

## A GLOBAL EXISTENCE THEOREM FOR THE FOUR BODY PROBLEM<sup>1</sup>

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Consider the four body problem of Newtonian mechanics where physical space is either two or three dimensional and where the center of mass of the system is fixed at the origin of the inertial coordinate system. Phase space is 12 dimensional for the planar problem and 18 dimensional for the nonplanar problem. One of the basic questions in the study of the 4 body problem is to determine the size and nature of the set of initial conditions for which the solutions terminate in finite time.

**THEOREM.** *Let  $B$  be the set of initial conditions such that an analytic solution of the 4 body problem exists on the domain  $(-\infty, \infty)$ . The complement of  $B$  is a set of Lebesgue measure zero and first Baire category.*

A similar result is known to hold for the 2 and 3 body problems. This leads to the following statement.

**COROLLARY.** *For almost all initial conditions of the noncollinear 2, 3, or 4 body problems, an analytic solution exists for all values of time.*

The analysis for the 2 and 3 body problem differs sharply from that of the  $n$  body problem for  $n \geq 4$ . It was shown by Painlevé [4] that the only possible singularities for the 2 and 3 body problems are collisions. It was conjectured by J. Littlewood [1], [2] and shown by Saari [5], [6], [7] that for the noncollinear  $n$  body problem the set of initial conditions leading to collisions forms a set of Lebesgue measure zero and first Baire category. Because of these results, the announced theorem follows if the set of initial conditions leading to noncollision singularities can be shown to be small in the above sense. This is what is done. (The existence of noncollision singularities remains an open question. However a recent related result by Mather and McGehee [3] suggests the answer may be in the affirmative. They show that such motion does exist in the collinear four body problem if binary collisions are admitted.)

This analysis is aided by a characterization of noncollision singularities in the  $n$  body problem given in [11], [10], [8]. In particular, for the four body

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