

# Supergravity, Complex Geometry and $G$ -Structures

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**Abstract.** The geometry of supergravity is studied. New formulations of supergravity are given. The equivalence of different approaches to supergravity is analyzed.

## Introduction

The subject of the present work is the geometrical aspect of supergravity. (We mean the  $N = 1$  supergravity everywhere.) There are various geometrical approaches to the supergravity theory. The most elegant one is due to V. Ogievetsky and E. Sokatchev [1], [2]. In that approach the role of the field is played by a  $(4, 4)$ -dimensional surface in  $\mathbb{C}^{4,2}$  (the complex superspace of the complex dimension  $(4, 2)$ ). Another approach, that by Wess and Zumino, is based upon the concept of the frame<sup>1</sup> fields in the  $(4, 4)$ -dimensional superspace; the frame field in this approach is determined up to a transformation belonging to the Lorentz group. The equivalence between the Ogievetsky–Sokatchev approach and the Wess–Zumino approach was established previously [2] by means of a rather cumbersome consideration and its geometrical background is not always quite clear.

A purpose of the present investigation is to analyze the internal geometry of  $(4, 4)$ -dimensional surfaces embedded into the space  $\mathbb{C}^{4,2}$ . The analysis results first of all in a simpler construction of the action functional than the Ogievetsky–Sokatchev approach [2, 3]. Namely, it was found that the action is simply expressed in terms of the so-called Levi form for the surface. Moreover, the analysis of the geometry in the surface provides manifest way to establish a correspondence between the Ogievetsky–Sokatchev and Wess–Zumino methods.

Our construction is based on the theory of  $G$ -structures[4]. The meaning of this statement is that the surface geometry is given by a frame field which is determined not up to a local Lorentz rotation, as it was in the Wess–Zumino approach, but by the frame field determined up to a transformation belonging to an arbitrary linear group  $G$ . In other words, two frames  $\tilde{E}_A^M(x)$  and  $E_A^M(x)$  are considered as corresponding to the same geometry, if  $\tilde{E}_A^M(x) = g_A^B(x)E_B^M(x)$ , where  $g_A^B(x)$  is a function taking its values in the group  $G$ . The frame fields determining the

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1 We prefer the term “frame” instead of “supertetrad” and “Vielbein” used in the physics literature