# ON THE CONVERSE OF THE TRANSITIVITY OF MODULARITY 

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E. H. Moore's theorem on the transitivity of modularity is as follows: Consider the basis ${ }^{1} \mathfrak{N}, \mathfrak{B}, \epsilon$; if a positive hermitian matrix $\epsilon_{0}$ is modular as to $\epsilon \epsilon$, then every vector which is modular as to $\epsilon_{0}$ is modular ${ }^{2}$ as to $\epsilon$ (that is, $\mathfrak{M}_{\epsilon_{0}} \subset \mathfrak{M}_{\epsilon}$ ).

In his doctoral thesis, the author establishes the converse of the preceding theorem as a consequence of the Hellinger-Toeplitz theorem. ${ }^{3}$ In this note, we give a new proof for the converse of the transitivity of modularity, and then deduce the generalized HellingerToeplitz theorem as a corollary. The converse of the transitivity of modularity is, therefore, equivalent to the Hellinger-Toeplitz theorem. We also establish the converse of the transitivity of modularity for matrices, and a theorem on the transitivity of accordance and finiteness.

Theorem I. Consider the basis $\mathfrak{N}, \mathfrak{B}, \boldsymbol{\epsilon}$; and let $\epsilon_{0}$ be a positive hermitian matrix. Then the following assertions are equivalent:
(1) every vector $\mu_{0}$ modular as to $\epsilon_{0}$ is modular as to $\epsilon$;
(2) $\epsilon_{0}$ is modular as to $\epsilon \epsilon_{0}$;
(3) $\epsilon_{0}$ is modular as to $\epsilon \epsilon$.

If one of the preceding conditions is satisfied, the modulus of $\epsilon_{0}$ as to $\epsilon \epsilon$ is equal to the norm of $\epsilon_{0}$ as to $\boldsymbol{\epsilon} \boldsymbol{\epsilon}_{0}$.

In the course of demonstration, we let $\mathfrak{M}_{0}$ denote the space of vectors $\mu_{0}$ modular as to $\epsilon_{0} ; J_{0}$, the integration process based on $\epsilon_{0}$; and $M_{0}$, the modulus as to $\epsilon_{0}$. Similar interpretations are given to the symbols $\mathfrak{M}, J, M$, for the base matrix $\epsilon$. A vector which is finite as to $\epsilon$ is denoted by $\beta$.

If every $\mu_{0}$ is modular as to $\epsilon$, the matrix $\epsilon_{0}$ is of type $\mathfrak{M}_{0} \bar{M}$. Then $J \epsilon_{0} \beta$ is in $\mathfrak{M}_{0}$ for every $\beta$, and $J_{0}\left(J \bar{\beta} \epsilon_{0}\right) \mu_{0}=J \bar{\beta} J_{0} \epsilon_{0} \mu_{0}=J \bar{\beta} \mu_{0}$ for every pair $\beta, \mu_{0}$. Consequently, for every $\beta, M_{0} J \epsilon_{0} \beta$ is equal to the least upper bound of $\left|J \bar{\beta} \mu_{0}\right|$ for all $\mu_{0}$ such that $M_{0} \mu_{0} \leqq 1$, by part (2) of Theorem (41.9) in G.A. Similarly, for every $\mu_{0}$, which is modular as to $\epsilon$ by hypothesis, $M \mu_{0}$ is equal to the least upper bound of $\left|J \bar{\beta} \mu_{0}\right|$

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[^0]:    ${ }^{1}$ E. H. Moore, General Analysis (G.A. for abbreviation), Part I, p. 4, and Part II, p. 84.
    ${ }^{2}$ Theorem (46.4), part (1) in G.A., II, p. 137.
    ${ }^{3}$ Spaces associated with non-modular matrices with applications to reciprocals, Chicago thesis, 1931, pp. 3-9. The same proof is given in G.A., II, p. 193.

