

## A CLASS OF VARIATIONALLY COMPLETE REPRESENTATIONS

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### Introduction

Let  $M$  be a complete Riemannian manifold on which a compact connected Lie group  $K$  acts as a group of isometries. If  $M = \mathbf{R}^n$ , then  $K$  has a fixed point, hence we lose no generality in assuming for this case that the action of  $K$  is a linear orthogonal representation.

Bott and Samelson [5] have defined the concept of variational completeness. Roughly speaking, the action of  $K$  on  $M$  is variationally complete if it produces enough Jacobi fields along geodesics to determine the multiplicities of focal points to the  $K$ -orbits. This notion remains interesting and useful for the case  $M = \mathbf{R}^n$  (e.g., cf. [4], [5]).

In [6] we formulated the notion of a " $K$ -transversal domain". This is a closed connected flat totally geodesic imbedded submanifold  $T \subset M$  which meets all  $K$ -orbits and is orthogonal to every  $K$ -orbit at each point of intersection. We showed that the existence of a  $K$ -transversal domain implies variational completeness, and deduced strong structure theorems for the singular set, the Weyl group, and the Bott-Samelson  $K$ -cycles. For  $M = \mathbf{R}^n$ , such a  $T$  is evidently a linear subspace.

The theorems of [6], applied to the case  $M = \mathbf{R}^n$ , show that those orthogonal representations of  $K$  which admit a  $K$ -transversal domain bear striking resemblances to the isotropy representations associated to compact symmetric spaces (hereafter referred to as  $s$ -representations). Indeed,  $s$ -representations constitute the principal class of known examples. This suggests that further such analogies should be sought and exploited, the ultimate aim being a complete structure theory and classification.

We will present here three theorems which advance the above program. For this purpose we employ a linear map (due to Kostant)

$$R: A^2(\mathbf{R}^n) \rightarrow \mathfrak{k} = \text{Lie algebra of } K,$$

which will be called the curvature tensor of the representation.  $R$  is defined for an arbitrary orthogonal representation of  $K$ , and in the case of an  $s$ -representation it will actually coincide with the Riemann tensor [9]. Usually

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Communicated by H. Samelson, November 2, 1970.