y} = \{Y(\cdot)\}$  is the Gaussian random measure associated with a certain measure  $\mu$  on the set of all hyperplanes.

In this paper we shall discuss Brownian motion that corresponds to a general metric. When the metric d on  $\mathbb{R}^n$  is expressible as d(p, q) = r(|p-q|) where r is a positive increasing continuous function, the Brownian motion is called a Euclidean random field (ERF). The main purpose of this paper is to establish the representations of the form (1) for some important classes of ERFs.

In Section 1 we will consider a simple and basic class of ERFs, denote it by  $\{\mathscr{U}^{\rho}\}$ , and their representations. The covariance function of the field  $\mathscr{U}^{\rho}$  is of finite range and rotationally invariant. The form (1) for the ordinary Brownian motion with parameter  $\mathbb{R}^{n}$  is obtained as the limit  $\rho \to \infty$  of these fields  $\mathscr{U}^{\rho}$ .

In Section 2 the representation of type (1) will be considered for general ERF related to the  $\{\mathscr{U}^{\rho}\}$ . We will start with a special class of ERFs. If  $r(t) = t^{\alpha}$  the random field is called the self-similar Euclidean random field (SERF) of index  $\alpha$ . The representation of SERF of index  $0 < \alpha < 1$  will be written as a superposition of the fields  $\mathscr{U}^{\rho}$ . For general ERF, two sufficient conditions for the existence of the representation of form (1) will be given as conditions on the function  $r(\cdot)$ .

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