

MANIFOLDS OF RIEMANNIAN METRICS WITH PRESCRIBED SCALAR CURVATURE

BY ARTHUR E. FISCHER AND JERROLD E. MARSDEN¹

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1. Introduction. Throughout, M will denote a C^∞ compact connected oriented n -manifold, $n \geq 2$. Let $\rho: M \rightarrow \mathbb{R}$ be a C^∞ function, \mathcal{M} the space of C^∞ riemannian metrics on M and

$$\mathcal{M}_\rho = \{g \in \mathcal{M} : R(g) = \rho\}$$

where $R(g)$ is the scalar curvature of g . As in Ebin [3], a superscript s will denote objects in the corresponding Sobolev space, $s > n/2 + 1$ (one can also treat $W^{s,p}$ spaces in the same way), and we also allow $s = \infty$ so $\mathcal{M}^\infty = \mathcal{M}$. Sign conventions on curvatures are as in Lichnerowicz [10].

Two of our main results follow:

THEOREM 1. *If ρ is not identically zero or a positive constant, then \mathcal{M}_ρ^s is a smooth submanifold of \mathcal{M}^s .*

We can also treat the case $\rho \equiv 0$. Let \mathcal{F}^s denote the set of flat metrics in \mathcal{M}^s . Then we have

THEOREM 2. *Assume $\mathcal{F}^s \neq \emptyset$. Writing $\mathcal{M}_0^s = (\mathcal{M}_0^s \setminus \mathcal{F}^s) \cup \mathcal{F}^s$, \mathcal{M}_0^s is the disjoint union of closed submanifolds.*

REMARK. If $\dim M = 2$, $\mathcal{M}_0^s = \mathcal{F}^s$, and if $\dim M = 3$, the hypothesis that $\mathcal{F}^s \neq \emptyset$ can be dropped.

The proof of Theorem 1 also allows us to conclude that a solution h of the linearized equations $DR(g_0) \cdot h = 0$ is tangent to a curve of exact solutions of $R(g) = \rho$ through a given solution g_0 , provided ρ is not a constant ≥ 0 . In the terminology of [4] we say the equation $R(g) = \rho$ is *linearization-stable* at g_0 . From Theorem 3 below the equation $R(g) = 0$ is still linearization-stable about a solution g_0 provided $\text{Ric}(g_0)$ is not identically zero.

For the singular case $\rho = 0$, Theorem 2 incorporates an isolation theorem inspired by the work of Brill and Deser [2], namely, that the flat metrics are isolated solutions of $R(g) = 0$. As a corollary one has: *If $g(t)$ is a*

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