

# ON THE CANONICAL FORM OF TURBULENCE

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§ 0. **Introduction.** In K. Itô's paper [1] on the theory of turbulence, the problem to determine the canonical form of the moment tensor of temporally homogeneous and isotropic turbulence, has not been solved. In the present paper, the author will solve the problem by making use of the result of his preceding paper [2]. We shall treat the turbulence in  $R^3$ , but the similar argument is possible in  $R^n$ .

§ 1. **Generalities.** In the theory of *turbulence*, the deviation of the velocity from its mean may be considered as a system of random vectors  $u(t, \mathfrak{X}, \omega) = \langle u_p(t, \mathfrak{X}, \omega) / p = 1, 2, 3 \rangle$ , where  $t \in R^1$  and  $\mathfrak{X} \in R^3$  denote the time and the position respectively and  $\omega \in (\mathcal{Q}, \mathcal{P})$  is the probability parameter; we assume naturally that  $u_p(t, \mathfrak{X}, \omega)$  is  $\mathcal{B}$ -measurable in  $\langle t, \mathfrak{X}, \omega \rangle$  and belongs to  $L^2(\mathcal{Q}, \mathcal{P})$  for any fixed  $\langle p, t, \mathfrak{X} \rangle$ .<sup>1)</sup> We have clearly

$$(1.1) \quad \mathbf{E}_\omega [u_p(t, \mathfrak{X}, \omega)] = 0 \quad (\mathbf{E}_\omega [\dots] \text{ denotes the expectation}).$$

Now we define the moment tensor of the turbulence by

$$(1.2) \quad R_{pq}(t, \mathfrak{X}; s, \mathfrak{Y}) = \mathbf{E}_\omega [u_p(t, \mathfrak{X}, \omega) u_q(s, \mathfrak{Y}, \omega)];$$

then

$$(1.3) \quad R_{pq}(t, \mathfrak{X}; s, \mathfrak{Y}) = R_{qp}(s, \mathfrak{Y}; t, \mathfrak{X}), \text{ and}$$

$$(1.4) \quad \sum_{i,j} \alpha_i \bar{\alpha}_j R_{p_i p_j}(t_i, \mathfrak{X}_i; t_j, \mathfrak{X}_j) \cong 0^{2)} \quad (\alpha_i: \text{complex number}).$$

We consider the turbulence satisfying the following three conditions:

$$(1.5) \quad R_{pq}(t + \tau, \mathfrak{X}; s + \tau, \mathfrak{Y}) = R_{pq}(t, \mathfrak{X}; s, \mathfrak{Y}) \quad (\text{temporally homogeneous});$$

$$(1.6) \quad R_{pq}(t, \mathfrak{X} + \mathbf{a}; s, \mathfrak{Y} + \mathbf{a}) = R_{pq}(t, \mathfrak{X}; s, \mathfrak{Y}) \quad (\text{spatially homogeneous});$$

and

$$(1.7) \quad \sum_{p', q'} k_{p'p} k_{q'q} R_{p'q'}(t, \mathfrak{X}; s, \mathfrak{X} + K(\mathfrak{Y} - \mathfrak{X})) = R_{pq}(t, \mathfrak{X}; s, \mathfrak{Y})$$

for any orthogonal transformation  $K \equiv (K_{pq}/p, q = 1, 2, 3)$  (*isotropic*). We can easily prove by (1.3) that the isotropism implies the homogeneity (1.6). Consequently we get

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<sup>1)</sup> See [1].

<sup>2)</sup> If  $R_{pq}(t, \mathfrak{X}; s, \mathfrak{Y})$  is real-valued and satisfies (1.4), then it satisfies (1.3) automatically.