THE EXISTENCE OF NONTRIANGULABLE CUT LOCI

BY DAVID SINGER AND HERMAN GLUCK¹ Communicated by S. S. Chern, March 5, 1976

We continue in this note the description of deformation theorems for geodesic fields on a Riemannian manifold begun in [1], restricting ourselves here to surfaces of revolution and to deformations of metric within this class. Using real and holomorphic Fourier transforms, we obtain in Theorem 2 an explicit formula for the deformation of metric corresponding to a prescribed deflection of geodesics. As an application, we turn again to the structure of the cut locus and prove

THEOREM 1. There exists in \mathbb{R}^3 a strictly convex surface of revolution containing a nonempty open set of points p for which the cut locus C(p) is non-triangulable.

We thank Professors Robert Strichartz, Oscar Rothaus and Emil Grosswald for many helpful conversations.

1. Geodesics on a surface of revolution. Let M be a surface of revolution whose metric is given in polar coordinates on the disc $r \leq 1$ by

$$ds^2 = E(r)dr^2 + r^2 d\theta^2.$$

Then the equation of a geodesic $\gamma(t) = (r(t), \theta(t))$ is given explicitly [4] by

(1)
$$\theta = \theta_0 + \int_{r_0}^r \frac{c\sqrt{E(r)}}{r\sqrt{r^2 - c^2}} dr$$

where the quantity |c| measures the closest approach (in the *r*- θ plane) of the geodesic to the origin. Note that the constant *c* can be computed from any small segment of the geodesic by Clairaut's theorem [4]:

(2)
$$c = r(t) \sin \epsilon(t),$$

where $\epsilon(t)$ is the angle between γ and the meridian θ = constant.

AMS (MOS) subject classifications (1970). Primary 53C20; Secondary 42A68.

¹We thank the National Science Foundation for financial support.

Copyright © 1976, American Mathematical Society