

$\text{Gr} \implies \text{SW}$
**FROM PSEUDO-HOLOMORPHIC CURVES
 TO SEIBERG-WITTEN SOLUTIONS**

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The Seiberg-Witten invariants were defined by Witten [24] for any compact, oriented 4-manifold with $b_+^2 > 1$; after the choice of an orientation for a certain determinant line, they constitute a map, SW, from the set \mathcal{S} of $\text{Spin}^{\mathbb{C}}$ structures on X to \mathbb{Z} which depends only on the diffeomorphism type of X . Roughly speaking, SW is computed from a weighted count of solutions to a natural, non-linear system of differential equations on X . (See [9], [8] and [12].) As remarked in [17], a symplectic 4-manifold has a canonical identification $\mathcal{S} \approx H^2(X; \mathbb{Z})$; and with this identification understood, the Seiberg-Witten invariant on a symplectic X can be thought of as mapping $H^2(X; \mathbb{Z})$ to \mathbb{Z} .

Meanwhile, a symplectic 4-manifold has a second natural map, Gr: $H^2(X; \mathbb{Z}) \rightarrow \mathbb{Z}$, called the Gromov invariant. The latter invariant is defined in [18]. To a first approximation, Gr assigns to a class $e \in H^2(X; \mathbb{Z})$ a certain weighted count of the symplectic submanifolds of X whose fundamental class is Poincaré dual to e . The following theorem was announced in [17]:

Theorem 1. *Let X be a compact, symplectic 4-manifold with $b_+^2 > 1$. Use the symplectic structure to orient X , to define the Seiberg-Witten invariants of X as a map $\text{SW} : H^2(X; \mathbb{Z}) \rightarrow \mathbb{Z}$, and also to define the Gromov invariant $\text{Gr} : H^2(X; \mathbb{Z}) \rightarrow \mathbb{Z}$. Then $\text{Gr} = \text{SW}$.*

As remarked in [17], there are essentially three parts to the proof of this theorem. The first part appears in [19] where it was shown how

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