

169. Approximation Theorem on Stochastic Stability

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(Comm. by Kōsaku YOSIDA, M. J. A., Oct. 13, 1975)

§ 1. This paper treats the approximation theorem on the stability theory of dynamical systems given by stochastic differential equations. Consider a dynamical system in R^n :

$$(1) \quad dx_i(t) = \sum_{k=1}^n \sigma_{ik}(x(t)) dB_k(t) + b_i(x(t)) dt \quad (i=1, \dots, n)$$

(in this paper, we always assume that coefficients of (1) are Lipschitz continuous). If we assume that for $m \geq 1$

$$(2) \quad \begin{cases} \sigma_{ik}(x) = \tilde{\sigma}_{ik}(\lambda) |x|^m + o(|x|^m) \\ b_i(x) = \tilde{b}_i(\lambda) |x|^{2m-1} + o(|x|^{2m-1}) \end{cases} \quad |x| \rightarrow 0,$$

where $\lambda = x/|x|$, then the first approximation of (1) is defined by

$$(3) \quad dx_i(t) = \sum_k \tilde{\sigma}_{ik}(\lambda(t)) |x(t)|^m dB_k(t) + \tilde{b}_i(\lambda(t)) |x(t)|^{2m-1} dt.$$

Following to Khas'minskii [2], we call $x(t)$ asymptotic stable in probability if $\lim_{|x| \rightarrow 0} P_x \{ \lim_{t \rightarrow \infty} |x(t)| = 0 \} = 1$, asymptotic unstable in probability if $P_x \{ \lim_{t \rightarrow \infty} |x(t)| = \infty \} = 1$ for all $x (\neq \{0\})$, divergent in probability if $P_x \{ \sup_{t > 0} |x(t)| > \varepsilon \} = 1$ for all $x (\neq \{0\})$ and small $\varepsilon > 0$.

The main theorems are:

Theorem 1. *If the solution of (3) is asymptotic stable in probability, then that of (1) is so.*

Theorem 2. *If the solution of (3) is asymptotic unstable in probability, then that of (1) is divergent in probability.*

When $m=1$, the results have been already proved by Khas'minskii [2] and Pinsky [4].

In § 2 we sketch proofs of Theorems 1 and 2. In § 3 they are applied to a limit behaviour of a stochastic process on a two dimensional compact manifold, which is useful for studying the stability of three dimensional linear systems (see [1]).

Acknowledgement. The author would like to express his hearty gratitude to Professor M. Motoo for his suggestions.

§ 2. **Remark 1.** In this section it will be proved that the stability of (3) is equivalent to that of

$$(4) \quad dx_i(t) = \sum_k \tilde{\sigma}_{ik}(\lambda(t)) |x(t)| dB_k(t) + \tilde{b}_i(\lambda(t)) |x(t)| dt.$$

Thus, a little modification of Khas'minskii's sharp stability criterion formulated in [1] is applicable to (3).