

General Integrable Problems of Classical Mechanics

O.I. Bogoyavlenskij*

The Fields Institute for Research in Mathematical Sciences, Waterloo, Ontario, Canada,
N2L 5Z5 and Queen's University, Kingston, Ontario, Canada, K7L 3N6

Received April 4, 1992; in revised form June 29, 1992

Abstract. Several classical problems of mechanics are shown to be integrable for the special systems of coupled rigid bodies, introduced in this work and called C^k -central configurations. It is proven that dynamics of an arbitrary C^k -central configuration in a Newtonian gravitational field with an arbitrary quadratic potential is integrable in the Liouville sense and in the theta-functions of Riemann surfaces. Hidden symmetry of the inertial dynamics of these configurations is disclosed and reductions of the Lagrange equations to the Euler equations on Lie coalgebras are obtained. Reductions and integrable cases of a heavy C^k -central configuration rotation around a fixed point are indicated. Separation of rotations of a space station type orbiting system, being a C^k -central configuration of rigid bodies, is proven. This result leads to the possibility of the independent stabilization of rotations of the rigid bodies in such orbiting configurations.

Contents

1. Introduction and Summary	24
2. Complete integrability of dynamics of a C^1 -central configuration	25
3. General integrable problems of classical mechanics	29
4. Hidden symmetry of the inertial dynamics	31
5. Reductions and integrable cases of C^k -central configuration rotation around a fixed point in the Newtonian gravitational fields with quadratic and linear potentials.	34
6. Multibody integrable generalization of the Neumann problem	35
7. Separation of rotations of an orbiting space station type C^k -central configuration.	36
8. Separation of rotations of CR^n -central configuration of coupled gyrostats	40

* Supported by the Ministry of Colleges and Universities of Ontario and the Natural Sciences and Engineering Research Council of Canada