

### 123. On the Spectra of Some Non-linear Operators. II

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In this note, we continue the study on the Hammerstein operators whose spectra contain no intervals. We denote the spectrum of a Hammerstein operator  $H$  by  $S(H)$ .<sup>1)</sup>

§1. Let  $f_i(x)$  ( $i=1, 2, \dots$ ) be countable number of real-valued continuous functions with  $f_i(0)=0$  defined on the whole real line, and  $k_i$  ( $i=1, 2, \dots$ ) be countable number of positive numbers. We define an operator  $H$  on  $l^2$  of vectors  $\phi=(x_1, x_2, \dots)$  with  $\sum_{i=1}^{\infty} x_i^2 < +\infty$  by

$$H\phi=(k_1f_1(x_1), k_2f_2(x_2), \dots). \quad (1)$$

We assume that the range of  $H$  is also in  $l^2$ . This is of Hammerstein type, i.e.  $H=K\uparrow$ , where

$$\uparrow\phi=(f_1(x_1), f_2(x_2), \dots)$$

and  $K$  is a matrix of diagonal form.

*Theorem 1.* Let us assume that the functions  $g_i(x)=\frac{f_i(x)}{x}$  be continuous. Then, for the operator  $H\phi$  defined by (1), if  $S(H)$  contains no intervals,  $H$  must be linear.

*Proof.* When  $k_1f_1(x_1)=\lambda x_1$  for some  $x_1 \neq 0$  and  $\lambda \neq 0$ , then we consider the vector  $\phi_1=(x_1, 0, 0, \dots)$  for which we have

$$\begin{aligned} H\phi_1 &= (k_1f_1(x_1), k_2f_2(0), k_3f_3(0), \dots) \\ &= (\lambda x_1, 0, 0, \dots) = \lambda\phi_1, \end{aligned}$$

namely,  $\lambda \in S(H)$ . Therefore, if the continuous function  $g_1(x)$  takes two different values  $\lambda_1, \lambda_2$  at points different from zero:

$$k_1g_1(x_1)=\lambda_1, \quad k_1g_1(x_2)=\lambda_2; \quad x_1 \neq 0, \quad x_2 \neq 0,$$

then, since  $k_1g_1(x)$  takes every value between  $\lambda_1$  and  $\lambda_2$ ,  $S(H)$  contains at least one interval. Namely, if  $S(H)$  contains no intervals,  $k_1g_1(x)$  must be constant, and hence it follows that

$$k_1f_1(x)=\lambda_1x \quad (-\infty < x < +\infty)$$

for a uniquely defined number  $\lambda_1$ . Similarly, we have

$$k_i f_i(x) = \lambda_i(x) \quad (-\infty < x < +\infty; \quad i=2, 3, \dots).$$

Therefore, for  $\phi=(x_1, x_2, \dots)$  and  $\psi=(y_1, y_2, \dots)$ , we have

$$\begin{aligned} H(x\phi + y\psi) &= (k_1f_1(xx_1 + yy_1), k_2f_2(xx_2 + yy_2), \dots) \\ &= (\lambda_1(xx_1 + yy_1), \lambda_2(xx_2 + yy_2), \dots) \\ &= x(k_1f_1(x_1), k_2f_2(x_2), \dots) + y(k_1f_1(y_1), k_2f_2(y_2), \dots) \end{aligned}$$

1) As was pointed out in the preceding paper [2], we need only to study the case when  $H0=0$ .