for a beginner. This book is an important and valuable addition to a growing secondary literature, which is perhaps best absorbed by wandering back and forth from one book to another and thence to the primary sources as quickly as possible.

We wish to add our thanks and compliments to J. N. Crossley for translating this work into (very readable) English.

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Linear estimation and stochastic control, by M. H. A. Davis, Wiley, New York, 1977, xii + 224 pp., \$14.95.

In this monograph the author gives a highly readable introduction to two topics, namely the Kalman filter and the stochastic linear regulator problem. These two topics have been called the "bread and butter" of modern stochastic systems theory. They have the fortunate feature that the mathematical techniques used are elegant, while at the same time the results have been quite widely used in engineering and other applications. Rather modest background is needed to read the book. The equivalent of introductory real-analysis, probability, and some familiarity with elementary linear systems theory should suffice.

The linear estimation problem is as follows. Given random variables X, Y, for  $s \in S$ , all of zero mean and finite variance, find the approximation  $\hat{X}$  to X