

68. A Note on the Asymptotic Behavior of the Solutions  
of  $\ddot{x} + a(t)f(\ddot{x})\ddot{x} + b(t)\phi(\dot{x}, \ddot{x}) + c(t)g(\dot{x})$   
 $+ d(t)h(x) = p(t, x, \dot{x}, \ddot{x}, \ddot{\ddot{x}})$

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1. Introduction. In this note we shall be concerned with fourth order non-autonomous differential equations of the form

$$(1.1) \quad \ddot{x} + a(t)f(\ddot{x})\ddot{x} + b(t)\phi(\dot{x}, \ddot{x}) + c(t)g(\dot{x}) + d(t)h(x) = p(t, x, \dot{x}, \ddot{x}, \ddot{\ddot{x}})$$

where  $a, b, c, d, f, \phi, g, h$  and  $p$  are continuous real-valued functions depending only on the arguments displayed, and dots indicate differentiation with respect to  $t$ .

Many authors (J. O. C. Ezeilo [3], M. Harrow [6], A. S. C. Sinha and R. G. Hoft [10], M. A. Asmussen [1], B. S. Lalli and W. S. Skrapek [8], T. Hara [4], etc. [9]) have studied the stability of the trivial solution of the fourth order autonomous differential equations of the form

$$(1.2) \quad \ddot{x} + f(\ddot{x})\ddot{x} + \phi(\dot{x}, \ddot{x}) + g(\dot{x}) + h(x) = 0$$

and their perturbed equations of the form

$$(1.3) \quad \ddot{x} + f(\ddot{x})\ddot{x} + \phi(\dot{x}, \ddot{x}) + g(\dot{x}) + h(x) = p(t, x, \dot{x}, \ddot{x}, \ddot{\ddot{x}}).$$

We shall investigate sufficient conditions under which all solutions of the non-autonomous differential equation (1.1) tend to zero as  $t \rightarrow \infty$ .

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2. Assumptions and theorem. Let us begin by stating the assumptions on the functions appeared in the equation (1.1).

Assumptions.

( I )  $a(t), b(t), c(t)$  and  $d(t)$  are  $C^1$ -functions in  $I = [0, \infty)$ .

( II )  $f(z)$  is a  $C^1$ -function in  $R^1$ .

( III ) The functions  $\phi(y, z)$  and  $\frac{\partial \phi}{\partial y}(y, z)$  are continuous in  $R^2$ .

( IV )  $g(y)$  is a  $C^1$ -function in  $R^1$ .

( V )  $h(x)$  is a  $C^1$ -function in  $R^1$ .

( VI ) The function  $p(t, x, y, z, w)$  is continuous in  $I \times R^4$ .

Hereafter the following notations are used:

$$g_1(y) = \frac{g(y)}{y} \quad (y \neq 0), \quad g_1(0) = g'(0),$$

$$f_1(z) = \frac{1}{z} \int_0^z f(\zeta) d\zeta \quad (z \neq 0), \quad f_1(0) = f(0).$$

Our result is summarized in the following theorem: