BRANCHED AND FOLDED PARAMETRIZATIONS OF THE SPHERE

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- 0. This study is addressed to the following genre of topological problems. Let Π be a subset of a manifold W and $\varphi: \Sigma \to \Pi$ be a parametrization of Π by a manifold collection Σ . We seek a factorization $\Sigma \to {}^{i}M \to {}^{F}W$, $\varphi = F \circ i$, where i is an inclusion of Σ in a manifold M of the same dimension as W and F is a map in a certain class, such that the invariants of (W, Π, φ) in some reasonable sense determine (M, F, i) up to topological equivalence. For instance, let Π be a closed, but not necessarily simply closed polygon in the complex plane W, Σ the extended real line and F a Schwarz-Christoffel transformation of the Gaussian upper half plane M, such that the image $[\varphi]$ of $\varphi = F|\Sigma$ coincides with Π . Necessary and sufficient conditions for Π to bound a conformal, or more generally, a holomorphic image of a disc were first given by Titus [11]. In view of the Stoïlow-Whyburn [16] theory, it proved more convenient to use light open maps F such that φ is a regular parametrization of a smooth, closed curve Π . If the curve lies in general position, the conditions can be expressed in terms of the Whitney [14]-Titus [10] intersection sequence, which is a combinatorial structure on the set of signed self-intersection points $X(\varphi)$ of Π . In the last decade considerable progress has been made in the direction of relaxing the specialized aspects of the Picard-Loewner problem solved by Titus. We present here some current work, the precise formulation of some technical definitions and proofs have or will appear elsewhere.
- 1. Let M denote a smooth, compact oriented surface, possibly with boundary ∂M , and W a smooth, oriented surface without boundary, but with base point ∞ . We admit smooth maps $F: M \rightarrow W$ which in the vicinity of a point $m \in M$ is locally smoothly equivalent to one of the following canonical plane maps near the origin:

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m \in B is a branch point (w=(x+iy)^v, v>1) of valence v, m \in C is a fold point (w=x^2+iy), m \in K is a cusp point (w=x^3-xy+iy), m \in P=F^{-1}(\infty) is a simple pole point (w=(x+iy)^{-1}), m \in J=\partial M is a border point (w=x+iy, y\geq 0), m \in M_0 is a regular point (w=x+iy).
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