THE HEAVISIDE OPERATIONAL CALCULUS*

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The Heaviside operational calculus is a systematic method, originated and developed by Oliver Heaviside, for the solution of systems of linear differential equations with constant coefficients, and linear partial differential equations of the type of the *wave equation*. Its important applications in mathematical physics are to the dynamics of small oscillations, the Fourier theory of heat flow and to electrical transmission theory. It was, in fact, in connection with problems of the latter class that the operational calculus was developed, and in the solution of such problems it is an instrument of remarkable directness, simplicity and power.[†]

The operational calculus may be described with sufficient generality for our present purposes, in connection with the solution of the system of linear differential equations

(1)
$$\begin{cases} a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \cdots + a_{1n}x_n = f_1(t) , \\ a_{21}x_1 + a_{22}x_2 + a_{23}x_3 + \cdots + a_{2n}x_n = f_2(t) , \\ \vdots \\ a_{n1}x_1 + a_{n2}x_2 + a_{n3}x_3 + \cdots + a_{nn}x_n = f_n(t) , \end{cases}$$

where the coefficient a_{jk} has the form

(2)
$$a_{jk} = \alpha_{jk} + \beta_{jk} \frac{d}{dt} + \gamma_{jk} \frac{d^2}{dt^2} + \cdots$$

 $\alpha, \beta, \gamma, \cdots$ being constants. We require the solution for x_1, x_2, \cdots, x_n for the following boundary conditions: The known functions f_1, \cdots, f_n and the dependent variables x_1, \cdots, x_n are identically zero for t < 0. In the language of dynamics, the "forces" f_1, \cdots, f_n are applied to a system

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[†] For a brief discussion of the Heaviside operational calculus from the point of view adopted in this paper, see Carson, *The Heaviside Operational Calculus*, BELL SYSTEM TECHNICAL JOURNAL, Nov., 1922.