

40. On the Euler-Poisson-Darboux Equation and the Toda Equation. I

By Yoshinori KAMETAKA

Department of Applied Mathematics, Faculty of Engineering,
Ehime University

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§1. Summary. The Toda equation with two time variables

$$(1.1) \quad XY \log t_n = t_{n+1}t_{n-1}/t_n^2 \quad \left(X = \frac{\partial}{\partial x}, Y = \frac{\partial}{\partial y}, t_n = t_n(x, y) \right)$$

can be solved using solutions of the Euler-Poisson-Darboux equations ([1])

$$(1.2) \quad (XY + (\alpha + \beta - 1 - 2n)\varphi^{-1}X - (n - \alpha)(n - \beta)\varphi^{-2})u_n = 0,$$

where $\varphi = x - y$. Rational solutions, Gauss hypergeometric function solutions and solutions which can be expressed by hypergeometric functions with two variables (Appell hypergeometric functions F_1, F_2 and F_3 are included) are obtained. K. Okamoto ([2]) also found these hypergeometric solutions.

§2. Bäcklund transformation. When t_n satisfies (1.1)

$$(2.1) \quad r_n = XY \log t_n, \quad s_n = Y \log t_{n-1}/t_n$$

satisfies

$$(2.2) \quad Yr_n = r_n(s_n - s_{n+1}), \quad Xs_n = r_{n-1} - r_n.$$

Eliminating s_n we have

$$(2.3) \quad XY \log r_n = r_{n+1} - 2r_n + r_{n-1}.$$

This form of the Toda equation was found by G. Darboux ([1]). As was shown in our previous work ([3])

$$(2.4) \quad t_n = F(n)\varphi^{-f(n)},$$

where $f(n) = (n - \alpha)(n - \beta)$, α and β are arbitrary constants,

$$F(n+1)F(n-1)/F(n)^2 = -f(n), \quad F(0) = F(1) = 1,$$

satisfies the Toda equation (1.1). Corresponding

$$(2.5) \quad r_n = -f(n)\varphi^{-2}, \quad s_n = (\alpha + \beta + 1 - 2n)\varphi^{-1}$$

satisfies the Toda equation (2.2). This simple important solution r_n was first found by G. Darboux ([1]). For these special solutions we put

$$(2.6) \quad M_n = XY + (\alpha + \beta - 1 - 2n)\varphi^{-1}X - (n - \alpha)(n - \beta)\varphi^{-2}, \\ X_n = ((n - \alpha)(n - \beta))^{-1}\varphi^2X, \quad Y_n = Y + (\alpha + \beta - 1 - 2n)\varphi^{-1}.$$

Define

$$(2.7) \quad T = \{u_n; M_0u_0 = 0, u_{n+1} = Y_nu_n (n \geq 0), u_{n-1} = X_nu_n (n \leq 0)\}.$$

Theorem 2.1 (Bäcklund transformation). *If $u_n \in T$ then we have $M_nu_n = 0$, $u_{n+1} = Y_nu_n$, $u_{n-1} = X_nu_n$ ($n = 0, \pm 1, \pm 2, \dots$) and $\tau_n = u_n t_n$*