## 106. The Whitehead Theorems in Shape Theory

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§1. Introduction. Recently the notion of shape which was originally introduced by K. Borsuk [2] for compact metric spaces has been extended to the case of topological spaces by S. Mardešić [3]. In this paper we shall use the notion of shape in the sense of Mardešić [3]. As in our previous paper [6], let  $\pi_n(X, A, x_0)$  be the *n*-th (Čech) homotopy pro-group of a pair  $(X, A, x_0)$  of pointed topological spaces and  $H_n(X, A)$  the *n*-th (Čech) homology pro-group of a pair (X, A) of topological spaces. For a continuous map  $f: (X, A, x_0) \rightarrow (Y, B, y_0)$  let us denote by  $\pi_k(f)$  or  $H_k(f)$  the induced morphism of the *k*-th homotopy or homology pro-groups.

In this paper we shall establish the following theorems as analogues of the classical Whitehead theorems.

**Theorem 1.** Let  $(X, x_0)$  and  $(Y, y_0)$  be connected pointed spaces and let  $f: (X, x_0) \rightarrow (Y, y_0)$  be a continuous map. For  $n \ge 2$  let us consider the following conditions.

(i)  $\pi_k(f): \pi_k(X, x_0) \rightarrow \pi_k(Y, y_0)$ is an isomorphism for  $1 \leq k < n$  and an epimorphism for k=n. (ii)  $H_k(f): H_k(X, x_0) \rightarrow H_k(Y, y_0)$ 

is an isomorphism for  $1 \leq k < n$  and an epimorphism for k=n.

Then (i) implies (ii), and conversely, if  $\pi_1(X, x_0) = 0$  and  $\pi_1(Y, y_0) = 0$ , (ii) implies (i).

**Theorem 2.** Let  $(X, x_0)$  and  $(Y, y_0)$  be connected pointed spaces of finite dimension and let  $n_0 = \max(1 + \dim X, \dim Y)$ . If  $f: (X, x_0)$  $\rightarrow (Y, y_0)$  is a continuous map such that the induced morphism  $\pi_k(f)$ :  $\pi_k(X, x_0) \rightarrow \pi_k(Y, y_0)$  is a bimorphism for  $1 \le k < n_0$  and an epimorphism for  $k = n_0$ , then f induces a shape equivalence.

In [4] Mardešić deduced the conclusion of Theorem 2 under a condition that  $\pi_k(f)$  is a bimorphism for  $1 \leq k \leq n_0$  and an epimorphism for  $k=n_0+1$ . For the case of compact metric spaces the same result as in Mardešić [4] was obtained earlier by M. Moszyńska [9].

§ 2. Preliminaries. Let  $f: (X, x_0) \to (Y, y_0)$  be a continuous map of pointed topological spaces. Let  $(Z, x_0)$  be the mapping cylinder of fwhich is obtained from the topological sum  $(X \times I) \cup Y$  (where I is the closed unit interval [0, 1] in the real line) by identifying (x, 1) with f(x)for  $x \in X$  and by shrinking  $(x_0 \times I) \cup \{y_0\}$  to a point which we denote by