## Generalized Extremal Length of an Infinite Network

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## Introduction

The extremal length of a network, which is the reciprocal of the value of a quadratic programming problem, was first investigated by R. J. Duffin [4] on a finite graph and next by the second author [7] on an infinite graph. In this paper we shall be concerned with a generalized form of the extremal length as in [5] along the same lines as in [4] and [7]. The generalized extremal length of an infinite network may be regarded as the reciprocal of the value of a convex programming problem. One of our main purposes is to establish a reciprocal relation between the generalized extremal distance and the generalized extremal width of an infinite network which was established by M. Ohtsuka [5] for the continuous case. We shall also study the generalized extremal length of an infinite network relative to a finite set and the ideal boundary of the network. A concept of non-linear flows which was studied in [1] and [3] will appear in §3 and §4 in connection with the extremal width of a network.

## §1. Preliminaries

Let X be a set of nodes and let Y be a set of directed arcs. Since we always consider the case where X and Y consist of a countably infinite number of elements, we put

$$X = \{0, 1, 2, \dots, n, \dots\},\$$
$$Y = \{1, 2, \dots, n, \dots\}.$$

Let  $K = (K_{vj})$  be the node-arc incidence matrix. Namely  $K_{vj} = 1$  if arc j is directed toward node v,  $K_{vj} = -1$  if arc j is directed away from node v and  $K_{vj} = 0$  if arc j and node v do not meet.

We assume that X, Y and K satisfy the following conditions:

- (1.1)  $\{j \in Y; K_{\nu j} \neq 0\}$  is a nonempty finite set for each  $\nu \in X$ .
- (1.2)  $e(j) = \{v \in X; K_{vj} \neq 0\}$  consists of exactly two nodes for each  $j \in Y$ .
- (1.3) For any  $\alpha$ ,  $\beta \in X$ , there are  $v_1, \dots, v_n \in X$  and  $j_1, \dots, j_{n+1} \in Y$  such that  $e(j_i) = \{v_{i-1}, v_i\}, i=1,\dots, n+1$  with  $v_0 = \alpha$  and  $v_{n+1} = \beta$ .