

## On the Nonlinear Autonomous System Admitting of a Family of Periodic Solutions near its Certain Periodic Solution

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### 1. Introduction

Let

$$(1.1) \quad \frac{dy}{dt} = Y(y)$$

be a given nonlinear autonomous system, where  $Y(y) \in C^2_y$  in a domain  $G$  of the phase  $(n+1)$ -space  $R^{n+1}$ . Here, of course,  $y$  and  $Y$  are the  $(n+1)$ -dimensional vectors. In the sequel, let us call the independent variable  $t$  the *time*.

In this paper, we consider the case where, in a domain  $G$ , the system (1.1) admits of a family  $\mathfrak{F}$  of closed paths in the neighborhood of its certain closed path

$$C_0 : y = \phi(t).$$

According to the nomenclature of the preceding paper [5]<sup>1)</sup>, the system (1.1) is called respectively the *fully* or the *partially oscillatory* system according as the family  $\mathfrak{F}$  consists of whole paths or of a portion of them lying near  $C_0$ . In either case, according to [5], we assume that, when  $n \geq 2$ , the periods of the closed paths belonging to  $\mathfrak{F}$  are bounded. Then, by 4.1 of [5], there exist the *universal periods* for paths belonging to  $\mathfrak{F}$  such that they are continuous at  $C_0$ . Let us denote such a universal period of  $C_0$  by  $\omega_0$ .

According to [5], we make use of a moving orthonormal system along  $C_0$ . Let  $\xi_i$ 's ( $i=1, 2, \dots, n$ ) be the normal unit vectors of a moving orthonormal system along  $C_0$  such that  $\xi_i(t) \in C^2_i$ . Then, with respect to this moving orthonormal system, any path  $C$  lying near  $C_0$  is represented as

$$(1.2) \quad y = \phi(t) + \sum_{i=1}^n x^i \xi_i$$

and the time variable  $\tau$  along  $C$  and the  $n$ -dimensional vector  $x = (x^i)$  are determined respectively by the differential equations

$$(1.3) \quad \frac{d\tau}{dt} = \frac{\|Y\|^2 + \sum_{i=1}^n x^i Y^* \dot{\xi}_i}{Y^* Y'} \quad ,$$

1) Numbers in brackets refer to the references listed at the end of the paper.

2)  $\|Y\|$  denotes the Euclidean norm of  $Y$ . The dots above the letters denote differentiation with respect to  $t$ . The symbol  $*$  denotes the transposed.