

## 186. Realization of Irreducible Bounded Symmetric Domain of Type (VI)

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(Comm. by Kunihiko KODAIRA, M. J. A., Dec. 12, 1969)

1. This is a continuation of our preceding note [3] which appeared in these Proceedings. We shall present here, without proof, the *canonical bounded model* of the irreducible bounded symmetric domain of exceptional type (VI) in the sense of [4].

As was pointed out in [4], we need at first to describe explicitly the irreducible representation of the complex simple Lie algebra of type  $E_7$ , which is of the lowest degree, 56. Such a representation was previously discussed by several authors, for instance by H. Freudenthal; however a presentation of that representation which suited our purpose was recently given by R. B. Brown [1] for the first time. His result will be, therefore, briefly reproduced in the following sections 2-3. As for the notation we refer the reader to [3], [4].

2. Let  $\mathfrak{S}$  denote the exceptional simple Jordan algebra as described in [1]-[3]; namely  $\mathfrak{S}$  is the totality of the (3,3)-hermitian matrices over the complex Cayley numbers  $\mathbb{C}$ . The canonical non-degenerate inner-product  $(u, v)$  in  $\mathfrak{S}$  will be introduced by  $(u, v) = \text{Trace}(u \circ v)$ ,  $(u, v \in \mathfrak{S})$  (cf. [1], [2], [5]), for which we consider the dual  $\mathfrak{S}^*$  of  $\mathfrak{S}$  and will identify hereafter  $\mathfrak{S}^*$  with  $\mathfrak{S}$  through this inner-product. Now we introduce a 56-dimensional complex vector space  $V$  by putting (1)

$$V = V_1 \oplus V_2 \oplus V_3 \oplus V_4,$$

where both  $V_1$  and  $V_4$  are of 1-dimension and  $V_2 = \mathfrak{S}^*$ ,  $V_3 = \mathfrak{S}$ . The element  $x$  of  $V$  is then written as

$$(2) \quad x = \alpha f_1 + u^* + v + \beta f_2; \quad \alpha, \beta \in \mathbb{C}, \quad u, v \in \mathfrak{S},$$

where  $f_1, f_2$  denote, respectively, the generators of  $V_1, V_4$  and  $u^* \in \mathfrak{S}^*$  is defined by  $u^*(v) = (u, v)$  for all  $v \in \mathfrak{S}$ . After R. B. Brown we introduce in  $V$  a non-associative algebra structure  $\mathfrak{B}$  by the following rule:

- i)  $f_i f_i = f_1$  ( $i=1, 2$ ),  $f_1 f_2 = f_2 f_1 = 0$
- ii)  $f_1 u = \frac{1}{3} u$ ,  $f_2 u = \frac{2}{3} u$ ;  $f_1 v^* = \frac{2}{3} v^*$ ,  $f_2 v^* = \frac{1}{3} v^*$
- iii)  $u f_1 = 0$ ,  $u f_2 = u$ ;  $v^* f_1 = v^*$ ,  $v^* f_2 = 0$
- iv)  $u v^* = (u, v) f_1$ ,  $u^* v = (u, v) f_2$
- v)  $u v = 2(u \times v)^*$ ,  $u^* v^* = 2(u \times v)$

$(u, v \in \mathfrak{S})$ , where the crossed product  $u \times v$  in  $\mathfrak{S}$  is given through  $(u \times v, w) = 3(u, v, w)$  (for  $w \in \mathfrak{S}$ ), the right hand side being the tri-linear form on  $\mathfrak{S}$  obtained by linearizing the cubic form on  $\mathfrak{S}$  (see, [1], [5]):