Here  $e_2 \oplus e_3 \neq e_3 \oplus e_2$ .

$\overline{\mathrm{III}}_{b}.$	Ð	$e_1$	$e_2$	<i>e</i> <sub>3</sub>	$\odot$	$e_1$	$e_2$	$e_3$
	$e_1$	$e_1$	$e_2$	e <sub>3</sub>	$e_1$	$e_1$	$e_1$	<i>e</i> <sub>1</sub>
	$e_2$	$e_2$	$e_2$	$e_2$	$e_2$	$e_1$	$e_2$	$e_2$
	$e_3$	$e_3$	$e_2$	$e_3$	$e_3$	$e_1$	$e_3$	$e_3$
Here $e_2 \odot$	$e_3 \neq e_3$	• e	82.					

UNIVERSITY OF CALIFORNIA, March, 1916.

## NOTE ON REGULAR TRANSFORMATIONS.

BY DR. L. L. SILVERMAN.

LET u(x) be bounded and integrable,  $0 \leq x$ , and k(x, y) integrable in y for each x,  $0 < y \leq x$ ; then the transformation\*

(1) 
$$v(x) = \alpha u(x) + \int_0^x k(x, s) u(s) ds$$

is regular if

 $\lim u(x)$  $x = \infty$ 

implies the existence of

$$\lim_{x=\infty} v(x)$$

and the equality of the limits. The transformation (1), which depends on the number  $\alpha$  and on the function k(x, y), will be denoted by the symbol  $[\alpha; k(x, y)]$ . Examples of regular transformations are given by [1; 0], which is the identical transformation, and [0; 1/x], which corresponds to the first Hölder mean. In a forthcoming paper† the author discusses conditions on  $\alpha$  and k(x, y) for the regularity of the transformation<sup>‡</sup> (1), and proves the following theorem:

THEOREM 1. A sufficient condition that k(x, y) defined,  $0 < y \leq x$ , and integrable in y for each x, correspond to a

\* It is assumed that the improper integral converges; the lower limit of integration is taken zero for convenience.

† Transactions, vol. 17 (1916). ‡ The function k(x, y) in (1) is  $(1 - \alpha)$  times the function k(x, y) in the article referred to.

|| See Theorem III in the article referred to; the numbers a and b of that theorem are here replaced by 0 and a respectively. The right-hand member of the last condition is  $1 - \alpha$  instead of unity; see preceding footnote.