## Exactness and Bernoulliness of generalized random dynamical systems

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Recently the second author of the present paper proposed the idea of generalized random dynamical systems and investigated their ergodic properties in [3]. This paper is a supplementary note for [3]. We will investigate the exactness and the Bernoulliness of skew product transformations associated with generalized random dynamical systems.

## §1. Preliminaries

Let  $(S, \mathcal{B}, \mu)$  and  $(Y, \mathcal{F}, \nu)$  be standard probability spaces. We consider  $(S, \mathcal{B}, \mu)$  as a phase space and  $(Y, \mathcal{F}, \nu)$  as a parameter space. Namely for each  $y \in Y$  a measure-preserving transformation  $\varphi_y$  on  $(S, \mathcal{B}, \mu)$  is given. We assume that the mapping  $(s, y) \mapsto \varphi_y(s)$  is  $\mathcal{B} \times \mathcal{F}/\mathcal{B}$ -measurable. We are concerned with the behavior of the random orbit

$$X_n(s) = \varphi_{v_n} \circ \varphi_{v_{n-1}} \circ \cdots \circ \varphi_{v_n}(s) , \qquad s \in S, \qquad y_1, \ldots, y_n \in Y, \qquad n \ge 1 ,$$

where  $y_1, \ldots, y_n$  are taken randomly in the following manner. There are given a family of probability density functions  $\{\gamma(s, y), s \in S\}$  on Y:

$$\gamma(s, y) \ge 0$$
,  $\int_Y \gamma(s, y) d\nu(y) = 1$ ,  $s \in S$ ,

and a sub- $\sigma$ -field  $\mathcal{B}_0 \subset \mathcal{B}$  such that

- (i)  $\gamma(s, y)$  is  $\mathcal{B}_0 \times \mathcal{F}$ -measurable and
- (ii)  $\varphi_y^{-1}\mathcal{B}$  and  $\mathcal{B}_0$  are independent for each  $y \in Y$ . Each  $y_k$   $(k \ge 1)$  is choosen according to the probability measure  $\gamma(X_{k-1}(s), y) \, d\nu(y)$  where  $X_0(s) = s$ . Then  $X = \{X_n(s), n \ge 0\}$  becomes a stationary Markov chain with the transition probability

$$P(s, B) = \int_{Y} 1_{B}(\varphi_{y}(s))\gamma(s, y) d\nu(y), \qquad B \in \mathscr{B},$$

and the stationary measure  $\mu$ . Let T be the corresponding Markov operator:

$$Tf(s) = \int_S f(t)P(s, dt) = \int_Y f(\varphi_y(s))\gamma(s, y) \, dv(y) \,, \qquad f \in L^1(S, \mu) \,.$$