

## A POINCARÉ-HOPF TYPE THEOREM FOR THE DE RHAM INVARIANT

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The Poincaré-Hopf theorem relates the Euler-characteristic of a manifold to the local behavior of a generic vector-field on the manifold in a neighborhood of its zeroes. As a corollary of this, by taking the gradient, one can calculate the Euler-characteristic of a manifold from a local knowledge of a generic map to  $R^1$  around its singular points. We prove an analogue of this theorem for calculation of the de Rham invariant of  $4k + 1$  dimensional orientable manifolds from a map to  $R^2$ .

For  $4k + 1$  dimensional orientable manifolds we have the de Rham invariant  $d(m)$ . This invariant is

(a) the rank of the 2-torsion in  $H_{2k}(M)$ ,

(b)  $\hat{\chi}_Q(M) - \hat{\chi}_2(M) \pmod 2$  where  $\hat{\chi}_F(M)$  is the semicharacteristic of  $M$  with coefficients in  $F$ ,

(c)  $d(M) = [w_2 w_{4k-1}(M), [M]] = [v_{2k} sq^1 v_{2k}(M), [M]]$ ,

where  $w_i(M)$  is the  $i$ th Stiefel-Whitney class and  $v_i$  is the  $i$ th Wu class of  $M$ .

For the equivalence of these definitions see [L-M-P]. The de Rham invariant is important in the theory of surgery; see [M] or [M-S].

**Definition of the local invariant.** Let  $M^m, N^n$  be  $C^\infty$  manifolds. Let  $C^\infty(M, N)$  be the space of  $C^\infty$  maps from  $M$  to  $N$  topologized with the  $C^\infty$  topology. Within  $C^\infty(M, N)$  we have a dense (in fact residual) subset  $G(M, N)$  of maps which are generic in the sense of Thom-Boardman [B] and satisfy the normal crossing condition [G-G]. This second condition is essentially that  $f$  is in general position as a map of its singularity submanifolds to  $N$ .

Let  $f \in G(M, R^2)$ ; then  $df$  is of rank 2 except on a collection of disjoint closed curves in  $M$ , the singular set of  $f, S_1(f)$ . At points of  $S_1(f)$ ,  $df$  is of rank 1. Restricted to  $S_1(f)$   $f$  is an immersion except at a finite set of points,  $S_{1,1}(f)$ , the cusp points of  $f$ .  $S_1(f) - S_{1,1}(f) = S_{1,0}(f)$  is the set of fold points of  $f$ . Suppose  $x \in S_{1,0}(f)$  then we can choose coordinates  $x_1, \dots, x_n$  around  $x$  and coordinates  $y_1, y_2$  around  $f(x)$  so that

$$f(x_1, \dots, x_n) = (x_1, x_2^2 + x_3^2 + \dots + x_k^2 - x_{k+1}^2 - \dots - x_n^2).$$

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