## 247. On an Algebraic Model for von Neumann Algebras. II

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1. In the previous paper [6], we have introduced algebraic models of von Neumann algebras as a non-commutative extension of algebraic models of measures due to Dinculeanu and Foiaş [2], and we have proved that an algebraic model determines the algebra structure up to isomorphisms (unfortunately, a von Neumann algebra can not decide an algebraic model within isomorphisms).

In an another note [3], Dinculeanu and Foiaş, introduced an another concept, that is, algebraic models for measure preserving transformations. In §2, we shall extend the above notion to an automorphism of von Neumann algebra. In §3, we shall present a measure system which is an algebraic model for the crossed product of a von Neumann algebra by an automorphism group. And in §4, we shall present an algebraic ergodic system which is an algebraic model for a certain automorphism of the crossed product.

Dinculeanu and Foiaş [3] introduced also the notion of discrete models of measures and established several important theorems. A non-commutative variant of discrete models gives a characterization of group von Neumann algebras. We shall discuss discrete models in a subsequent paper.

Throughout the note, we shall use the terminology of [4] without explanations.

2. Let  $(\Gamma, \varphi)$  be a measure system introduced in [6], U be an isomorphism of  $\Gamma$  into  $\Gamma$ . Then we shall say  $(\Gamma, U, \varphi)$  an algebraic ergodic system if

$$\varphi(U\gamma) = \varphi(\gamma)$$
 for every  $\gamma \in \Gamma$ .

Two algebraic ergodic systems  $(\Gamma, U, \varphi)$  and  $(\varDelta, V, \varphi)$  are called *isomorphic* if there exists an isomorphism  $\phi$  of  $\Gamma$  into  $\varDelta$  such that

(i) 
$$\varphi(\gamma) = \psi(\phi\gamma)$$

and

(ii) 
$$\phi U = V \phi$$
.

Definition 1. Let  $(\Gamma, \varphi)$  be an algebraic model for a von Neumann algebra  $\mathcal{A}$  with a generating vector x and U an isomorphism of  $\Gamma$ into  $\Gamma$ . Let  $\alpha$  be an automorphism of  $\mathcal{A}$ . An algebraic ergodic system  $(\Gamma, U, \varphi)$  is an algebraic model for  $\alpha$  if

$$J(U\gamma) = J(\gamma)^{\alpha}$$
 for  $\gamma \in \Gamma$ ,