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1. Notation and results. Extending the usage of language in Galois cohomology, T. Ono defined "Hasse principle" for any group G (cf. [2]). We know that the Hasse principle holds for G = abelian, dihedral, quatenion,  $PSL_2(\mathbf{Z})$ ,  $PSL_2(\mathbf{F}_p)$  (cf. [2]), free groups ([3]), symmetric groups and alternating groups ([4]).

Let D be an Euclidean domain (for examples  $D = \mathbf{Z}$ ,  $D = \mathbf{F}_p$ ). Put  $\varepsilon = (-1)^{n-1}$  and we define in  $SL_n(D)$ 

$$S = \begin{pmatrix} 0 & \dots & \dots & 0 & \varepsilon \\ 1 & \ddots & & & 0 \\ 0 & \ddots & \ddots & & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & \dots & 0 & 1 & 0 \end{pmatrix},$$

$$T_{\mu} = \begin{pmatrix} 1 & \mu & 0 & \dots & 0 \\ 0 & \ddots & 0 & & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & & \ddots & \ddots & 0 \\ 0 & \dots & \dots & 0 & 1 \end{pmatrix}, \ T = T_{1}.$$

Then  $SL_n(\mathbf{Z})$  is generated by S and T (cf.[1]). Similarly using Eucledian algorithm we can prove that  $SL_n(D)$  is generated by S and  $\{T_{\mu} \mid \mu \in D\}$ . Using this fact, T. Ono proved that  $SL_2(D)$  enjoys the Hasse principle (unpublished). In this paper, we shall prove more generally the following

**Theorem.** For any natural number n,  $SL_n(D)$ and  $PSL_n(D)$  enjoy the Hasse principle.

M. Mazur [5] noticed that f(x) is a cocycle iff g(x) = f(x)x is an endomorphism of G, f(x) is a local coboundary iff  $g(x) \sim x$  (conjugate in G) for each  $x \in G$  and f(x) is a global coboundary iff g(x) is an inner automorphism. Therefore "Hasse principle" is equivalent to say that "any endomorphism of G which satisfies  $g(x) \sim x$  for each  $x \in G$  must be an inner automorphism".

2. Proof of the theorem. Let g(x) be an endomorphism which satisfies  $g(x) \sim x$  for each  $x \in G$ . We may assume g(S) = S,  $g(T) = M^{-1}TM$ 

where

$$M = \begin{pmatrix} a_1 & a_2 & \dots & a_n \\ b_1 & b_2 & \dots & b_n \\ \vdots & \vdots & & \vdots \\ g_1 & g_2 & \dots & g_n \end{pmatrix} = \begin{pmatrix} \boldsymbol{a} \\ \boldsymbol{b} \\ \vdots \\ \boldsymbol{g} \end{pmatrix},$$
$$M^{-1} = \begin{pmatrix} x_1 & & \\ x_2 & & \\ \vdots & * & \\ x_n & & \end{pmatrix}.$$

Then

$$g(T) = E + M^{-1}E_{12}M = \begin{pmatrix} 1 + x_1b_1 & x_1b_2 & \dots & x_1b_n \\ x_2b_1 & 1 + x_2b_2 & \dots & x_2b_n \\ \vdots & \vdots & & \vdots \\ x_nb_1 & x_nb_2 & \dots & 1 + x_nb_n \end{pmatrix}.$$

where  $E_{ij}$  is the matrix unit whose ij-element is 1 and the other elements are 0. Put

(1) 
$$\tilde{M} = \begin{pmatrix} v_1 \\ b \\ v_3 \\ v_4 \\ \vdots \\ v_n \end{pmatrix} = \begin{pmatrix} b_2 & b_3 & b_4 & \dots & b_n & \varepsilon b_1 \\ b_1 & b_2 & b_3 & \dots & b_{n-1} & b_n \\ \varepsilon b_n & b_1 & b_2 & \dots & b_{n-2} & b_{n-1} \\ \varepsilon b_{n-1} & \varepsilon b_n & b_1 & \dots & b_{n-3} & b_{n-2} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \varepsilon b_3 & \varepsilon b_4 & \varepsilon b_5 & \dots & b_1 & b_2 \end{pmatrix}.$$

Then after a little calculation we have

$$|xE - Sg(T)| =$$

$$x^{n} - \sum_{i=1}^{n-1} (x_{1}b_{i+1} + x_{2}b_{i+2} + \dots + x_{n-i}b_{n})$$

$$+\varepsilon x_{n-i+1}b_{1} + \dots + \varepsilon x_{n}b_{i})x^{n-i} - \varepsilon =$$

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