# BRANCHED AND FOLDED PARAMETRIZATIONS OF THE SPHERE 

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0 . This study is addressed to the following genre of topological problems. Let $\Pi$ be a subset of a manifold $W$ and $\varphi: \Sigma \rightarrow \Pi$ be a parametrization of $\Pi$ by a manifold collection $\Sigma$. We seek a factorization $\Sigma \rightarrow{ }^{i} M \rightarrow{ }^{F} W$, $\varphi=F \circ i$, where $i$ is an inclusion of $\Sigma$ in a manifold $M$ of the same dimension as $W$ and $F$ is a map in a certain class, such that the invariants of ( $W, \Pi, \varphi$ ) in some reasonable sense determine ( $M, F, i$ ) up to topological equivalence. For instance, let $\Pi$ be a closed, but not necessarily simply closed polygon in the complex plane $W, \Sigma$ the extended real line and $F$ a Schwarz-Christoffel transformation of the Gaussian upper half plane $M$, such that the image $[\varphi]$ of $\varphi=F \mid \Sigma$ coincides with $\Pi$. Necessary and sufficient conditions for $\Pi$ to bound a conformal, or more generally, a holomorphic image of a disc were first given by Titus [11]. In view of the Stoïlow-Whyburn [16] theory, it proved more convenient to use light open maps $F$ such that $\varphi$ is a regular parametrization of a smooth, closed curve $\Pi$. If the curve lies in general position, the conditions can be expressed in terms of the Whitney [14]-Titus [10] intersection sequence, which is a combinatorial structure on the set of signed self-intersection points $X(\varphi)$ of $\Pi$. In the last decade considerable progress has been made in the direction of relaxing the specialized aspects of the Picard-Loewner problem solved by Titus. We present here some current work, the precise formulation of some technical definitions and proofs have or will appear elsewhere.

1. Let $M$ denote a smooth, compact oriented surface, possibly with boundary $\partial M$, and $W$ a smooth, oriented surface without boundary, but with base point $\infty$. We admit smooth maps $F: M \rightarrow W$ which in the vicinity of a point $m \in M$ is locally smoothly equivalent to one of the following canonical plane maps near the origin:
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\(m \in B\) is a branch point \(\left(w=(x+i y)^{v}, v>1\right)\) of valence \(v\),
\(m \in C\) is a fold point \(\left(w=x^{2}+i y\right)\),
\(m \in K\) is a cusp point \(\left(w=x^{3}-x y+i y\right)\),
\(m \in P=F^{-1}(\infty)\) is a simple pole point \(\left(w=(x+i y)^{-1}\right)\),
\(m \in J=\partial M\) is a border point ( \(w=x+i y, y \geqq 0\) ),
\(m \in M_{0}\) is a regular point \((w=x+i y)\).
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