

**203. On the Stability of Solutions of  
Some Non-Autonomous Differential  
Equations of the Third Order**

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**1. Introduction.** In this note we investigate the asymptotic stability in the large, as  $t \rightarrow \infty$ , of the zero solution of the differential equation

$$(1.1) \quad \ddot{x} + \psi(t, x, \dot{x}, \ddot{x}) + \phi(t, x, \dot{x}) + c(t)f(x) = 0,$$

where  $\psi$ ,  $\phi$ ,  $f$  and  $c$  are real valued functions. The dots indicate differentiation with respect to  $t$  and all solutions considered are assumed real.

In [4] K. E. Swick established conditions under which all solutions of the non-autonomous equations

$$(1.2) \quad \ddot{x} + p(t)\dot{x} + q(t)g(\dot{x}) + r(t)h(x) = 0$$

$$(1.3) \quad \ddot{x} + f(t, x, \dot{x})\ddot{x} + q(t)g(\dot{x}) + r(t)h(x) = 0$$

tend to the zero solution as  $t \rightarrow \infty$ .

Recently, in [2] T. Hara also obtained some conditions under which all solutions of the equation

$$(1.4) \quad \ddot{x} + a(t)\ddot{x} + b(t)\dot{x} + c(t)x = 0$$

$$(1.5) \quad \ddot{x} + a(t)f(x, \dot{x})\ddot{x} + b(t)g(x, \dot{x})\dot{x} + c(t)x = 0$$

tend to the zero solution as  $t \rightarrow \infty$ .

To prove the following theorems (see 3) we construct a Liapunov function using the well-known techniques which are frequent in [3].

**2. Auxiliary Lemmas.** Consider the system of differential equation

$$(2.1) \quad \dot{X} = F(t, X)$$

where  $X = (x_1, \dots, x_n)$ ,  $F(t, 0) = 0$  for  $t \in I = [0, +\infty)$  and  $F(t, X)$  is continuous in  $I \times R^n$ .

The following lemmas are well-known and play the essential role to prove the theorems, see [5] (Th. 8.1, Th. 10.2, Th. 14.2).

**Lemma 2.1.** *Suppose that there exists a Liapunov function  $V(t, X)$  defined on  $0 \leq t < \infty$ ,  $\|X\| < H (H > 0)$ , which satisfies the following conditions; (i)  $V(t, 0) \equiv 0$ , (ii)  $w_1(\|X\|) \leq V(t, X)$ , where  $w_1(r)$  is a continuous increasing, positive definite function, (iii)  $\dot{V}_{(2.1)}(t, X) \leq 0$ . Then, the zero solution  $X(t) \equiv 0$  of the system (2.1) is stable.*

**Lemma 2.2.** *Suppose that there exists a Liapunov function  $V(t, X)$*