

FINITE DIMENSIONAL H -SPACES¹

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1. **Introduction.** An H -space is a space X with base point e equipped with a continuous function

$$X \times X \xrightarrow{\mu} X$$

such that $\mu(x, e) = x = \mu(e, x)$ for all $x \in X$. This condition can also be formulated as follows. The *wedge* $X \vee X$ of X is defined by

$$X \vee X = (X \times e) \cup (e \times X) \subset X \times X,$$

and the *folding map* ∇ is given by

$$\nabla(x, e) = x, \quad \nabla(e, x) = x, \quad \nabla: X \vee X \rightarrow X.$$

The H -space condition is then that the following diagram commutes

$$\begin{array}{ccc} X \times X & \xrightarrow{\mu} & X \\ \uparrow i & \nearrow \nabla & \\ X \vee X & & \end{array}$$

where i is the inclusion map. This formulation has the advantage that we can now relax the condition and just require that the diagram be homotopy commutative; i.e., that the maps $\mu \circ i$ and $\mu \circ \nabla$ are homotopic, $\mu \circ i \sim \mu \circ \nabla$.

When one is considering different H -space structures μ, μ' on an H -space X this distinction between the diagram commuting and homotopy commuting is important. But we will be concerned solely

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³ The author felt no need to expand the talk to a survey of H -spaces because of the monograph of Stasheff, " H -spaces from the homotopy point of view," Springer, 1970. The only exceptions are §8, which notes some recent results not covered in the talk (nor in Stasheff's monograph), and a bibliography much more extensive than just references made in the paper.