## 103. On the Global Solution of a Certain Nonlinear Partial Differential Equation

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1. Introduction. We consider the following fourth order partial differential equation

(1)  $\partial^2 y/\partial t^2 = (1 + \alpha(\partial y/\partial x)^{2p})\partial^2 y/\partial x^2 - \beta \partial^4 y/\partial x^4$ , where  $\alpha$  and  $\beta$  are positive constants and  $p = 1, 2, \cdots$ , which is deeply connected with the study of the anharmonic lattice (see [1]).

Here we consider the initial-boundary value problem for (1) with initial values

(2)  $y(0, x) = f(x), \quad \partial y/\partial t(0, x) = g(x),$ 

and with periodic boundary condition

(3) y(t, x) = y(t, x+1) for all x and t.

Then we have the following theorem being concerned with the global solution for the problem:

**Theorem.** For every  $\alpha > 0$ ,  $\beta > 0$ , and for every real 1-periodic initial functions  $f \in W_2^{(6)}(0, 1)$ ,  $g \in W_2^{(4)}(0, 1)$ , there exists the unique function which satisfies (1), (2) and (3) in the classical sense in the whole (t, x) plane.

The method of proof is the semi-discrete approximation similar to that presented by Sjöberg [2].

The authors were announced by Nisida [3] that he independently treated the same problem by means of the theory of semi-groups.

2. Proof of existence of the global solution. In order to prove the existence of the desired solution we employ the following semidiscrete approximation:

$$(4) \begin{array}{c} d^2 y_N(t,x_r)/dt^2 = D_+ [D_- y_N(t,x_r) + \alpha (D_- y_N(t,x_r))^{2p+1}/2p+1] \\ -\beta D_+^2 D_-^2 y_N(t,x_r), \quad r=1,2,\cdots,N \\ y_N(0,x_r) = f(x_r), \quad dy_N/dt(0,x_r) = g(x_r), \quad r=1,2,\cdots,N, \end{array}$$

 $y_N(t, x_r) = y_N(t, x_{r+N}), \quad r = 1, 2, \dots, N \quad \text{and all } t$ 

where the mesh-width h=1/N, N natural number,  $x_r=rh$  and the difference operators  $D_+$  and  $D_-$  are defined by

 $hD_+y(x_r) = y(x_{r+1}) - y(x_r), \qquad hD_-y(x_r) = y(x_r) - y(x_{r-1}).$ 

For every h>0 the solution of the problem (4) uniquely exists on the basis of the theory of ordinary differential equations. The solution  $y_N(t, x_r)$ , fixed N, is a grid-function defined for  $x_r=rh$ . We may write  $y_N(t, x_r)=y_r(t)$  for the sake of simplicity.