## 50. Cauchy Problem for Degenerate Parabolic Equations

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1. Introduction. We consider the Cauchy problem for the equation

(1.1) 
$$\partial_t u - \sum_{j,k=1}^n \partial_{x_j} (a_{jk}(x,t) \partial_{x_k} u) - \sum_{j=1}^n b_j(x,t) \partial_{x_j} u - c(x,t) u$$
$$= \partial_t u - A u = f,$$

(x, t) in  $\mathbb{R}^n \times [0, \infty)$  with the initial-value

(1.2) 
$$u(x, 0) = u_0(x),$$

where  $a_{jk}(x, t)$ ,  $b_j(x, t)$ , c(x, t) are real-valued smooth functions. We assume that  $(a_{jk})_{1 \le j \le n, 1 \le k \le n}$  is symmetric and satisfies the condition: for any  $(x, t) \in \mathbf{R}^n \times [0, \infty)$ 

(1.3) 
$$\sum_{j,k=1}^{n} a_{jk}(x,t)\xi_{j}\xi_{k} \ge 0 \quad \text{for all } \xi \in \mathbf{R}^{n}.$$

O. A. Oleinik has treated this problem (see [3] and [4]). Her method consists of the following procedure (elliptic regularization): Instead of (1.1), the following equations (depending on a positive parameter  $\varepsilon$ ) in  $G = \mathbf{R}^n \times [0, T]$ 

(1.4)  $\partial_t u - \varepsilon \Delta u - Au = f$ are considered. Let  $u_{\varepsilon}$  be the solution of (1.4) with the given initialvalue  $u_0(x) \in L^2(\mathbb{R}^n)$  and  $f(x, t) \in L^2(G)$ . Then it is shown that  $\{u_{\varepsilon}(x, t)\}$ is bounded in  $L^2(G)$ . Then a weak limit of them, as  $\varepsilon \to +0$ , gives the desired solution  $u(x, t) \in L^2(G)$ . The uniqueness of the solution is proved. She also proved the smoothness of u, assuming the smoothness of  $u_0$  and f.

Contrary to the above point of view, we regard (1.1) as evolution equation. More precisely, we want to show the existence of the unique solution  $u(x,t) \in \mathcal{C}_{t}^{0}(L^{2}) \cap \mathcal{C}_{t}^{1}(\mathcal{D}_{L^{2}}^{\prime 2})$  of (1.1)–(1.2) for any  $f(x,t) \in \mathcal{C}_{t}^{0}(L^{2})$ and any initial-value  $u_{0}(x) \in L^{2}$ .\*)

Our approach is based on the semi-group theory. Instead of elliptic regularization, we use Friedrichs' mollifier. Its property (see

<sup>\*)</sup> Throughout this paper, we use the following notation:  $x = (x_1, \dots, x_n)$ .  $\partial_t = \partial/\partial t$ ,  $\partial_j = \partial x_j = \partial/\partial x_j$ ,  $\partial_x^* = \partial_1^{y_1} \dots \partial_n^{y_n}$ , where  $\nu = (\nu_1, \dots, \nu_n)$ .  $L^2 = L^2(\mathbb{R}^n)$ .  $u(x) \in \mathcal{D}_{L^2}^m$  means that its derivatives (in the sense of distribution)  $\partial_x^* u$  up to order m belong to  $L^2$ .  $\mathcal{D}_{L^2}^{(m)}$  is the dual space of  $\mathcal{D}_{L^2}^m$  and sometimes we denote it by  $\mathcal{D}_{L^2}^{-m}$ .  $\varphi(x) \in \mathcal{B}^m$  means that its derivatives  $\partial_x^* \varphi$  up to order m are continuous and bounded in  $\mathbb{R}^n$ .  $f(t) \in \mathcal{E}_t^k(\mathcal{D}_{L^2}^m \text{ (or } \mathcal{B}^m))$  means that  $t \to f(t) \in \mathcal{D}_{L^2}^m$  (or  $\mathcal{B}^m$ ) is continuously differentiable up to order k.