## 150. 5-dimensional Orientable Submanifolds of R<sup>7</sup>. II

By Minoru KOBAYASHI

Department of Mathematics, Josai University, Saitama

(Comm. by Kinjirô KUNUGI, M. J. A., Oct. 13, 1969)

1. Introduction. In our previous paper [4], we showed that, using the vector cross product induced by Cayley numbers, any 5-dimensional orientable submanifold M of  $R^{7}$  admits an almost contact structure.

In this paper, denoting this almost contact structure by  $(\emptyset, \xi, \eta)$ , we shall study the torsion of  $\emptyset$ . First, we shall prove that if M is totally geodesic then the torsion of  $\emptyset$  vanishes identically (Theorem 1). Secondly, we consider the converse problem. Unfortunately, this is not true in general. But we shall prove that if M is totally umbilical, then the vanishing of the torsion of  $\emptyset$  implies that M is totally geodesic (Theorem 2).

2. Basic informations.

(a) Almost contact manifolds.

Let *M* be a (2n+1)-dimensional  $C^{\infty}$  manifold with an almost contact structure  $(\emptyset, \xi, \eta)$ . Then we have, by definition,

(1)  $\eta(\xi) = 1,$ 

where I is the identity transformation field.

By above relations, it can be easily shown that the rank of  $\emptyset$  is 2n.

We denote the associated Riemannian metric of  $(\emptyset, \xi, \eta)$  by  $\langle , \rangle$ . Then it satisfies

(4)

 $\eta{=}{\langle{arsigma},{\,\cdot\,
angle},}$ 

(5)  $\langle \emptyset X, \emptyset Y \rangle = \langle X, Y \rangle - \eta(X)\eta(Y)$ , for any vector fields X, Y on M. The tensor N(X, Y) defined by

(6) 
$$N(X, Y) = [X, Y] + \emptyset[\emptyset X, Y] + \emptyset[X, \emptyset Y] - [\emptyset X, \emptyset Y] - \{X \cdot \eta(Y) - Y \cdot \eta(X)\}\xi$$

is called the *torsion* of  $\emptyset$  and M is called *normal* if N vanishes identically.

(b) The vector cross product on  $\mathbb{R}^{7}$ .

The vector cross product on  $R^{\tau}$  is a linear map  $P: V(R^{\tau}) \times V(R^{\tau}) \rightarrow V(R_{\tau})$  (writing here  $P(\vec{X}, \vec{Y}) = \vec{X} \otimes \vec{Y}$ ) satisfing the following conditions:

- (7)  $\bar{X}\otimes\bar{Y}=-\bar{Y}\otimes\bar{X},$
- (8)  $\langle \vec{X} \otimes \vec{Y}, \vec{Z} \rangle = \langle \vec{X}, \vec{Y} \otimes \vec{Z} \rangle,$