

## 45. Continuity of Path Functions of Strictly Stationary Linear Processes

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Let  $X(t)$ ,  $-\infty < t < +\infty$ , be a mean continuous purely non-deterministic weakly stationary process with  $EX(t)=0$ . Then, by Karhunen [5],  $X(t)$  can be expressed in the following form.

$$(1) \quad X(t) = \int_{-\infty}^t g(t-u) dZ(u),$$

where the function  $g$  is in  $L_2(R)$  and  $dZ$  is an orthogonal random measure such that  $E(dZ(u))^2 = du$ . Further, let  $\mathfrak{M}_t(X)$ ,  $\mathfrak{M}(X)$  and  $\mathfrak{M}_t(Z)$  be closed linear manifolds spanned by  $\{X(\tau); \tau \leq t\}$ ,  $\{X(\tau); -\infty < \tau < +\infty\}$  and  $\{Z(\tau) - Z(\tau'); \tau, \tau' \leq t\}$ , respectively. We can take  $g$  and  $dZ$  to satisfy  $\mathfrak{M}_t(X) = \mathfrak{M}_t(Z)$ , uniquely up to the constant multiple with absolute value one.

Next, following P. Lévy and Hida-Ikeda [2], we call  $X(t)$  a *linear process* if  $\mathfrak{M}_t(X)$  and  $\mathfrak{M}_t^\perp(X) = \{\text{the orthogonal complement of } \mathfrak{M}_t(X) \text{ in } \mathfrak{M}(X)\}$  are mutually independent for each  $t$ .

**PROPOSITION.** *Let  $X(t)$  be a strictly stationary process with canonical representation of the form (1). Then  $X(t)$  is a linear process if and only if  $Z_a(t) = Z(t) - Z(a)$ ,  $t \geq a$ , is a temporally homogeneous additive process for each  $a$ .*

The proof of 'if' part is found in Hida-Ikeda [2]. 'Only if' part is easily proved by the definition of canonical representation.

In the following we assume  $X(t)$  to be strictly stationary and linear. We want to investigate properties of its path functions.

An additive process which is continuous in probability may be considered as a Lévy process by taking an appropriate version. Hence, by Lévy-Itô's decomposition, we can write

$$(2) \quad Z(t) - Z(a) = \sqrt{v}(B_0(t) - B_0(a)) + P(t) - P(a),$$

where  $B_0(t)$  is the standard Brownian motion and  $P(t) - P(a)$  is the Poisson part. Then (1) and (2) imply

$$(3) \quad X(t) = \sqrt{v} \int_{-\infty}^t g(t-u) dB_0(u) + \int_{-\infty}^t g(t-u) dP(u).$$

We denote the first term on the right side by  $X_1(t)$  and the second by  $X_2(t)$ .  $X_1(t)$  is a Gaussian stationary process and the properties of its path functions are investigated by Hunt [3] and Belayev [1]. So we shall treat  $X_2(t)$  and give a sufficient condition for the continuity